

**GLOBAL EXISTENCE OF WEAK SOLUTIONS  
FOR INTERFACE EQUATIONS COUPLED  
WITH DIFFUSION EQUATIONS**

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# GLOBAL EXISTENCE OF WEAK SOLUTIONS FOR INTERFACE EQUATIONS COUPLED WITH DIFFUSION EQUATIONS

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**Abstract.** A weak formulation for an interface dynamics coupled with a diffusion equation is introduced. A global-in-time weak solution is constructed for an arbitrary initial data under a periodic boundary condition. The result applies to the interface equation obtained as a certain singular limit of some reaction-diffusion systems including the activator-inhibitor model.

**Key words.** Interface equation with diffusion equation, global existence, viscosity solution

**AMS(MOS) subject classifications.** 35K55, (35K57 35K65)

**1. Introduction.** This paper is concerned with interface equations coupled with diffusion equations. A typical example is formally obtained as a certain singular limit of a class of reaction diffusion systems [XYC]. Our main objective is to construct a global-in-time weak solution for the initial value problem of these interface equations.

Let  $\Omega_{\pm}(t)$  be two disjoint open sets in  $\mathbb{R}^n$  depending on time  $t$ . The complement of the union of  $\Omega_+(t)$  and  $\Omega_-(t)$  is called the interface and denoted by  $\Gamma(t)$ . To write down the equation we assume that the interface  $\Gamma(t)$  is a smooth hypersurface so that  $\Gamma(t)$  is the boundary of  $\Omega_{\pm}(t)$ . Let  $V = V(t, x)$  denote the speed of  $\Gamma(t)$  at  $x \in \Gamma(t)$  in the normal direction  $\vec{n}$  from  $\Omega_+(t)$  to  $\Omega_-(t)$ . Let  $\kappa (= \operatorname{div} \vec{n})$  denote  $(n - 1)$  times the mean curvature of  $\Gamma(t)$  at  $x \in \Gamma(t)$ . We consider an interface equation for  $\Gamma(t)$ :

$$(1.1) \quad V = W(v) - c\kappa \quad \text{on } \Gamma(t)$$

coupled with a diffusion equation for  $v = v(t, x)$ :

$$(1.2) \quad v_t = D\Delta v + g_{\pm}(v), x \in \Omega_{\pm}(t), t > 0,$$

where  $c \geq 0$  and  $D > 0$  are constants. Here  $g_{\pm}$  and  $W$  are given bounded continuous functions on  $\mathbb{R}$ . We also impose a condition that  $v(t) = v(t, \cdot)$  is continuous in  $\mathbb{R}^n$  with its first derivatives, i.e.,

$$(1.3) \quad v(t) = v(t, \cdot) \in C^1(\mathbb{R}^n) \quad \text{for } t > 0.$$

Our goal is to construct a global solution of the initial value problem for interface equations coupled with diffusion equations – a typical example of which is (1.1)–(1.3). There is an intrinsic difficulty to construct a global solution  $(\Omega_{\pm}(t), v(t))_{t \geq 0}$  since  $\Gamma(t)$  may have singularities in a finite time. If  $v$  is a constant so that  $g_{\pm}(v) = 0$ , (1.1)–(1.3) becomes

$$(1.4) \quad V = C - c\kappa,$$

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where  $C$  is a constant. If  $C = 0$  and  $c > 0$ , (1.4) becomes

$$(1.5) \quad V = -c\kappa,$$

which is called the mean curvature flow equation. Even for (1.5) Grayson [Gr] gives an example of a barbell in  $\mathbb{R}^3$  with a long, thin handle that actually pinches off in a finite time. To track whole evolution of interface we interpret  $\Gamma(t)$  as a level set of viscosity solution of some second order evolution equations as in [CGG]. In fact Y.-G. Chen and the first two authors [CGG] constructed a *unique* global weak solution with arbitrary initial data for a class of interface equations including (1.4) and (1.1) where  $v$  only depends on time; see [GG1] for interface equations that the theory in [CGG] applies to. Almost at the same time Evans and Spruck [ES1] constructed the same solution but only for (1.5). Another formulation closely related to [CGG] and [ES1] is given in [S]. We refer to [ES2] and [GG2] for further development of the theory and references. We note that idea using level of viscosity solutions for  $V = C$  is also found in an unpublished paper of Barles [B].

Although the interface equation admits a global weak solution,  $\Gamma(t)$  may develop an interior (Remark 2.5). We introduce a generalized formulation of (1.2)–(1.3). For technical reasons we impose a periodic boundary condition. In this paper among other results we construct a global weak solution of the initial value problem for (1.1)–(1.3) with arbitrary initial data  $(\Gamma(0), v(0, x))$ ,  $v(0, x) \in C^2$  under the periodic boundary condition (Theorem 4.6). (We may assume  $D = 1$  without the loss of generality). For this purpose for continuous  $v$  we construct a unique global weak solution for (1.1). The basic idea is the same as in [CGG] but we are forced to use results in [GGIS] since  $v$  may depend on  $x$  as well as  $t$ . We solve (1.2) – (1.3) with above  $v$  and  $\Omega_{\pm}(t)$  determined by (1.1) with the initial condition. If we write the solution by  $w$  we have a mapping  $v \mapsto w$ . Since our weak formulation forces us to interpret the mapping  $v \mapsto w$  as a multi-valued mapping, we use Kakutani (-Ky Fan's) fixed point theory (see e.g. [AF]) to get a global generalized solution as a fixed point of the mapping  $v \mapsto w$ . Our results applies to the system (1.2) – (1.3) with (1.1) replaced by more general interface equations including anisotropic motion (cf [Gu1,2], [C]). We do not know the uniqueness of our solutions.

Let us mention some results on (1.1) – (1.3) related to ours. In [XYC] X.-Y. Chen constructed a unique local smooth solution for a smooth initial data  $(\Gamma(0), v(0, x))$  in  $\mathbb{R}^n$  when  $c > 0$ . When  $n = 1$ , the curvature term in (1.1) disappears. Hilhorst, Nishiura and Mimura [HNM] constructed a global unique solution for (1.1) – (1.3) when the interface is a point and  $n = 1$  under the Neumann boundary condition. Their interface is  $C^1$  in time. After this work was completed, we learned of the recent paper of X. Chen [XC2] which extends the local existence results in [XYC] to the case  $c = 0$ . Our result seems to be a first global result even for (1.1) – (1.3) with  $c > 0$  or  $c = 0$  when  $n > 1$ .

Interface equations and reaction-diffusion equations are closely related; see [F]. Typical examples of the system (1.1) – (1.3) is provided as a singular limit of reaction-diffusion equations at least formally; see [OMK] and [XYC]. We will explain it more explicitly following [XYC]. We consider a reaction-diffusion system describing the activator-inhibitor model:

$$(1.6) \quad u_t = \varepsilon \Delta u + \frac{1}{\varepsilon} f(u, v), \quad x \in \mathbb{R}^n, t > 0,$$

$$(1.7) \quad v_t = D \Delta v + g(u, v), \quad x \in \mathbb{R}^n, t > 0,$$

with

$$\begin{aligned} f(u, v) &= f_0(u) - v, f_0(u) = u(1 - u)(u - a), \\ g(u, v) &= u - \gamma v, \end{aligned}$$

where  $\gamma > 0$ ,  $0 < a < 1$  and  $\varepsilon$  is a small positive parameter. The zero set of  $f$  consists of three branches

$$\begin{aligned} u &= h_-(v) && \text{for } u < a_-, \\ u &= h_+(v) && \text{for } a_+ < u, \\ u &= h_0(v) && \text{for } a_- < u < a_+, \end{aligned}$$

where  $a_- < a_+$  and  $f'_0(a_-) = f'_0(a_+) = 0$ . When  $\varepsilon \rightarrow 0$ , it is expected that  $u$  tends to  $h_{\pm}(v)$  in some region  $\Omega_{\pm}(t)$  in  $\mathbb{R}^n$  since  $h_{\pm}(v)$  is a stable zero of  $u_t = f(u, v)$ . From (1.6) it is also expected that the interface  $\Gamma(t)$  moves by (1.1) with  $c = \varepsilon$ . Here  $W(b)$  for  $b$ ,  $f_0(a_-) < b < f_0(a_+)$  is the speed of the travelling wave of

$$u_t = \Delta u + f(u, b)$$

and is given by

$$W(b) = \frac{1}{\sqrt{2}}(h_+(b) + h_-(b) - h_0(b));$$

see Aronson and Weinberger [AW]. The equation (1.7) now becomes (1.2) as  $\varepsilon \rightarrow 0$  by taking  $g_{\pm}(v) = g(h_{\pm}(v), v)$ . For more details we refer to [OMK] and [XYC] and references therein. We note that anisotropic interface equations are also derived by a singular limit of some reaction-diffusion equation [C].

There is an extensive literature on the behavior  $u^{\varepsilon}$  as  $\varepsilon \downarrow 0$  in (1.6) and its relation to the solutions of interface equation when  $v$  is given and the space dimension  $n = 1$ . See e.g. [FH], [BK], [CP]. Recently, some results are extended to the case  $n > 1$  where the curvature effect comes in. If  $v$  is a constant and  $W(v) = 0$ , (1.6) is called the Allen-Cahn equation whose relation to (1.5) with  $c > 0$  is rigorously analyzed by Bronsard and Kohn [BK] and DeMottoni and Schatzman [DS]. X. Chen [XC1] extended results of [DS] and simplified the argument. After this work was completed, we learned that X. Chen [XC2] derived (1.1) – (1.3) with  $c = 0$  rigorously as a singular limit of (1.6) – (1.7). There is also an argument to interpret the case  $c = \varepsilon > 0$  in [XC2]. His method is an extension of his work [XC1]. All results in [BK, DS, XC1, XC2] assume that the solution of the interface equation is smooth to get the behavior of  $u^{\varepsilon}$  as  $\varepsilon \downarrow 0$ . Very recently we learned that Evans, Soner and Songanidis [ESS] obtained the behavior of  $u^{\varepsilon}$  even after singularities appear on the interface for the Allen-Cahn equation.

In §2 we solve a general interface equation including (1.1) for given continuous function  $v$  globally in time under a periodic boundary condition. In §3 we give a generalized formulation of (1.2) – (1.3). In §4 we state our main existence results and prove them by a fixed point argument. In Appendix we state a stability property of viscosity solutions used in §4.

After this work was completed, X.-Y. Chen kindly informed that he found another proof for global existence for (4.1), (4.2), (4.3') with  $c > 0$  without using a fixed point argument for multi-valued mappings.

**2. Interface equations.** We consider interface equations under periodic boundary conditions. The periodic boundary condition is important because it is often used in numerical experiments. For  $\alpha_i > 0 (1 \leq i \leq n)$  let  $R$  be a rectangle in  $\mathbb{R}^n$  of the form

$$R = \{(x_1, \dots, x_n) \in \mathbb{R}^n; 0 \leq x_i \leq \alpha_i, 1 \leq i \leq n\}.$$

We identify faces  $x_i = 0$  and  $x_i = \alpha_i (1 \leq i \leq n)$  of  $R$  to obtain an  $n$ -dimensional flat torus  $\mathbb{T}$ . Motion of interfaces in  $R$  under periodic boundary conditions is interpreted as the motion in  $\mathbb{T}$ . We consider  $\mathbb{T}$  rather than  $\mathbb{R}^n$  for later technical convenience because  $\mathbb{T}$  is compact and has no boundary.

Let  $\Omega_{\pm}(t)$  be an open set in  $\mathbb{T}$  depending on time  $t \geq 0$  such that  $\Omega_+(t) \cap \Omega_-(t) = \emptyset$ . Let  $\Gamma(t)$  denote the complement of  $\Omega_+(t) \cup \Omega_-(t)$  in  $\mathbb{T}$ . Physically speaking,  $\Gamma(t)$  is called an interface bounding two phases  $\Omega_{\pm}(t)$  of material, e.g. solid and liquid region. Suppose that  $\Gamma(t)$  is a smooth hypersurface and let  $\vec{n}$  denote the unit normal vector field pointing from  $\Omega_+(t)$  to  $\Omega_-(t)$ . Let  $V = V(t, x)$  denote the speed of  $\Gamma(t)$  at  $x \in \Gamma(t)$  in the direction  $\vec{n}$ . It is convenient to extend  $\vec{n}$  to a vector field (still denoted by  $\vec{n}$ ) on a tubular neighborhood of  $\Gamma(t)$  such that  $\vec{n}$  is constant in the normal direction of  $\Gamma(t)$ . The equation for  $\Gamma(t)$  we consider here is of the form

$$(2.1) \quad \begin{aligned} V &= \xi(t, x, \vec{n}, \nabla \vec{n}) \\ &:= \eta(\vec{n}, \nabla \vec{n}) + \omega(t, x, \vec{n}) \text{ on } \Gamma(t), \end{aligned}$$

where  $\eta$  and  $\omega$  are given functions and  $\nabla$  stands for the spatial gradient in  $\mathbb{T}$ . A typical example is

$$(2.2) \quad V = c \operatorname{div} \vec{n} + \omega(t, x),$$

where  $c$  is a nonnegative constant and  $\omega$  is independent of  $\vec{n}$ . The equation (2.2) is called the mean curvature flow equation if  $c > 0$  and  $\omega \equiv 0$ . A reason we consider general (2.1) is to include anisotropic motion as in [Gu1,2].

We next introduce a weak formulation for (2.1) following [CGG, GG1]. For  $\eta$  we set

$$(2.3) \quad \begin{aligned} F_{\eta}(p, X) &:= -|p|\eta(-\bar{p}, -Q_{\bar{p}}(X)), \bar{p} = p/|p|, \\ Q_{\bar{p}}(X) &= R_{\bar{p}}X R_{\bar{p}} \text{ with } R_{\bar{p}} = I - \bar{p} \otimes \bar{p}, \end{aligned}$$

where  $p \in \mathbb{R}^n \setminus \{0\}$  and  $X \in \mathbb{S}_n$ , the space of  $n \times n$  real symmetric matrices. We also set

$$(2.4) \quad F_{\xi}(t, x, p, X) := F_{\eta}(p, X) - \omega(t, x, -\bar{p})|p|.$$

For example a calculation shows

$$(2.5) \quad F_{\eta}(p, X) = -c \operatorname{trace} ((I - \bar{p} \otimes \bar{p})X)$$

if

$$(2.6) \quad \eta(\vec{n}, \nabla \vec{n}) = -c \operatorname{div} \vec{n}$$

as in (2.2). The following definition of weak solutions for (2.1) is a variant of that in [CGG, GG1]. For the definition of (viscosity) sub- and supersolutions and viscosity solutions; see e.g. [GGIS].

DEFINITION 2.1. Let  $\{\Omega_{\pm}(t)\}_{0 \leq t < T}$  be a one parameter family of open sets in  $\mathbb{T}$  such that  $\Omega_+(t) \cap \Omega_-(t) = \emptyset$ . Suppose that there is a viscosity solution  $u \in C([0, T] \times \mathbb{T})$  of

$$(2.7) \quad u_t + F_{\xi}(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } (0, T) \times \mathbb{T}$$

such that

$$(2.8) \quad \Omega_{\pm}(t) = \{x \in \mathbb{R}^n; u(t, x) \gtrless 0\} \text{ for } 0 \leq t < T.$$

We say  $\{\Omega_{\pm}(t)\}_{0 \leq t < T}$  is a *weak solution* of (2.1) in  $(0, T)$  with initial data  $\Omega_{\pm}(0)$ . Here  $F_{\xi}$  is defined by (2.3) – (2.4).

Roughly speaking, if (2.1) is parabolic (not necessarily strictly parabolic),  $\eta$  grows linearly in  $\nabla \vec{n}$  then one can claim the unique global existence of weak solutions for (2.1) with given initial data  $\Omega_{\pm}(0)$  provided that  $\eta$  and  $\omega$  are continuous. If  $\omega$  is independent of  $x$  and  $\mathbb{T}$  is replaced by  $\mathbb{R}^n$ , the unique global existence is now well known if one of  $\Omega_{\pm}(0)$  is bounded (cf. [CGG, GG1]). We now list our assumptions on  $\eta$  and  $\omega$ .

$\eta$  is a real valued continuous function on the vector bundle

$$(2.9) \quad E = \{(\bar{p}, Q_{\bar{p}}(X)); \bar{p} \in S^{n-1}, X \in \mathbb{S}_n\}$$

over a unit sphere  $S^{n-1}$ .

$$(2.10) \quad \eta(-\bar{p}, -Q_{\bar{p}}(X)) \geq \eta(-\bar{p}, -Q_{\bar{p}}(Y)) \text{ for } X \geq Y, \bar{p} \in S^{n-1},$$

where  $\mathbb{S}_n$  is equipped with usual ordering .

$$(2.11) \quad \liminf_{\rho \downarrow 0} \rho \inf_{|\bar{p}|=1} \eta \left( -\bar{p}, \frac{I - \bar{p} \otimes \bar{p}}{\rho} \right) > -\infty$$

$$\limsup_{\rho \downarrow 0} \rho \sup_{|\bar{p}|=1} \eta \left( -\bar{p}, \frac{-I + \bar{p} \otimes \bar{p}}{\rho} \right) < \infty.$$

$$(2.12) \quad \omega \text{ is continuous from } [0, T] \times \mathbb{T} \times S^{n-1} \text{ to } \mathbb{R}.$$

All assumptions on  $\eta$  is found in [GG1]; (2.10) means that  $-\eta$  is degenerate elliptic and (2.11) restricts the growth of  $\eta$  in  $\nabla \vec{n}$ . The only assumption for  $\omega$  is (2.12)

THEOREM 2.2. *Assume (2.9) – (2.12) for  $\eta$  and  $\omega$ . Let  $\Omega_{\pm}(0)$  be mutually disjoint open sets in  $\mathbb{T}$ . Then there is a unique global weak solution  $\{\Omega_{\pm}(t)\}_{0 \leq t < T}$  of (2.1) in  $(0, T)$  with initial data  $\Omega_{\pm}(0)$ . (The case  $T = \infty$  is included.)*

The basic idea of the proof is the same as [CGG, Theorems 6.8, 7.1]; see also [GG1] for relation between assumptions on  $\eta$  and  $F_{\eta}$ . The major technical difference is that the comparison theorem in [CGG] does not apply to (2.7) because  $F_{\xi}$  depends on  $x$ . Instead we apply [GGIS, Theorem 4.1] to get a comparison principle for (2.7). For the reader's convenience we state a version of the comparison principle which follows from [GGIS, Theorem 4.1] and give a brief proof of Theorem 2.2.

PROPOSITION 2.3. *Assume (2.9) – (2.12). Let  $u$  and  $v$  be, respectively, (viscosity) sub- and supersolutions of (2.7). Assume that  $u$  and  $v$  are, respectively, upper and lower semicontinuous functions on  $[0, T] \times \mathbf{T}$ . If*

$$u(0, x) \leq v(0, x) \text{ on } \mathbf{T},$$

then  $u(t, x) \leq v(t, x)$  on  $[0, T] \times \mathbf{T}$ .

*Proof.* To apply [GGIS, Theorem 4.1] we extend  $u, v$  and  $\omega$  periodically in space variables outside  $R$  and regard (2.7) as

$$u_t + F_\xi(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } (0, T') \times \mathbb{R}^n,$$

where  $T'$  is an arbitrary positive number less than  $T$ .

We first check assumptions of equation in [GGIS]. By (2.9) – (2.10) we know  $F_\eta$  satisfies all assumptions on  $F$  in [GGIS, Theorem 4.1]. Except the boundedness of  $F_\eta(p, X)$  on a bounded set in  $(\mathbb{R}^n \setminus \{0\}) \times \mathbb{S}_n$  the proof is found in [GG1]. This boundedness of  $F_\eta$  can be proved similarly to the proof of [GG1, Lemma 3.5].

By (2.12) we see  $\omega$  is uniformly continuous in  $[0, T'] \times \mathbb{R}^n \times \mathbb{S}^{n-1}$  so  $F_\xi$  satisfies the uniform continuity assumption in  $x$  of [GGIS, (F8)]: there is a modulus  $\sigma$  (i.e.  $\sigma : [0, \infty) \rightarrow [0, \infty)$  is continuous, nondecreasing and  $\sigma(0) = 0$ ) such that

$$|F_\xi(t, x, p, X) - F_\xi(t, y, p, X)| \leq \sigma(|x - y|(|p| + 1))$$

for  $x, y \in \mathbb{R}^n, t \in [0, T'], p \in \mathbb{R}^n \setminus \{0\}, X \in \mathbb{S}_n$ . All other assumptions on  $F$  in [GGIS, Theorem 4.1] are fulfilled since  $\omega$  satisfies (2.12) and  $F_\eta$  satisfies all assumptions on  $F$ .

Since  $u$  and  $v$  is extended periodically and  $R$  is bounded, it is not difficult to see that  $u$  and  $v$  satisfy all the assumptions of [GGIS, Theorem 4.1].

We now apply [GGIS, Theorem 4.1] to conclude  $u \leq v$  on  $[0, T'] \times \mathbb{R}^n$ . Since  $T' < T$  is arbitrary, this completes the proof.  $\square$

*Proof of Theorem 2.2.* (Uniqueness). Suppose that  $u, v \in C([0, T] \times \mathbf{T})$  solves (2.7) such that

$$\Omega_\pm(0) = \{x \in \mathbf{T}, u(0, x) \gtrless 0\} = \{x \in \mathbf{T}; v(0, x) \gtrless 0\}.$$

By [CGG, Lemma 7.2] there is a continuous nondecreasing function  $\theta : \mathbb{R} \rightarrow \mathbb{R}$  with  $\theta(0) = 0$  such that

$$u(0, x) \leq \theta(v(0, x)).$$

Since  $F_\xi$  is geometric, i.e.,

$$(2.13) \quad \begin{aligned} F_\xi(t, x, \lambda p, \lambda X + \sigma p \otimes p) &= \lambda F_\xi(t, x, p, X) \\ \text{for } \lambda > 0, \sigma \in \mathbb{R}, t \in (0, T), x \in \mathbf{T}, p \in \mathbb{R}^n \setminus \{0\}, X \in \mathbb{S}_n, \end{aligned}$$

by [CGG, Theorem 5.2] we see  $\theta(v(t, x))$  also solves (2.7). From Proposition 2.3 it follows  $u \leq \theta(v)$  on  $[0, T] \times \mathbf{T}$ . We thus observe that  $u > 0$  implies  $v > 0$  and  $v < 0$  implies  $u < 0$ . A parallel argument yields the converse implication so  $\Omega_\pm(t)$  is determined by  $\Omega_\pm(0)$  and is independent of the choice of  $u$ . This proves the uniqueness of weak solutions.

(Existence). For given  $\Omega_{\pm}(0)$  we take  $u_0(x) \in C(\mathbb{T})$  such that

$$\Omega_{\pm}(0) = \{x \in \mathbb{T}; u_0(x) \geq 0\}.$$

Since (2.11) is assumed, one may apply [CGG, Proposition 6.4] to (2.7) in  $[0, T'] \times \mathbb{R}^n$  with periodic initial data and find sub- and supersolutions  $v_-, v_+$  of (2.7) on  $[0, T'] \times \mathbb{R}^n$  such that

$$\begin{aligned} v_{\pm}(0, x) &= u_0(x) \text{ on } \mathbb{R}^n \\ v_-(t, x) &\leq u_0(x) \leq v_+(t, x) \text{ on } [0, T'] \times \mathbb{R}^n, \end{aligned}$$

where  $T' < T$ . The dependence of  $x$  in  $F_{\xi}$  is allowed in [CGG, Proposition 6.4]. A trivial modification of the argument enables us to take  $v_-, v_+$  as functions on  $[0, T'] \times \mathbb{T}$ .

Existence of  $v_{\pm}$  yields a viscosity solution  $u \in C([0, T'] \times \mathbb{T})$  of (2.7) with  $u(0, x) = u_0(x)$  by Perron's method and Proposition 2.3. Since  $T' < T$  is arbitrary and the solution is unique, we now obtain a weak solution  $\{\Omega_{\pm}(t)\}_{0 \leq t < T}$  for initial data  $\Omega_{\pm}(0)$ .

Note that the scaling property (2.13) also used to construct  $v_{\pm}$ .  $\square$

*Remark 2.4.* The family  $\{\Omega_+(t)\}$  is determined by  $\Omega_+(0)$  and is independent of  $\Omega_-(0)$ . Indeed, if  $u$  solves (2.7) with (2.8) then  $\theta(u)$  solves (2.7) for continuous nondecreasing  $\theta : \mathbb{R} \rightarrow \mathbb{R}$  since  $F_{\xi}$  is geometric. Take  $\theta(\sigma) = \sigma_+ = \max(\sigma, 0)$  to observe that  $u_+ = \theta(u)$  solves (2.7). By (2.8)  $u_+$  gives a weak solution  $\{\Omega'_{\pm}(t)\}_{0 \leq t < T}$  with initial data  $(\Omega_+(0), \phi)$ . By definition of  $u_+$  we see  $\Omega'_+(t) = \Omega_+(t)$  and  $\Omega'_-(t) = \phi$ . We thus observe that  $\Omega_+(t)$  is determined by  $\Omega_+(0)$ .

*Remark 2.5.* The interface  $\Gamma(t)$  is defined by the complement of  $\Omega_+(t) \cup \Omega_-(t)$  in  $\mathbb{T}$ . There is a chance that  $\Gamma(t)$  develops an interior even if  $\Gamma(0)$  is a smooth hypersurface in  $\mathbb{T}$ . For example consider the equation  $V = -1$  and

$$R = \{(x_1, x_2) \in \mathbb{R}^2; 0 \leq x_1 \leq 2, 0 \leq x_2 \leq 2\}.$$

Suppose that

$$\Omega_+(0) = \{x \in \mathbb{T}; x_1 \neq 1\}, \Omega_-(0) = \phi$$

so that  $\Gamma(0) = \{x_1 = 1\}$ . Then  $\Omega_+(t) = \{x \in \mathbb{T}; 0 \leq x_1 \leq 2, |x_1 - 1| > t\}$  and  $\Omega_-(t) = \phi$ . Indeed equation (2.7) for this example is

$$(2.14) \quad u_t + |\nabla u| = 0.$$

By definition of viscosity solutions, one can check that

$$(2.15) \quad u(t, x) = \begin{cases} 0 & \text{for } |x_1 - 1| \leq t \\ x_1 - 1 - t & \text{for } x_1 - 1 > t \\ 1 - x_1 - t & \text{for } x_1 - 1 < -t \end{cases} \quad (x \in \mathbb{R}^2)$$

is a viscosity solution of (2.14) on  $(0, \infty) \times \mathbb{T}$ . We now observe that  $\Omega_{\pm}(t)$  is given by (2.8) with  $u$  of (2.15).

For the mean curvature flow equation

$$V = -\operatorname{div} \vec{n}$$

we do not know whether or not  $\Gamma(t)$  develops an interior if  $\Gamma(0)$  is a smooth hypersurface. As pointed out in [ES1] we know  $\Gamma(t)$  may develop an interior if  $\Gamma(0)$  has a singularity.

**3. Diffusion equations across interfaces.** This section gives a generalized formulation of

$$(3.1) \quad v_t = \Delta v + g_{\pm}(v) \quad \text{in } Q_T^{\pm} = \bigcup_{0 < t < T} \{t\} \times \Omega_{\pm}(t),$$

$$(3.2) \quad v(t) := v(t, \cdot) \in C^1(\mathbb{T}) \quad \text{for } 0 < t < T,$$

where

$$(3.3) \quad Q_T^{\pm} = \{(t, x) \in Q_T; u(t, x) \gtrless 0\}, Q_T = (0, T) \times \mathbb{T}$$

with some function  $u \in C(\overline{Q}_T)$ . The interpretation of the equation on the interface is crucial.

We introduce a multi-valued function  $\Phi$  associated with continuous functions  $g_{\pm}(\sigma)$ . For  $(s, \sigma) \in \mathbb{R}^2$  we define a closed interval  $\Phi(s, \sigma)$  such that

$$(3.4) \quad \Phi(s, \sigma) = \begin{cases} \{g_+(\sigma)\} & \text{if } s > 0 \\ [\underline{g}(\sigma), \overline{g}(\sigma)] & \text{if } s = 0 \\ \{g_-(\sigma)\} & \text{if } s < 0 \end{cases}$$

where  $\underline{g}(\sigma) = \min(g_+(\sigma), g_-(\sigma))$ ,  $\overline{g}(\sigma) = \max(g_+(\sigma), g_-(\sigma))$ . This correspondence defines a mapping  $\Phi : \mathbb{R}^2 \rightarrow 2^{\mathbb{R}}$ . For  $u, v \in C(\overline{Q}_T)$  we define a subset  $G(u, v)$  such that

$$(3.5) \quad G(u, v) = \{q \in L^{\infty}(Q_T); q(z) \in \Phi(u(z), v(z)) \text{ a.e. } z \in Q_T\},$$

where  $z = (t, x)$ . This correspondence defines a mapping  $G : C(\overline{Q}_T) \times C(\overline{Q}_T) \rightarrow 2^{L^{\infty}(Q_T)}$ .

**DEFINITION 3.1.** Suppose that  $u \in C(\overline{Q}_1)$  is given and that  $Q_T^{\pm}$  is defined by (3.3). Suppose that  $g_{\pm} : \mathbb{R} \rightarrow \mathbb{R}$  is continuous. We say  $v \in C(\overline{Q}_T)$  is a *generalized solution* of (3.1) – (3.2) if

$$v_t - \Delta v \in G(u, v) \text{ in } Q_T$$

i.e., there is  $q \in G(u, v)$  such that

$$v_t - \Delta v = q \text{ in } Q_T$$

in the distribution sense. Since  $G(u, v)$  depends on  $u$  only through its signature, this definition only depends on  $Q_T^{\pm}$  and is independent of the choice of  $u$ .

**PROPOSITION 3.2.** For  $u, v \in C(\overline{Q}_T)$  the set  $G(u, v)$  is a nonempty, bounded convex subset of  $L^{\infty}(Q_T)$ .

*Proof.* Since  $\Phi(s, \sigma)$  is convex in  $\mathbb{R}$ ,

$$\lambda q_1(z) + (1 - \lambda)q_2(z) \in \Phi(u(z), v(z)) \quad \text{for a.e. } z$$

if  $q_1, q_2 \in G(u, v)$  and  $0 < \lambda < 1$ . This implies that  $\lambda q_1 + (1 - \lambda)q_2 \in G(u, v)$  so  $G(u, v)$  is convex in  $L^{\infty}(Q_T)$ .

The Borel measurable function

$$\psi(s, \sigma) = \chi_{(-\infty, 0)}(s)g_-(\sigma) + \chi_{[0, \infty)}(s)g_+(\sigma)$$

on  $\mathbb{R}^n$  satisfies  $\psi(s, \sigma) \in \Phi(s, \sigma)$  for all  $s, \sigma \in \mathbb{R}$ , and therefore  $\psi(u, v) \in G(u, v)$ .

Since  $g_{\pm}$  is locally bounded, we see  $G(u, v)$  is bounded in  $L^{\infty}(Q_T)$ .  $\square$

LEMMA 3.3. *Suppose that  $u_m \rightarrow u$  in  $C(\overline{Q_T})$  and that  $v_m \rightarrow v$  in  $C(\overline{Q_T})$ . Suppose that  $q_m \in G(u_m, v_m)$ . Then there is a subsequence  $\{m_j\}$  and  $q \in G(u, v)$  such that  $q_{m_j} \rightarrow q$   $*$ -weakly in  $L^{\infty}(Q_T)$ .*

*Proof.* Since  $g_{\pm}$  is continuous,  $\bigcup_{m=1}^{\infty} G(u_m, v_m)$  is bounded in  $L^{\infty}(Q_T)$ . In particular  $\{q_m\}$  is bounded in  $L^{\infty}(Q_T)$ . By the Banach-Alaoglu theorem  $\{q_m\}$  has a  $*$ -weak convergent subsequence (still denoted  $\{q_m\}$ ), i.e.,

$$q_m \rightarrow q \text{ } * \text{-weakly in } L^{\infty}(Q_T).$$

In particular  $q_m \rightarrow q$  weakly in  $L^2(Q_T)$  since  $Q_T$  is bounded. Applying Mazur's theorem (see e.g. [Y]) we see there is  $\lambda_m^1, \dots, \lambda_m^{\ell_m} \geq 0$  with

$$\sum_{j=1}^{\ell_m} \lambda_m^j = 1$$

such that

$$\tilde{q}_m := \sum_{j=1}^{\ell_m} \lambda_m^j q_j \rightarrow q \text{ strongly in } L^2(Q_T) \text{ as } m \rightarrow \infty.$$

Taking a subsequence if necessary we may conclude

$$(3.6) \quad \tilde{q}_m(z) \rightarrow q(z) \quad (m \rightarrow \infty) \text{ for a.e. } z.$$

We fix  $z \in Q_T$  such that (3.6) and

$$(3.7) \quad q_m(z) \in \Phi(u_m(z), v_m(z)) \text{ for all } m \geq 1.$$

Suppose that  $u(z) = 0$ . By (3.4) and (3.7)

$$(3.8) \quad q_m(z) \in [\underline{g}(v_m(z)), \overline{g}(v_m(z))]$$

since  $\{g_{\pm}(v_m(z))\}$  lies in the interval in (3.8). Since  $\underline{g}$  and  $\overline{g}$  are continuous and  $v_m(z) \rightarrow v(z)$ , for each  $\varepsilon > 0$  there is  $m_0$  such that if  $m \geq m_0$  then

$$[\underline{g}(v_m(z)), \overline{g}(v_m(z))] \subset (a - \varepsilon, b + \varepsilon)$$

with

$$[a, b] := [\underline{g}(v(z)), \overline{g}(v(z))].$$

By (3.8) we now observe that

$$\tilde{q}_m(z) \in (a - \varepsilon, b + \varepsilon).$$

From (3.6) it follows that

$$q(z) \in (a - \varepsilon, b + \varepsilon).$$

Since  $\varepsilon > 0$  is arbitrary, this implies

$$(3.9) \quad q(z) \in [\underline{g}(v(z)), \overline{g}(v(z))].$$

Suppose that  $u(z) > 0$ . For sufficiently large  $m$ , say  $m \geq m_0$ , we may assume  $u_m(z) > 0$ . It follows that

$$\Phi(u_m(z), v_m(z)) = \{g_+(v_m(z))\} \text{ for } m \geq m_0.$$

By (3.7) we have

$$(3.10) \quad q_m(z) = g_+(v_m(z)) \text{ for } m \geq m_0.$$

Since  $\tilde{q}_m(z) \rightarrow q(z)$  by (3.6) and  $q_+$  is continuous, (3.10) yields

$$(3.11) \quad q(z) = q_+(v(z)).$$

The proof for  $u(z) < 0$  parallels that for  $u(z) > 0$ . By (3.9) and (3.11) one can conclude that

$$q(z) \in \Phi(u(z), v(z)), \text{ a.e. } z \in Q_T,$$

which completes the proof.  $\square$

**COROLLARY 3.4.** *The set  $G(u, v)$  is weak  $*$  compact in  $L^\infty(Q_T)$ .*

*Proof.* By Lemma 3.3 we see  $G(u, v)$  is weak  $*$  sequentially closed. Since  $G(u, v)$  is bounded by Proposition 3.2 and since the predual  $L^1(Q_T)$  is separable, one can drop the word “sequentially”. The boundedness of  $G(u, v)$  now implies that  $G(u, v)$  is weak  $*$  compact.  $\square$

*Remark 3.5.* The condition (3.2) is implicit in Definition 3.1. We will see that all generalized solution  $v$  has the regularity property (3.2).

**4. Main results.** We consider a system (3.1) – (3.2) coupled with an interface equation:

$$(4.1) \quad v_t = \Delta v + g_\pm(v) \quad \text{in } Q_T^\pm = \bigcup_{0 < t < T} \{t\} \times \Omega_\pm(t)$$

$$(4.2) \quad v(t) = v(t, \cdot) \in C^1(\mathbb{T}) \quad \text{for } 0 < t < T$$

$$(4.3) \quad V = \eta(\vec{n}, \nabla \vec{n}) + W(v)\alpha(\vec{n}) \quad \text{on } \Gamma(t) = \mathbb{T} \setminus (\Omega_+(t) \cup \Omega_-(t))$$

with given initial data

$$(4.4) \quad v(0, x) = v_0(x) \text{ in } \mathbb{T}$$

$$(4.5) \quad \Omega_\pm(t)|_{t=0} = \Omega_\pm(0).$$

Here we assume that

$$(4.6a) \quad g_\pm : \mathbb{R} \rightarrow \mathbb{R} \text{ is continuous and bounded}$$

$$(4.6b) \quad \eta \text{ satisfies (2.9) – (2.11)}$$

$$(4.6c) \quad W : \mathbb{R} \rightarrow \mathbb{R} \text{ is continuous}$$

$$(4.6d) \quad \alpha : S^{n-1} \rightarrow \mathbb{R} \text{ is continuous .}$$

We say  $(\Omega_\pm(t), v(t))$  is a *weak solution* of (4.1)–(4.5) if  $\{\Omega_\pm(t)\}_{0 \leq t < T}$  is a weak solution of (4.3), (4.5) with  $v \in C(\overline{Q_T})$  and  $v$  is a generalized solution of (4.1)–(4.2) with (4.4); see Definitions 2.1 and 3.1. We now state one of our main results.

**THEOREM 4.1.** *Let  $T > 0$ . Assume that  $g_{\pm}, \eta, W, \alpha$  satisfy (4.6a-d). Suppose that  $\Omega_+(0)$  and  $\Omega_-(0)$  are mutually disjoint open sets in  $\mathbb{T}$  and that  $v_0(x) \in C^2(\mathbb{T})$ . Then there exists a (global) weak solution  $(\Omega_{\pm}(t), v(t))$  of (4.1)–(4.5) such that  $v \in C^{1,0}(\overline{Q_T}) = \{v \in C(\overline{Q_T}); \nabla v \in C(\overline{Q_T})\}$ .*

*Remark 4.2.* We note that (4.3) includes

$$(4.3') \quad V = -c \operatorname{div} \vec{n} + W(v), \quad c \geq 0$$

as a special example. If (4.3') replaces (4.3) in (4.1) – (4.5), then it is known that there is a unique smooth local solution. This is proved by X.-Y. Chen [XYC] for  $c > 0$  and by X. Chen [XC2] for  $c = 0$  where  $\mathbb{R}^n$  replaces  $\mathbb{T}$ . Our result is the first global existence result even for this special system if the space dimension  $n \geq 2$ . For  $n = 1$  see [HNM].

We shall construct a solution using Kakutani's fixed point theory for a multi-valued mapping. We take a Banach space

$$X := C^{1,0}(\overline{Q_T}).$$

For  $v \in X$  we solve (4.3), (4.5) by applying Theorem 2.2. Since  $v$  can be extended continuously for  $t > T$  we have a unique weak solution  $\{\Omega_{\pm}(t)\}_{0 \leq t \leq T}$  for (4.3), (4.5) with given  $\Omega_{\pm}(0)$ . If we set

$$\tilde{Q}_T^{\pm} = \bigcup_{0 \leq t \leq T} \{t\} \times \Omega_{\pm}(t),$$

then we have a mapping

$$\mathcal{T}: X \rightarrow \mathcal{O}, v \mapsto (\tilde{Q}_T^+, \tilde{Q}_T^-),$$

where  $\mathcal{O}$  denotes the set of disjoint pair of open sets in  $[0, T] \times \mathbb{T}$ .

For  $q \in L^{\infty}(Q_T)$  let  $w = E(q)$  be the unique solution of

$$(4.7) \quad \begin{aligned} w_t - \Delta w &= q \text{ in } Q_T \\ w(0, x) &= v_0(x) \in C^2(\mathbb{T}). \end{aligned}$$

By the parabolic theory [LUS]  $E$  defines a continuous linear operator from  $L^{\infty}(Q_T)$  to  $\cap_{p>1} W_p^{2,1}(Q_T)$ , which is continuously embedded in  $X$  by the Sobolev inequality. Thus

$$E: L^{\infty}(Q_T) \rightarrow X$$

is a bounded linear operator. For  $u, v \in C(\overline{Q_T})$  we define a subset of  $X$  by

$$\mathcal{P}(u, v) = \{E(q); q \in G(u, v)\}.$$

This correspondence defines a mapping

$$\mathcal{P}: C(\overline{Q_T}) \times C(\overline{Q_T}) \rightarrow 2^X.$$

For given  $(\tilde{Q}_T^+, \tilde{Q}_T^-) \in \mathcal{O}$  we take  $u \in C(\overline{Q_T})$  such that

$$\tilde{Q}_T^{\pm} = \{(t, x) \in \overline{Q_T}; u \gtrless 0\}.$$

Since  $G$  depends on  $u$  through its signature, one may regard the mapping  $\mathcal{P}$  as

$$\mathcal{P} : \mathcal{O} \times C(\overline{Q}_T) \rightarrow 2^X.$$

For given  $v_0$  and  $\Omega_{\pm}(0)$  we define

$$\mathfrak{S} : X \rightarrow 2^X$$

by  $\mathfrak{S}(v) = \mathcal{P}(\mathcal{T}(v), v)$ . If  $\mathfrak{S}$  has a fixed point  $\bar{v} \in X$ , i.e.,

$$\bar{v} \in \mathfrak{S}(\bar{v})$$

it is easy to see that  $(\Omega_{\pm}(t), \bar{v}(t))$  is a weak solution of (4.1) – (4.5) where

$$\mathcal{T}(\bar{v}) = \bigcup_{0 \leq t \leq T} \{t\} \times \Omega_{\pm}(t).$$

We shall prove that  $\mathfrak{S}$  has a fixed point.

**PROPOSITION 4.3.** *The set  $\mathcal{P}(u, v)$  is nonempty, compact and convex in  $C(\overline{Q}_T)$  (and in  $X$ ).*

*Proof.* Since  $E$  defined by (4.7) is linear and  $G(u, v)$  is nonempty and convex by Proposition 3.2 we see  $\mathcal{P}(u, v)$  is convex.

We next observe that  $E$  is continuous from a bounded set of  $L^\infty(\overline{Q}_T)$  (equipped with weak  $*$  topology) to  $X$ . Indeed, if  $q_m \rightharpoonup q$   $*$  weakly in  $L^\infty(Q_T)$  then  $\{E(q_m)\}$  has a weakly convergent subsequence in  $W_p^{2,1}(Q_T)$  for  $p > 1$ . Since the inclusion

$$(4.8) \quad W_p^{2,1}(Q_T) \rightarrow X = C^{1,0}(\overline{Q}_T) \text{ is compact if } p > n + 1$$

(see e.g. [LUS]),  $E(q_m) \rightarrow w$  strongly in  $X$  by taking a subsequence. Since  $w_m = E(q_m)$  satisfies

$$(\partial_t - \Delta)w_m = q_m \text{ in } Q_T, \quad w_m(0, x) = v_0(x),$$

$w$  solves

$$(\partial_t - \Delta)w = q \text{ in } Q_T$$

in the distribution sense with  $w(0, x) = v_0(x)$ . This implies  $w = E(q)$ . Since the limit  $w$  is independent of the choice of subsequences, we observe

$$E(q_m) \rightarrow E(q) \text{ in } X.$$

This sequential continuity implies the continuity on a bounded set of  $L^\infty(Q_T)$ .

Since  $G(u, v)$  is weak  $*$  compact in  $L^\infty(Q_T)$ , the continuous image of  $G(u, v)$  is compact. The above continuity of  $E$  implies that  $\mathcal{P}(u, v)$  is compact in  $C^0(\overline{Q}_T)$  as well as in  $X$ .  $\square$

Since  $g_{\pm}$  is bounded by (4.6a), we see

$$\bigcup_{u, v \in C(\overline{Q}_T)} G(u, v)$$

is bounded in  $L^\infty(Q_T)$ . Therefore, by the parabolic theory for (4.7) [LUS]

$$\mathfrak{S}(v) \subset K = \{w \in W_p^{2,1}(Q_T); \|w\|_{W_p^{2,1}} \leq M\}, p > 1$$

if  $M$  is taken sufficiently large. We fix  $p > n + 1$  so that  $K$  is compact in  $X$  by (4.8). The mapping  $\mathfrak{S}$  is now interpreted as

$$\mathfrak{S} : X \rightarrow 2^K.$$

The graph of  $\mathfrak{S}$  is defined by

$$\text{gr}\mathfrak{S} = \{(v, w); w \in \mathfrak{S}(v)\} \subset X \times K.$$

Since  $K$  is compact,  $\text{gr}\mathfrak{S}$  is closed if and only if  $\mathfrak{S}$  is upper semicontinuous. For the definition of upper semicontinuity see [AF].

**PROPOSITION 4.4.** *The set  $\text{gr}\mathfrak{S}$  is closed in  $X \times K$ .*

*Proof.* Suppose that  $v_m, v \in X, w_m \in \mathfrak{S}(v_m), w \in X$  such that  $v_m \rightarrow v$  in  $X$  and  $w_m \rightarrow w$  in  $X$ . Our goal is to prove  $w \in \mathfrak{S}(v)$ . By the definition of weak solutions for (4.3) there is a viscosity solution  $u_m \in C(\overline{Q_T})$  of

$$u_t + F_m(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T$$

with

$$F_m(t, x, p, X) = F_\eta(p, X) - W(v_m(t, x))\alpha(-p/|p|)|p|$$

such that

$$\mathcal{J}(v_m) = (\{u_m(t, x) > 0\}, \{u_m(t, x) < 0\}).$$

One can arrange  $u_m(0, x) = u_0(x)$  independent of  $m$  such that

$$\Omega_\pm(0) = \{x \in \mathbb{T}; u_0(x) \gtrless 0\}.$$

Since  $v_m \rightarrow v$  in  $C(\overline{Q_T})$ , by the stability of viscosity solutions there is  $u \in C(\overline{Q_T})$  such that  $u_m \rightarrow u$  in  $C(\overline{Q_T})$  and  $u$  solves (in the viscosity sense)

$$u_t + F(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T$$

with  $F(t, x, p, X) = F_\eta(p, X) - W(v(t, x))\alpha(-p/|p|)|p|$  (see Theorem in Appendix), where  $u(0, x) = u_0(x)$ . This implies

$$(4.9) \quad \mathcal{J}(v) = (\{u > 0\}, \{u < 0\}).$$

By the definition of  $\mathcal{P}$  there is  $q_m \in G(u_m, v_m)$  such that

$$(4.10) \quad \begin{aligned} (\partial_t - \Delta)w_m &= q_m \text{ in } Q_T, \\ w_m(0, x) &= v_0(x) \text{ on } \mathbb{T}. \end{aligned}$$

Applying Lemma 3.3, we may conclude that

$$q_m \rightharpoonup q \text{ * -weakly in } L^\infty(Q_T)$$

with some  $q \in G(u, v)$  by taking a subsequence if necessary. Since  $w_m \rightarrow w$  in  $X$ , (4.10) implies that

$$(\partial_t - \Delta)w = q \text{ in } Q_T$$

in the distribution sense and

$$w(0, x) = v_0(x).$$

This yields  $w \in \mathcal{S}(v)$  by (4.9) so the proof is now complete.  $\square$

*Proof of Theorem 4.1.* Since  $K$  is compact and convex by Propositions 4.3 and 4.4 one can apply the following fixed point theorem to conclude that there is  $\bar{v} \in \mathcal{S}(\bar{v}) \cap K$ . By the definition of  $\mathcal{S}$  we see  $\bar{v}$  together with  $\mathcal{T}(\bar{v})$  is a desired weak solution of (4.1)–(4.5).

**KAKUTANI'S FIXED POINT THEOREM** [AF, THEOREM 3.2.3]. *Let  $K$  be a convex compact subset of a Banach space  $X$  and  $\mathcal{S} : X \rightarrow 2^K$ . If  $\mathcal{S}$  is upper semicontinuous and  $\mathcal{S}(v)$  is a convex closed set in  $K$  for  $v \in X$ , then  $\mathcal{S}$  has a fixed point  $\bar{v} \in K \cap \mathcal{S}(\bar{v})$ .*

*Remark 4.5.* The assumption  $v_0(x) \in C^2(\mathbb{T})$  in Theorem 4.1 is weakened as  $v_0(x) \in W^{2-2/p}(\mathbb{T})$ ,  $p > n + 1$  because the regularity condition on  $v_0$  is only used to solve (4.7) in  $W_p^{2,1}(\bar{Q}_T)$ .

We conclude this paper by stating an existence result of a global solution on the time interval  $(0, \infty)$ .

**THEOREM 4.6.** *Assume the same hypotheses of Theorem 4.1 for  $g_t, \eta, w, \alpha, \Omega_\pm(0)$ . Suppose that  $v_0 \in W^{2-2/p}(\mathbb{T})$  for  $p > n + 1$ . Then there exists  $\{(\Omega_\pm(t), v(t))\}_{t \geq 0}$  which is a weak solution of (4.1) – (4.5) for arbitrary  $T > 0$ .*

*Proof.* For fixed  $T > 0$  by Remark 4.5 there is  $v_T \in \mathcal{S}(v_T)$ . This implies

$$\begin{aligned} (\partial_t - \Delta)v_T &= q_T \text{ in } Q_T, \\ v_T(0, x) &= v_0(x), \end{aligned}$$

with

$$q_T \in \bigcup_{u, v \in C(\bar{Q}_T)} G(u, v).$$

Since  $g_\pm$  is bounded by (4.6a) we observe

$$|q_T|_{L^\infty(Q_T)} \leq M = \sup_\sigma |g_\pm(\sigma)|$$

By the parabolic regularity theory [LUS]  $\{v_T\}_{T \geq 1}$  is bounded in  $W_p^{2,1}(\bar{Q}_{t_0})$  ( $p > n + 1$ ) for each  $t_0 > 0$ . By (4.8) and a diagonal argument there is a subsequence  $\{v_{T'}\}$  and  $v \in C([0, \infty) \times \mathbb{T})$  such that

$$(4.11) \quad v_{T'} \rightarrow v \text{ in } X_{t_0} = C^{1,0}(\bar{Q}_{t_0}).$$

Since  $v_{T'} \in \mathcal{S}(v_{T'}) \subset X_{t_0}$  and  $\text{gr}\mathcal{S}$  is closed, (4.11) implies  $v \in \mathcal{S}(v) \subset X_{t_0}$  where  $\mathcal{S}$  depends on  $t_0$ . Since  $t_0$  is arbitrary, this yields a desired global solution on  $[0, \infty)$ .  $\square$

**Appendix.** We shall state stability properties of viscosity solutions used in the proof of Proposition 4.4 for the reader's convenience. We use a following notation. For  $h_m : L \rightarrow \mathbb{R}$ ,  $L \subset Z$  we define

$$\begin{aligned} \lim_* h_m : \bar{L} &\rightarrow \mathbb{R} \cup \{-\infty\} \\ \lim^* h_m : \bar{L} &\rightarrow \mathbb{R} \cup \{+\infty\} \end{aligned}$$

by

$$(\lim_* h_m)(z) = \lim_{\substack{m \rightarrow \infty \\ \varepsilon \downarrow 0}} \inf \{h_j(y), d(z, y) < \varepsilon, j \geq m, y \in L\}$$

$$\text{and } \lim_* h_m = -\lim_* (-h_m),$$

where  $Z$  is a metric space with the metric  $d$ . If  $h$  is independent of  $m$ , we write  $h_* = \lim_* h_m$ ,  $h^* = \lim^* h_m$ . We shall suppress the word “viscosity”.

LEMMA. *Suppose that  $F_m : Q_T \times \mathbb{R}^n \times \mathbb{S}_n \rightarrow \mathbb{R}$  is lower semicontinuous and that  $F = \lim_* F_m$ . Suppose that  $u_m$  is a subsolution of*

$$u_t + F_m(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T.$$

*Then  $u = \lim^* u_m$  is a subsolution of*

$$u_t + F(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T$$

*provided that  $u$  does not take  $+\infty$  in  $Q_T$ .*

Similar results are proved by Barles and Perthame [BP] for first order differential equations and formulated in Ishii [I] in the general case. Since the proof is easily modified for our setting, we omit the proof. The following is a simple application of Lemma, the comparison Proposition 2.3, and construction of sub and supersolutions.

THEOREM. *Suppose that  $\eta, W, \alpha$  satisfy (4.6 b-d). Suppose that  $v_m \rightarrow v$  in  $C(\overline{Q}_T)$ . We set*

$$\begin{aligned} F_m &= F_\eta(p, X) - W(v_m(t, x))\alpha(-p/|p|)|p|, \\ F &= F_\eta(p, X) - W(v(t, x))\alpha(-p/|p|)|p|, \end{aligned}$$

*where  $F_\eta$  is defined by (2.3). Suppose that  $u_m \in C(\overline{Q}_T)$  is a solution of*

$$(1) \quad u_t + F_m(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T$$

*with  $u_m(0, x) = u_0(x) \in C(\mathbb{T})$ . Then  $u_m \rightarrow u$  in  $C(\overline{Q}_T)$  for some  $u \in C(\overline{Q}_T)$  and  $u$  is a solution of*

$$(2) \quad u_t + F(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T$$

*with  $u(0, x) = u_0(x)$ .*

*Proof.* Since  $v_m \rightarrow v$  in  $C(\overline{Q}_T)$  there are sub and supersolutions  $w_\pm$  of (1) such that

$$(3) \quad \begin{aligned} w_\pm(0, x) &= u_0(x) \\ w_-(t, x) &\leq u_0(x) \leq w_+(t, x) \text{ in } Q_T \end{aligned}$$

and that  $w_\pm$  is independent of  $m$ ; see [CGG, Proposition 6.4] and the proof of Theorem 2.2. By Proposition 2.3 we see

$$(4) \quad w_- \leq u_m \leq w_+ \text{ in } Q_T.$$

Since  $u_m$  is a subsolution of

$$u_t + (F_m)_*(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T$$

by definition, applying Lemma yields that  $\bar{u} = \lim^* u_m$  is a subsolution of

$$u_t + F_*(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T.$$

(This is the definition that  $\bar{u}$  is a subsolution of (2)). Similarly  $\underline{u} = \lim_* u_m$  is a supersolution of

$$u_t + F^*(t, x, \nabla u, \nabla^2 u) = 0 \text{ in } Q_T.$$

By (3) we observe that

$$\bar{u}(0, x) = \underline{u}(0, x) = u_0(x).$$

Applying Proposition 2.3 implies  $\bar{u} = \underline{u}$  and  $u = \bar{u}$  is a solution of (2). The property  $\bar{u} = \underline{u}$  implies that  $u_m \rightarrow u$  in  $C(\bar{Q}_T)$ . The proof is now complete.  $\square$

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