

**AN ERROR ESTIMATE FOR FINITE ELEMENT  
METHODS FOR SCALAR CONSERVATION LAWS**

By

**Bernardo Cockburn**

and

**Pierre-Alain Gremaud**

**IMA Preprint Series # 1144**

June 1993

# AN ERROR ESTIMATE FOR FINITE ELEMENT METHODS FOR SCALAR CONSERVATION LAWS

BERNARDO COCKBURN\* AND PIERRE-ALAIN GREMAUD†

**ABSTRACT.** In this paper, the Shock-Capturing Streamline Diffusion method and the Shock-Capturing Discontinuous Galerkin method for scalar conservation laws are proven to converge to the entropy solution with a rate of at least  $h^{1/8}$  in the  $L^\infty(L^1)$ -norm. The triangulations are made of general acute simplexes and the approximate solution is taken to be piecewise a polynomial of degree  $k$ . The result is independent of the dimension of the space.

**1. Introduction.** In this paper, we consider the problem of estimating the difference between the entropy solution of the initial value problem, [7],

$$\partial_t u + \operatorname{div} f(u) = 0 \quad \text{in } (0, T_\infty) \times \mathbb{R}^d, \quad (1.1)$$

$$u(0) = u_0 \quad \text{on } \mathbb{R}^d, \quad (1.2)$$

and the approximate solution given by the so-called Shock-Capturing Streamline Diffusion (SCSD) method, see [3], [9], [10] and the references therein, or given by the so-called Shock-Capturing Discontinuous Galerkin (SCDG) method, see [5] and [4]. More precisely, we prove that the  $L^\infty(L^1)$ -norm of the above mentioned difference goes to zero at least as  $h^{1/8}$  as the discretization parameter  $h$  goes to zero. We assume the flux function  $f : \mathbb{R} \rightarrow \mathbb{R}^d$  to be smooth and take the compactly supported initial data  $u_0$  in the space  $L^\infty(\mathbb{R}^d) \cap BV(\mathbb{R}^d)$  of bounded functions of bounded variation in  $\mathbb{R}^d$ .

Convergence of the SCSD method was first obtained by Szepessy [9]. By using the DiPerna theory [2] of measure-valued solutions for (1.1), (1.2), Szepessy proved that the piecewise-linear approximate solution given by the SCSD method converges in  $L^p_{loc}((0, T) \times \mathbb{R}^2)$  to the entropy solution of (1.1), (1.2), for any  $p \in [1, \infty)$ . Later, Szepessy [10] extended this result to the case of a general scalar conservation law in several space dimensions with boundary conditions and an approximate solution which is piecewise polynomial of degree  $k$ .

---

1991 *Mathematics Subject Classification.* Primary 65M60, 65N30, 35L65.

*Key words and phrases.* Error estimates, Streamline Diffusion method, Discontinuous Galerkin method, multidimensional conservation laws.

\*School of Mathematics, University of Minnesota, 127 Vincent Hall, Minneapolis, MN 55455. Partially supported by the NSF grant DMS-91-03997.

†School of Mathematics, University of Minnesota, 127 Vincent Hall, Minneapolis, MN 55455. Partially supported by a grant from the Fonds National Suisse pour la Recherche Scientifique.

To obtain convergence results in the framework of measure-valued solutions for (1.1), (1.2), [2], the approximate solution must

- (i) be bounded in the  $L^\infty((0, T_\infty) \times \mathbb{R}^d)$ -norm,
- (ii) be weakly consistent with all entropy inequalities,
- (iii) be strongly consistent with the initial condition.

Recently, Jaffré, Johnson, and Szepessy, [4], proved that the SCDG method converges to the entropy solution of problem (1.1), (1.2) by using an extension of the measure-value convergence theory of DiPerna [2] obtained by Szepessy [11] which allows to replace in (i), the  $L^\infty((0, T_\infty) \times \mathbb{R}^d)$ -norm by the  $L^\infty(0, T_\infty; L^2(\mathbb{R}^d))$ -norm. In this paper, we consider the case of piecewise polynomial approximations of degree  $k$  and show how to obtain, not only convergence, but error estimates with only a suitable version of (ii); the properties (i) and (iii) do not need to be obtained. The basic idea is to combine the estimates of the entropy dissipation, needed in (ii), with a modification of the Kuznetsov approximation theory [8] obtained by Cockburn, Coquel and LeFloch in [1].

The paper is organized as follows. In §2, we display the SCSD and SCDG methods and state and briefly discuss our main result, Theorem 2.1. The remaining of the paper is devoted to prove Theorem 2.1. In §3, we recall the basic approximation inequality obtained in [1]. This inequality states that, in order to obtain error estimates, only an estimate of the entropy dissipation is required. Such an estimate is obtained in §5 by using an *a priori* estimate and some very simple auxiliary results derived in §4. In §6, we end the proof of Theorem 2.1.

**2. The main result.** In this section, we describe the SCSD and SCDG finite element methods and state and briefly discuss the main result, Theorem 2.1.

The methods we have in mind being essentially implicit, we first decompose our domain into “slabs”. More precisely, let  $0 = t_0 < t_1 < t_2 < \dots < t_N = T_\infty$  be a sequence of time levels. We set

$$\begin{aligned} S_n &= (t_n, t_{n+1}) \times \mathbb{R}^d, & n = 0, \dots, N-1, \\ \mathbb{R}^d_n &= \{t_n\} \times \mathbb{R}^d, & n = 0, \dots, N. \end{aligned}$$

In each slab  $S_n$ , we define a triangulation  $\mathcal{T}_{h,n}$  of  $(d+1)$ -simplexes. No compatibility at  $t = t_n$  between the meshes of two consecutive slabs  $S_n$  and  $S_{n+1}$ ,  $n = 0, \dots, N-1$ , is required. We only assume that the triangulations satisfy the following simple conditions:

$$T \text{ is acute for all } T \in \mathcal{T}_{h,n}, \text{ and } n = 0, \dots, N-1, \quad (2.1a)$$

$$\frac{h_T}{\rho_T} \leq \sigma \quad \text{for all } T \in \mathcal{T}_{h,n}, \text{ and } n = 0, \dots, N-1, \quad (2.1b)$$

$$h_T \geq \bar{c} h \quad \text{for all } T \in \mathcal{T}_{h,n}, \text{ and } n = 0, \dots, N-1, \quad (2.1c)$$

where  $h_T$  is the diameter of  $T \in \mathcal{T}_{h,n}$ ,  $\rho_T$  is the diameter of the biggest ball totally included in  $T$ ,  $h = \max\{h_T, T \in \mathcal{T}_{h,n}, n = 0, \dots, N-1\}$ , and  $\bar{c}$  is a positive constant. The set of  $d$ -simplexes corresponding to the edges of  $\mathcal{T}_{h,n}$  is denoted  $\partial\mathcal{T}_{h,n}$ .

Taking into account the fact that  $u_0$  and (consequently)  $u(t, \cdot)$ ,  $t \in [0, T_\infty]$ , have compact support, we introduce the following spaces

$$\begin{aligned} V_{h,n} &= \{v; v|_T \in \mathcal{P}_k(T), \forall T \in \mathcal{T}_{h,n}, v = 0 \text{ for } |x| \geq M\}, \\ V_h &= \{v : \mathbb{R}^+ \times \mathbb{R}^d \rightarrow \mathbb{R}, v|_{(t_n, t_{n+1})} \in V_{h,n}\}, \end{aligned}$$

where  $M$  is a sufficiently large constant and  $\mathcal{P}_k$  stands for the space of polynomials of degree  $k$ . We emphasize that no continuity requirements are imposed upon the functions in  $V_h$ . Following [10], we partition each  $(d+1)$ -simplex  $T$  into  $k^{d+1}$  congruent  $(d+1)$ -simplexes, denoted by  $T_i$ , and introduce the spaces

$$\begin{aligned} \hat{V}_{h,n} &= \{v; v|_{T_i} \in \mathcal{P}_1(T_i), i = 1, \dots, k^{d+1}, \forall T \in \mathcal{T}_{h,n}, v = 0 \text{ for } |x| \geq M\}, \\ \hat{V}_h &= \{v : \mathbb{R}^+ \times \mathbb{R}^d \rightarrow \mathbb{R}, v|_{(t_n, t_{n+1})} \in \hat{V}_{h,n}\}. \end{aligned}$$

For each  $v \in V_h$ , we define  $\hat{v}$  to be the element of  $\hat{V}_h$  that coincides with  $v$  on each of the vertices of the  $(d+1)$ -simplexes  $T_i$ , for  $i = 1, \dots, k^{d+1}$  and every  $T$  of  $\mathcal{T}_{h,n}$ , for  $n = 0, \dots, N-1$ .

Finally, we define, for all  $T \in \mathcal{T}_{h,n}$  and  $n = 0, \dots, N-1$ ,

$$\begin{aligned} \mathbb{P}_h(v)|_T &= \frac{1}{|T|} \int_T v \, dx dt, \\ \|v\|_{\mathbb{P}_h}(t, x) &= \frac{1}{|T|^{1/2}} \|v\|_{L^2(T)}, \text{ for } (t, x) \in T, \end{aligned}$$

and, for all  $e \in \partial\mathcal{T}_{h,n}$  and  $n = 0, \dots, N-1$ ,

$$\begin{aligned} \mathbb{P}_h(v^T)|_e &= \frac{1}{|e|} \int_e v^T \, d\lambda, \\ \|v^T\|_{\mathbb{P}_h}(t, x) &= \frac{1}{|e|^{1/2}} \|v^T\|_{L^2(e)}, \text{ for } (t, x) \in e, \end{aligned}$$

where for  $p = (t, x) \in e \setminus \partial e$ , we have used the notation  $v^T(p) = \lim_{s \downarrow 0} v(p - sn_{e,T})$ ,  $n_{e,T}$  being the unit outer normal to  $T$  along its face  $e$ .

The approximate solution  $u_h$  given by the SCDG method is defined to be the element of  $V_h$  such that

$$\begin{aligned} &\sum_{T \in \mathcal{T}_{h,n}} \int_T A(u_h)(v + \delta \tilde{A}(u_h, v)) \, dx dt + \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \left( f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T} \right) v^T \, d\lambda \\ &+ \sum_{T \in \mathcal{T}_{h,n}} \int_T \varepsilon_1(u_h) \mathbb{P}_h(\nabla \hat{u}_h \cdot \nabla \hat{v}) \, dx dt + \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \varepsilon_2(u_h^T) \mathbb{P}_h(\nabla_e \hat{u}_h^T \cdot \nabla_e \hat{v}^T) \, d\lambda = 0, \\ &\forall v \in V_{h,n}, \quad n = 0, 1, \dots, N-1, \end{aligned} \tag{2.2}$$

where

$$A(v) = \partial_t v + \sum_{i=1}^d \partial_i f_i(v), \quad \tilde{A}(w, v) = \partial_t v + \sum_{i=1}^d f'_i(w) \partial_i v,$$

$$\nabla = (\partial_t, \partial_1, \partial_2, \dots, \partial_d), \quad \nabla_x = (\partial_1, \partial_2, \dots, \partial_d), \quad \nabla_e v^T = \nabla(v^T|_e),$$

and where  $v^{T_e}(p) = \lim_{s \downarrow 0} v(p + sn_{e,T})$ , for  $p = (t, x) \in e \setminus \partial e$  and  $e \in \partial T$ . The initial condition is defined as follows:

$$u_h^{T_e}(0, \cdot) = u_{0h}, \text{ for all } e \in \partial \mathcal{T}_{h,0} \cap \mathbb{R}_0^d, \quad (2.3)$$

$u_{0h}$  being the standard  $L^2$ -projection of  $u_0$  into the space of functions which are polynomials of degree  $k$  on  $e \in \partial \mathcal{T}_{h,0} \cap \mathbb{R}_0^d$ .

We use throughout the paper the so-called Lax-Friedrichs flux

$$f_{e,T}^{LF}(u_h^T, u_h^{T_e}) = \frac{1}{2}(\tilde{f}(u_h^T) + \tilde{f}(u_h^{T_e})) \cdot n_{e,T} + C_e^{LF}(u_h^T - u_h^{T_e}), \quad (2.4a)$$

where  $\tilde{f}(u_h) = (u_h, f(u_h))$ ,  $C_e^{LF} = 1/2$  if  $n_{e,T} = (\pm 1, 0, \dots, 0)$ . We assume that

$$C_e^{LF} - \frac{1}{2}|\tilde{f}'|_{e,\infty} \geq c_* > 0, \quad \text{for } e \in \mathcal{E}_n, \quad (2.4b)$$

with  $|\tilde{f}'|_{e,\infty} = \max\{|\tilde{f}'(\xi) \cdot n_{e,T}|, \xi \in [\min\{u_h^T, u_h^{T_e}\}, \max\{u_h^T, u_h^{T_e}\}]\}$  and where  $\mathcal{E}_n$  denotes the subset of the edges  $\partial \mathcal{T}_{h,n}$  whose intersection with  $\mathbb{R}_n^d \cup \mathbb{R}_{n+1}^d$  is of measure zero. The condition (2.4b) ensures that the flux  $f_{e,T}^{LF}(a, b)$  is a strictly monotone flux, that is, an increasing function of  $a$  and a decreasing function of  $b$ .

Finally, for  $T \in \mathcal{T}_{h,n}$ ,  $n = 0, 1, \dots, N-1$ , the shock capturing terms  $\varepsilon_1$  and  $\varepsilon_2$  are defined as follows

$$\varepsilon_1(v(\cdot, \cdot))|_T = \begin{cases} \delta_1 \frac{|A(v(\cdot, \cdot))|}{\|\nabla \hat{v}\|_{\mathbb{P}_k}} & \text{if } \|\nabla \hat{v}\|_{\mathbb{P}_k} \neq 0, \\ 0 & \text{if } \|\nabla \hat{v}\|_{\mathbb{P}_k} = 0, \end{cases}$$

and

$$\varepsilon_2(v^T)|_e = \begin{cases} \delta_2 \frac{|f_{e,T}^{LM}(v^T, v^{T_e}) - \tilde{f}(v^T) \cdot n_{e,T}|}{\|\nabla_e \hat{v}^T\|_{\mathbb{P}_k}} & \text{if } \|\nabla_e \hat{v}^T\|_{\mathbb{P}_k} \neq 0, \\ 0 & \text{if } \|\nabla_e \hat{v}^T\|_{\mathbb{P}_k} = 0, \end{cases}$$

for any  $v \in V_h$ . The parameters  $\delta$ ,  $\delta_1$ , and  $\delta_2$  will be defined later.

On the other hand, the SCSD method is the exact analog of SCDG but with *continuous* approximations inside each slab  $S_n$ ,  $n = 0, 1, \dots, N-1$ . Namely, instead of  $V_{h,n}$ , one considers the space  $\mathcal{V}_{h,n}$ , where

$$\mathcal{V}_{h,n} = \{v \in C^0(S_n); v|_T \in \mathcal{P}_k(T), \forall T \in \mathcal{T}_{h,n}, v = 0 \text{ for } |x| \geq M\}.$$

The spaces  $\mathcal{V}_h$ ,  $\hat{\mathcal{V}}_{h,n}$ ,  $\hat{\mathcal{V}}_h$  are also defined accordingly. Thus, the approximate solution  $u_h$  given by the SCSD method is the element of  $\mathcal{V}_h$  such that

$$\begin{aligned} & \int_{S_n} A(u_h)(v + \delta \tilde{A}(u_h, v)) dx dt + \int_{\mathbb{R}_n^d} (u_{h,+} - u_{h,-}) v_+ dx + \int_{S_n} \varepsilon_1(u_h) \mathbb{P}_k(\nabla \hat{u}_h \cdot \nabla \hat{v}) dx dt \\ & + \int_{\mathbb{R}_n^d} \varepsilon_2^{SD}(u_{h,+}) \mathbb{P}_k(\nabla_x \hat{u}_{h,+} \cdot \nabla_x \hat{v}_+) dx = 0, \quad \forall v \in \mathcal{V}_{h,n}, \quad n = 0, 1, \dots, N-1, \end{aligned} \quad (2.5)$$

where

$$\varepsilon_2^{SD}(v(t_n, \cdot))|_K = \begin{cases} \delta_2 \frac{|v_+(t_n, \cdot) - v_-(t_n, \cdot)|}{\|\nabla_x \hat{v}_+(t_n)\|_{\mathbb{P}_h}} & \text{if } \|\nabla_x \hat{v}_+(t_n)\|_{\mathbb{P}_h} \neq 0, \\ 0 & \text{if } \|\nabla_x \hat{v}_+(t_n)\|_{\mathbb{P}_h} = 0, \end{cases}$$

for any  $v \in \mathcal{V}_h$ , and where  $u_{h,\pm} = \lim_{s \rightarrow \pm 0} v(t + s, x)$ . Instead of (2.3), the initial condition is now given by

$$u_{h,-}(0, \cdot) = u_{0h}. \quad (2.6)$$

Notice that for both methods,  $u_h|_{S_n}$  is not coupled to  $u_h|_{S_{n+1}}$ ,  $n = 0, \dots, N-1$ , as a consequence of the “slab structure” and of the upwinding in time used in both numerical schemes.

Since the only relevant values of the nonlinear flux  $f$  are those in the range of the entropy solution  $u$ ,  $[a, b]$ , we extend each of the components of  $f$  smoothly in such a way that the extension is affine linear outside a fixed compact including  $[a, b]$ . We use that extension, which we still call  $f$ , to define the above schemes. Existence of a solution to (2.2), (2.3) (or (2.5), (2.6)) is well known and can be obtained by a fixed point argument; see [9], [10] and the references quoted therein.

We can now state our main result.

**Theorem 2.1.** *Let  $u$  be the unique weak entropy satisfying solution of (1.1), and let  $u_h$  be either a solution of (2.2) or of (2.5). Then, there exists a constant  $C$ , such that, for  $\delta = \mathcal{O}(h)$ ,  $\delta_1 = \mathcal{O}(h^{3/4})$ , and  $\delta_2 = \mathcal{O}(h^{3/4})$ ,*

$$\|u_h(\tau, \cdot) - u(\tau, \cdot)\|_{L^1(\mathbb{R}^d)} \leq C \left( \|u_{0h} - u_0\|_{L^1(\mathbb{R}^d)} + h^{1/8} \right) \quad \forall \tau \in (0, T_\infty).$$

The constant  $C$  depends on  $k, d, \sigma, \bar{c}, c^*$ ,  $\|u_0\|_{L^2(\mathbb{R}^d)}$ , and  $TV(u_0)$ .

Several versions of the SCSD and SCDG methods (i.e. several definitions of  $\varepsilon_1$ ,  $\varepsilon_2$  or  $\varepsilon_2^{SD}$ ) can be found in the literature; see e.g. [3], [6], [9], [10], and [4]. If, for instance, we do not divide by the gradient of the approximate solution in the definition of  $\varepsilon_1$ ,  $\varepsilon_2$  or  $\varepsilon_2^{SD}$ , we obtain different methods which, nevertheless, can be analyzed using the same technique as in this paper. The theoretical order of convergence (with  $\delta$ ,  $\delta_1$ , and  $\delta_2$  of order  $h$ ) is found to be the same as the one in Theorem 2.1.

Since the proofs follow the same lines for both methods (with a few simplifications due to the higher regularity of the approximate solution in the case of SCSD), we will, from now on, exclusively concentrate our attention on the SCDG algorithm. The proof of the above result relies on an approximation inequality obtained in [1] by suitably modifying the Kuznetsov approximation result [8, Lemma 2]. According to this new inequality, the error estimate follows from the estimate of the so-called entropy dissipation form. This approximation result is recalled in the next section.

**3. Kuznetsov approximation theory.** We follow Kuznetsov [8]. We first introduce the notation. Let  $w : \mathbb{R} \rightarrow \mathbb{R}$  be a smooth nonnegative even function with unit mass and support in  $[-1, 1]$ . We set

$$\varphi = w_{\varepsilon_t}(t - t') \prod_{i=1}^d w_{\varepsilon_x}(x_i - x'_i), \quad (x, t), (x', t') \in \mathbb{R}^d \times \mathbb{R}^+,$$

where  $\varepsilon_t$  and  $\varepsilon_x$  are two arbitrary positive numbers and  $w_\lambda(s) = w(s/\lambda)/\lambda$  for any  $s \in \mathbb{R}$ ,  $\lambda = \varepsilon_t, \varepsilon_x$ .

For  $u$  and  $v$  right-continuous functions from  $(0, T)$  to  $L^1(\mathbb{R}^d)$ , we define

$$E^{\varepsilon_t, \varepsilon_x}(v, u; \tau) = \int_0^\tau \int_{\mathbb{R}^d} \Theta_\tau^{\varepsilon_t, \varepsilon_x}(v, u; t, x) dx dt$$

with

$$\begin{aligned} \Theta_\tau^{\varepsilon_t, \varepsilon_x}(v, c; t, x) &= - \int_0^\tau \int_{\mathbb{R}^d} U(v(t', x') - c) \partial_{t'} \varphi dx' dt' \\ &\quad - \int_0^\tau \int_{\mathbb{R}^d} F(v(t', x'), c) \cdot \nabla_{x'} \varphi dx' dt' \\ &\quad - \int_{\mathbb{R}^d} U(v_-(0, x') - c) \varphi(t, x, 0, x') dx' \\ &\quad + \int_{\mathbb{R}^d} U(v(\tau, x') - c) \varphi(t, x, \tau, x') dx', \end{aligned}$$

where  $U$  is an arbitrary even entropy and  $F$  its associated flux, i.e.,  $\partial_u F(u, c) = U'(u)f'(u)$ , and  $v_-(0, \cdot)$  is the exterior trace of  $v$  at  $t = 0$ . We recall that if  $u$  is the entropy solution of (1.1), (1.2) and if we set  $u_-(0, x) = u_0(x)$ , then  $E^{\varepsilon_t, \varepsilon_x}(u, v; \tau) \leq 0$  for any  $v$ .

We restrict our attention to one particular family of entropies. Let  $G : \mathbb{R} \rightarrow \mathbb{R}^+$  be a smooth even function such that

$$G(0) = 0, \quad G'(x) = \begin{cases} 1 & \text{if } x \geq 1 \\ -1 & \text{if } x \leq -1 \end{cases}, \quad G'' \geq 0. \quad (3.1)$$

For any  $c \in \mathbb{R}$ , we define,

$$U_\varepsilon(u) = \varepsilon G\left(\frac{u}{\varepsilon}\right) \quad \text{and} \quad F_{c, \varepsilon, i}(u) = \int_c^u G'_\varepsilon(\lambda) f'_i(\lambda) d\lambda \quad i = 1, \dots, d.$$

Our main result is based on the following basic approximation inequality.

**Lemma 3.1** (Basic approximation inequality, [1]). *Let  $u$  be the entropy solution of (1.1). We have*

$$\begin{aligned} \int_{\mathbb{R}^d} U(v(T_\infty, x') - u(T_\infty, x')) dx' &\leq \sqrt{e} \int_{\mathbb{R}^d} U(v_-(0, x') - u_0(x')) dx' \\ &\quad + C(T_\infty \varepsilon + \varepsilon_x + \varepsilon_t) TV(u_0) + 2\sqrt{e} \sup_{0 \leq \tau \leq T_\infty} E^{\varepsilon_t, \varepsilon_x}(v, u; \tau), \end{aligned}$$

where  $C$  is a constant independent of  $\varepsilon, \varepsilon_x$ , and  $\varepsilon_t$ .

If we take  $v_-(0, x) = u_{0h}$  and set  $v$  equal to the right-continuous function that coincides with  $u_h$  on each interval of the form  $(t_n, t_{n+1})$ , we see that to obtain our error estimates, we only have to estimate the entropy dissipation  $E^{\varepsilon_t, \varepsilon_x}(v_h, u; \tau)$ . From now on, we will not distinguish between  $v_h$  and  $u_h$ .

We devote the remaining part of this section to the rewriting of the entropy dissipation  $E^{\varepsilon_t, \varepsilon_x}(u_h, u; \tau)$  as the sum of nine terms, which will then be estimated in §5. For the sake of clarity, we use, from now on, the following simplified notation:

$$\begin{aligned} u_h &= u_h(t', x'), & u &= u(t, x), \\ u_h^T &= u_h^T(t', x'), & u_h^{T_e} &= u_h^{T_e}(t', x'), \\ \varphi &= \varphi(t, x, t', x'), & \varphi(t_i, p_i) &= \varphi(t, x, t_i, p_i). \end{aligned}$$

(We recall that  $u_h^T$  and  $u_h^{T_e}$  refer to the internal and external traces of  $u_h$  on the boundary of the simplex  $T$ .) Furthermore, we will put a prime as a superscript in an operator when we want to emphasize the fact that such an operator is considered to be acting on the ‘primed’ variables only.

Using the definitions of the form  $\Theta_\tau^{\varepsilon_t, \varepsilon_x}$  and of the function  $F$ , we obtain, after a simple integration by parts,

$$\begin{aligned} \Theta_\tau^{\varepsilon_t, \varepsilon_x}(u_h, u; t, x) &= \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A'(u_h) U'(u_h - u) \varphi \, dx' dt' \\ &\quad - \sum_{n=0}^{N_\tau-1} \sum_{e \in \partial \mathcal{T}_{h,n}} \int_e \left( \tilde{F}(u_h^T, u) - \tilde{F}(u_h^{T_e}, u) \right) \cdot n_{e,T} \varphi \, d\lambda', \end{aligned}$$

where  $\tau, 0 < \tau \leq T_\infty$ , is supposed to be such that there exists  $N_\tau, 0 < N_\tau \leq N$ , with  $t_{N_\tau} = \tau$ , and where  $\tilde{F}(u_h, u) = (U(u_h - u), F(u_h, u))$  is the “extended” entropy flux. Following [9], we introduce the classical nodal interpolation operator  $\Pi'_h$  (which acts only on the variables  $t'$  and  $x'$ ) and rewrite  $\Theta_\tau^{\varepsilon_t, \varepsilon_x}$  as follows:

$$\begin{aligned} \Theta_\tau^{\varepsilon_t, \varepsilon_x}(u_h, u; t, x) &= \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A'(u_h) \Pi'_h(U'(u_h - u) \varphi) \, dx' dt' \\ &\quad + \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A'(u_h) \left( U'(u_h - u) \varphi - \Pi'_h(U'(u_h - u) \varphi) \right) \, dx' dt' \\ &\quad - \sum_{n=0}^{N_\tau-1} \sum_{e \in \partial \mathcal{T}_{h,n}} \int_e \left( \tilde{F}(u_h^T, u) - \tilde{F}(u_h^{T_e}, u) \right) \cdot n_{e,T} \varphi \, d\lambda'. \end{aligned}$$

By inserting the definition of  $u_h$  and setting  $v = \Pi'_h(U'(u_h - u) \varphi)$  in (2.2), we get

$$\begin{aligned} \Theta^{\varepsilon_t, \varepsilon_x}(u_h, u; t, x) &= \\ &\quad - \delta \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A'(u_h) \tilde{A}' \left( u_h, \Pi'_h[U'(u_h - u) \varphi] \right) \, dx' dt' \\ &\quad - \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \left( f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T} \right) \Pi'_h[U'(u_h^T - u) \varphi] \, d\lambda' \end{aligned}$$

$$\begin{aligned}
& - \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T \varepsilon_1(u_h) \mathbb{P}'_h(\nabla' \hat{u}_h \cdot \nabla' \hat{\Pi}'_h[U'(u_h - u)\varphi]) dx' dt' \\
& - \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \varepsilon_2(u_h^T) \mathbb{P}'_h(\nabla'_e \hat{u}_h^T \cdot \nabla'_e \hat{\Pi}'_h[U'(u_h^T - u)\varphi]) d\lambda' \\
& + \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A'(u_h) \left( U'(u_h - u)\varphi - \Pi'_h[U'(u_h - u)\varphi] \right) dx' dt' \\
& - \sum_{n=0}^{N_r-1} \sum_{e \in \partial \mathcal{T}_{h,n}} \int_e \left( \tilde{F}(u_h^T, u) - \tilde{F}(u_h^{T_e}, u) \right) \cdot n_{e,T} \varphi d\lambda'.
\end{aligned}$$

Noting that, by (2.4a),

$$\begin{aligned}
& \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \left( f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T} \right) U'(u_h^T - u) \varphi d\lambda' d\lambda' \\
& = \sum_{n=0}^{N_r-1} \sum_{e \in \mathcal{E}_n} \int_e \left( -f_{e,T}^{LF}(u_h^T, u_h^{T_e})(U'(u_h^T - u) - U'(u_h^{T_e} - u)) \right. \\
& \quad \left. + \tilde{f}(u_h^T) \cdot n_{e,T} U'(u_h^T - u) - \tilde{f}(u_h^{T_e}) \cdot n_{e,T} U'(u_h^{T_e} - u) \right) \varphi d\lambda' \\
& + \sum_{n=0}^{N_r-1} \int_{\mathbb{R}_n^d} (u_h^T - u_h^{T_e}) U'(u_h^T - u) \varphi dx',
\end{aligned}$$

and that, by definition of  $\tilde{F}(u_h, u)$ ,

$$\begin{aligned}
& \sum_{n=0}^{N_r-1} \sum_{e \in \partial \mathcal{T}_{h,n}} \int_e \left( \tilde{F}(u_h^T, u) - \tilde{F}(u_h^{T_e}, u) \right) \cdot n_{e,T} \varphi d\lambda' \\
& = \sum_{n=0}^{N_r-1} \sum_{e \in \mathcal{E}_n} \int_e \left( \tilde{F}(u_h^T, u) - \tilde{F}(u_h^{T_e}, u) \right) \cdot n_{e,T} \varphi d\lambda' \\
& + \sum_{n=0}^{N_r-1} \int_{\mathbb{R}_n^d} (U(u_h^T - u) - U(u_h^{T_e} - u)) \varphi dx',
\end{aligned}$$

we obtain, after a few manipulations and rearrangements,

$$\begin{aligned}
\Theta^{\varepsilon t, \varepsilon x}(u_h, u; t, x) = & \sum_{n=0}^{N_r-1} \sum_{e \in \mathcal{E}_n} \int_e \left( -f_{e,T}^{LF}(u_h^T, u_h^{T_e})(U'(u_h^T - u) - U'(u_h^{T_e} - u)) + \tilde{f}(u_h^T) \cdot n_{e,T} U'(u_h^T - u) \right. \\
& \left. - \tilde{f}(u_h^{T_e}) \cdot n_{e,T} U'(u_h^{T_e} - u) - (\tilde{F}(u_h^T, u) - \tilde{F}(u_h^{T_e}, u)) \cdot n_{e,T} \right) \varphi d\lambda'
\end{aligned}$$

$$\begin{aligned}
& + \sum_{n=0}^{N_r-1} \int_{\mathbb{R}^d} \left( -(u_h^T - u_h^{T_e}) U'(u_h^T - u) + U(u_h^T - u) - U(u_h^{T_e} - u) \right) \varphi dx' \\
& - \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T \varepsilon_1(u_h) \mathbb{P}'_h(\nabla' \hat{u}_h \cdot \nabla' \hat{\Pi}'_h [U'(u_h - u)] \mathbb{P}'_h \varphi) dx' dt' \\
& - \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \varepsilon_2(u_h^T) \mathbb{P}'_h(\nabla'_e \hat{u}_h^T \cdot \nabla'_e \hat{\Pi}'_h [U'(u_h^T - u)] \mathbb{P}'_h \varphi) d\lambda' \\
& - \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T \varepsilon_1(u_h) \mathbb{P}'_h(\nabla' \hat{u}_h \cdot \nabla' \hat{\Pi}'_h [U'(u_h - u)] (\varphi - \mathbb{P}'_h \varphi)) dx' dt' \\
& - \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \varepsilon_2(u_h^T) \mathbb{P}'_h(\nabla'_e \hat{u}_h^T \cdot \nabla'_e \hat{\Pi}'_h [U'(u_h^T - u)] (\varphi - \mathbb{P}'_h \varphi)) d\lambda' \\
& + \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A'(u_h) \left( U'(u_h - u) \varphi - \Pi'_h [U'(u_h - u)] \varphi \right) dx' dt' \\
& - \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \left( f_e^{LF}(u_h^T, u_h^{T_e}) - \bar{f}(u_h^T) \cdot n_e \tau \right) \left( U'(u_h^T - u) \varphi - \Pi'_h [U'(u_h^T - u)] \varphi \right) d\lambda' \\
& - \delta \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A'(u_h) \bar{A}' \left( u_h, \Pi'_h [U'(u_h - u)] \varphi \right) dx' dt' \\
& = \sum_{i=1}^9 \Theta_i^{\varepsilon t, \varepsilon x}(u_h, u; t, x).
\end{aligned}$$

Finally, by definition of  $E^{\varepsilon t, \varepsilon x}(u_h, u; \tau)$ , we can write,

$$E^{\varepsilon t, \varepsilon x}(u_h, u; \tau) = \sum_{i=1}^9 E_i^{\varepsilon t, \varepsilon x}(u_h, u; \tau),$$

where, for  $i = 1, \dots, 9$ ,

$$E_i^{\varepsilon t, \varepsilon x}(u_h, u; \tau) = \int_0^\tau \int_{\mathbb{R}^d} \Theta_i^{\varepsilon t, \varepsilon x}(u_h, u; t, x) dx dt.$$

This is the desired expression of the entropy dissipation form.

**4. Regularity of the approximate solution and auxiliary results.** To be able to estimate the entropy dissipation form, we need (i) *a priori* estimates for the approximate solution  $u_h$ , see Lemma 4.1, which could be considered as regularity results for  $u_h$ , (ii) suitable approximation results, see Lemma 4.4, that allow us to use the *a priori* estimates in the estimation of the entropy dissipation form, and (iii) ‘nonnegativity’ results, see Lemma 4.5, which reflect the nature of the so-called shock-capturing terms used in the definition of the scheme. The *a priori* estimates

are essentially an  $L^2$ -stability result that follows easily from the variational formulation. The approximation result is a standard finite element result in which the regularity of the triangulation, condition (2.1b), is essential, as expected. The ‘nonnegativity’ result holds because our simplexes are supposed to be acute, see condition (2.1a)

**Lemma 4.1** (A priori estimate). *For any  $N_\tau$ ,  $0 \leq N_\tau \leq N$ , we have*

$$\begin{aligned} & \frac{1}{2} \int_{\mathbb{R}_{N_\tau}^d} u_h^{T^2} dx + \frac{1}{2} \sum_{n=0}^{N_\tau-1} \int_{\mathbb{R}_n^d} (u_h^T - u_h^{T_e})^2 dx \\ & + \frac{1}{2} \sum_{n=0}^{N_\tau-1} \sum_{e \in \mathcal{E}_n} \int_e \int_{u_h^{T_e}}^{u_h^T} \left( f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(s) \cdot n_{e,T} \right) ds d\lambda \\ & + \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T \varepsilon_1(u_h) \|\nabla \hat{u}_h\|_{\mathbb{P}_h}^2 dx dt + \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \varepsilon_2(u_h^T) \|\nabla_e \hat{u}_h^T\|_{\mathbb{P}_h}^2 d\lambda \\ & + \delta \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A(u_h)^2 dx dt \leq \frac{1}{2} \|u_0\|_{L^2(\mathbb{R}^d)}^2. \end{aligned}$$

*Proof.* We consider only the non trivially positive terms in (2.2) when  $v$  is chosen as  $u_h$ , namely,

$$\begin{aligned} \Psi^n &= \sum_{T \in \mathcal{T}_{h,n}} \int_T \left( \frac{1}{2} \partial_t u_h^2 + \sum_{i=1}^d f'_i(u_h) u_h \partial_i u_h \right) dx dt \\ &+ \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \left( f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T} \right) u_h^T d\lambda. \end{aligned}$$

By introducing the auxiliary pair entropy-entropy flux  $\tilde{F}_a(u) = (U_a(u), F_a(u))$ , where

$$U_a(u) = \frac{1}{2} u^2 \quad \text{and} \quad F'_{a,i}(u) = f'_i(u) U'_a(u) = f'_i(u) u \quad i = 1, \dots, d,$$

the term  $\Psi^n$  may be expressed as

$$\begin{aligned} \Psi^n &= \sum_{T \in \mathcal{T}_{h,n}} \int_T \nabla \tilde{F}_a(u_h) dx dt + \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \left( f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T} \right) u_h^T d\lambda \\ &= \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e \left( \tilde{F}_a(u_h^T) \cdot n_{e,T} + (f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T}) u_h^T \right) d\lambda. \end{aligned}$$

After reordering, we get

$$\begin{aligned} \Psi^n &= -\frac{1}{2} \int_{\mathbb{R}_n^d} u_h^{T_e^2} dx + \frac{1}{2} \int_{\mathbb{R}_n^d} (u_h^T - u_h^{T_e})^2 dx + \frac{1}{2} \int_{\mathbb{R}_{n+1}^d} u_h^{T^2} dx \\ &+ \sum_{e \in \mathcal{E}_n} \int_e \left( (\tilde{F}_a(u_h^T) - \tilde{F}_a(u_h^{T_e})) \cdot n_{e,T} + f_{e,T}^{LF}(u_h^T, u_h^{T_e}) (u_h^T - u_h^{T_e}) \right. \\ &\quad \left. - (\tilde{f}(u_h^T) u_h^T - \tilde{f}(u_h^{T_e}) u_h^{T_e}) \cdot n_{e,T} \right) d\lambda. \end{aligned}$$

Since

$$\begin{aligned}\tilde{F}_a(u_h^T) - \tilde{F}_a(u_h^{T_e}) &= \int_{u_h^{T_e}}^{u_h^T} \tilde{F}'_a(s) ds = \int_{u_h^{T_e}}^{u_h^T} \tilde{f}'(s) s ds \\ &= - \int_{u_h^{T_e}}^{u_h^T} \tilde{f}(s) ds + \tilde{f}(u_h^T) u_h^T - \tilde{f}(u_h^{T_e}) u_h^{T_e},\end{aligned}$$

we get

$$\begin{aligned}\Psi^n &= -\frac{1}{2} \int_{\mathbb{R}^d} u_h^{T_e}{}^2 dx + \frac{1}{2} \int_{\mathbb{R}^d} (u_h^T - u_h^{T_e})^2 dx + \frac{1}{2} \int_{\mathbb{R}^{d+1}} u_h^{T^2} dx \\ &\quad + \sum_{e \in \mathcal{E}_n} \int_e \int_{u_h^{T_e}}^{u_h^T} \left( f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(s) \cdot n_{e,T} \right) ds d\lambda.\end{aligned}$$

Summing over  $n$  from 0 to  $N_\tau - 1$  completes the proof.  $\square$

For any monotone numerical flux, the terms appearing in the previous lemma are all nonnegative. In the particular case of the Lax-Friedrichs flux, we can be more precise. If the parameter  $C_e^{LF}$  is suitably chosen, the above result also gives an  $L^2$ -estimate of the jump of  $u_h$  across the inner edges  $\mathcal{E}_n$ .

**Corollary 4.2.** *If  $C_e^{LF}$  satisfies condition (2.4b), then*

$$\sum_{n=0}^{N_\tau-1} \sum_{e \in \mathcal{E}_n} \int_e (u_h^T - u_h^{T_e})^2 d\lambda \leq \frac{\|u_0\|_{L^2(\mathbb{R}^d)}^2}{c_\star}.$$

*Proof.* By the definition of the Lax-Friedrichs flux, (2.4a), we have

$$\begin{aligned}\int_e \int_{u_h^{T_e}}^{u_h^T} \left( f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(s) \cdot n_{e,T} \right) ds d\lambda &= \int_e C_e^{LF} (u_h^T - u_h^{T_e})^2 d\lambda \\ &\quad + \int_e \int_{u_h^{T_e}}^{u_h^T} \left( \frac{1}{2} (\tilde{f}(u_h^T) + \tilde{f}(u_h^{T_e})) \cdot n_{e,T} - \tilde{f}(s) \cdot n_{e,T} ds \right) d\lambda \\ &\geq \int_e C_e^{LF} (u_h^T - u_h^{T_e})^2 d\lambda - \int_e \frac{1}{2} |\tilde{f}'|_{e,\infty} (u_h^T - u_h^{T_e})^2 d\lambda \\ &\geq c_\star \int_e (u_h^T - u_h^{T_e})^2 d\lambda,\end{aligned}$$

by the condition (2.4b). The result follows easily from Lemma 4.1.  $\square$

The following result is a simple consequence of the fact that all norms are equivalent in finite dimensional spaces.

**Lemma 4.3.** *There is a constant  $C$  that depends only on  $k$  and  $d$  such that*

$$\begin{aligned}\|\nabla' u_h\|_{L^\infty(T)} &\leq C \|\nabla' \hat{u}_h\|_{\mathbb{P}_k} \quad \text{on } T, \forall T \in \mathcal{T}_{h,n}, n = 0, \dots, N-1, \\ \|\nabla'_e u_h^T\|_{L^\infty(e)} &\leq C \|\nabla'_e \hat{u}_h^T\|_{\mathbb{P}_k} \quad \text{on } e, \forall e \in \partial\mathcal{T}_{h,n}, n = 0, \dots, N-1.\end{aligned}$$

**Lemma 4.4** (Approximation properties of the operator  $\Pi_h$ ). *Let  $s \in L^1((0, T_\infty) \times \mathbb{R}^d)$  be a piecewise continuous function. We have*

$$\begin{aligned}
& \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T s(t', x') \int_0^T \int_{\mathbb{R}^d} \left( U'(u_h - u) \varphi - \Pi'_h[U'(u_h - u) \varphi] \right) dx dt dx' dt' \\
& \leq \frac{C}{\varepsilon} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |s(t', x')| \|\nabla' \hat{u}_h\|_{\mathbb{P}_h} h_T dx' dt' \\
& \quad + C \frac{h}{\varepsilon_x + \varepsilon_t} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |s(t', x')| dx' dt', \\
& \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e s^T \int_0^T \int_{\mathbb{R}^d} \left( U'(u_h^T - u) \varphi - \Pi'_h[U'(u_h^T - u) \varphi] \right) dx dt d\lambda' \\
& \leq \frac{C}{\varepsilon} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e |s^T| \|\nabla_e \hat{u}_h^T\|_{\mathbb{P}_h} h_e d\lambda' \\
& \quad + C \frac{h}{\varepsilon_x + \varepsilon_t} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e |s^T| d\lambda',
\end{aligned}$$

where  $h_e$  is the diameter of  $e$  and where  $C$  depends on  $k, d$ , and  $\sigma$  only.

*Proof.* Since the proofs of these inequalities are almost identical, we prove only the first one; let us denote by  $L$  its left hand side. Let  $\{(t_j, p_j)\}_{j=1}^{N_{d+1,k}}$  be the nodal points associated with the canonical basis  $\{\Psi_j^T\}_{j=1}^{N_{d+1,k}}$  of the space  $\mathcal{P}^k(T)$  where, of course,  $N_{d+1,k} = \binom{d+k+1}{k}$ . With this notation, we can express  $L$  as follows:

$$L = \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T s(t', x') \int_0^T \int_{\mathbb{R}^d} \chi dx dt dx',$$

where  $\chi = \chi(t, x, t', x')$  is defined by

$$\begin{aligned}
\chi &= U'(u_h - u) \varphi - \sum_{j=1}^{N_{d+1,k}} [U'(u_{h,j} - u) \varphi_j] \Psi_j^T \\
&= \sum_{j=1}^{N_{d+1,k}} \left( U'(u_h - u) \varphi - U'(u_{h,j} - u) \varphi_j \right) \Psi_j^T,
\end{aligned}$$

(since  $\sum_{j=1}^{N_{d+1,k}} \Psi_j^T \equiv 1$  on  $T$ ) where  $u_{h,j} = u_h(t_j, p_j)$  and  $\varphi_j = \varphi(t_j, p_j)$ . Moreover, since

$$\begin{aligned}
(U'(u_h - u) \varphi - U'(u_{h,j} - u) \varphi_j) &= (U'(u_h - u) - U'(u_{h,j} - u)) \varphi \\
&\quad - U'(u_{h,j} - u) (\varphi_j - \varphi),
\end{aligned}$$

we obtain, after simple manipulations,

$$\begin{aligned} L &\leq \frac{C}{\varepsilon} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |s(t', x')| \sum_{j=1}^{N_{d+1,k}} |u_h - u_{h,j}| |\Psi_j^T(t', x')| dx' \\ &\quad + C \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |s(t', x')| \sum_{j=1}^{N_{d+1,k}} \int_0^\tau \int_{\mathbb{R}^d} |\varphi - \varphi_j| |\Psi_i^T(t', x')| dt dx dt' dx', \end{aligned}$$

where we have used the fact that  $U' \leq 1$  and  $U'' \leq 1/\varepsilon$  by (3.1), and that  $\int_0^\tau \int_{\mathbb{R}^d} \varphi \leq 1$ . From this inequality, we immediately get

$$\begin{aligned} L &\leq \frac{C}{\varepsilon} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |s(t', x')| \|\nabla' u_h\|_{L^\infty(T)} h_T dt' dx' \\ &\quad + \frac{C h}{\varepsilon_x + \varepsilon_t} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |s(t', x')| dt' dx', \end{aligned}$$

The result follows from Lemma 4.3. This completes the proof.  $\square$

**Lemma 4.5** (Nonnegativity of the shock-capturing terms). *Suppose that the condition (2.1a) on the triangulations is satisfied. Then*

$$\begin{aligned} \nabla' \hat{u}_h \cdot \nabla' \hat{\Pi}'_h [U'(u_h - u)] &\geq 0, \\ \nabla'_e \hat{u}_h^T \cdot \nabla'_e \hat{\Pi}'_h [U'(u_h^T - u)] &\geq 0. \end{aligned}$$

*Proof.* We only prove the first inequality since the proof for the second is similar. By definition, we have that, on each  $(d+1)$ -simplex  $T_\ell$ ,

$$\hat{u}_h(t', x') = \sum_{i=1}^{d+2} u_{h,\ell,i} \Psi_i^{T_\ell}(t', x'),$$

where  $\{\Psi_i^{T_\ell}\}_{i=1}^{d+2}$  is the canonical basis of the space  $\mathcal{P}_1(T_\ell)$ ,  $\{(t_{\ell,i}, p_{\ell,i})\}_{i=1}^{d+2}$  are the vertices of  $T_\ell$ , and  $u_{h,\ell,i} = u_h(t_{\ell,i}, p_{\ell,i})$ .

Thus, for  $(t', x') \in T_\ell$ ,

$$\begin{aligned} \theta &= \nabla' \hat{u}_h \cdot \nabla' (\hat{\Pi}'_h [U'(u_h - u)]) \\ &= \sum_{i,j=1}^{d+2} u_{h,\ell,i} U'(u_{h,\ell,j} - u) \Lambda_{i,j}, \end{aligned}$$

where  $\Lambda_{i,j} = \nabla' \Psi_i^{T_\ell}(t', x') \cdot \nabla' \Psi_j^{T_\ell}(t', x')$ . Since  $\sum_{i=1}^{d+2} \Psi_i^{T_\ell}(t', x') \equiv 1$  on  $T_\ell$ , we have

$$\theta = \sum_{i,j=1}^{d+2} (-u_{h,\ell,j} + u_{h,\ell,i}) U'(u_{h,\ell,j} - u) \Lambda_{i,j}.$$

Interchanging  $i$  and  $j$  in the previous relation and averaging the two expressions for  $\theta$ , we get

$$\theta = \frac{1}{2} \sum_{i,j=1}^{d+2} (-u_{h,\ell,j} + u_{h,\ell,i}) (-U'(u_{h,\ell,j} - u) + U'(u_{h,\ell,i} - u)) (-\Lambda_{i,j}).$$

Since by (2.1a) the  $(d+1)$ -simplex  $T_\ell$  is acute, we have  $-\Lambda_{i,j} \geq 0$  on  $T_\ell$ . Hence by convexity of  $U$ ,  $\theta \geq 0$  on  $T_\ell$ . This completes the proof.  $\square$

**5. Estimating the entropy dissipation form.** In this section, we estimate each of the terms  $E_i^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau)$ .

**Lemma 5.1.** *Suppose that  $C_e^{LF}$  satisfies the condition (2.4b). Then we have*

$$E_1^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq 0.$$

*Proof.* We have

$$\begin{aligned} \tilde{F}(u_h^T, u) - \tilde{F}(u_h^{T_e}, u) &= \int_{u_h^{T_e}}^{u_h^T} \frac{d}{ds} \tilde{F}(s, u) ds = \int_{u_h^{T_e}}^{u_h^T} \tilde{f}'(s) U'(s - u) ds \\ &= - \int_{u_h^{T_e}}^{u_h^T} \tilde{f}'(s) U''(s - u) ds + \tilde{f}(u_h^T) U'(u_h^T - u) - \tilde{f}(u_h^{T_e}) U'(u_h^{T_e} - u), \end{aligned}$$

and thus

$$\begin{aligned} E_1^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) &= \int_0^\tau \int_{\mathbb{R}^d} \sum_{n=0}^{N_r-1} \sum_{e \in \mathcal{E}_n} \int_e \left( -f_{e,T}^{LF}(u_h^T, u_h^{T_e}) (U'(u_h^T - u) - U'(u_h^{T_e} - u)) \right. \\ &\quad \left. + \int_{u_h^{T_e}}^{u_h^T} \tilde{f}'(s) U''(s - u) ds \right) dx dt d\lambda' \\ &= \int_0^\tau \int_{\mathbb{R}^d} \sum_{n=0}^{N_r-1} \sum_{e \in \mathcal{E}_n} \int_e \int_{u_h^{T_e}}^{u_h^T} \left( \tilde{f}'(s) \cdot n_{e,T} - f_{e,T}^{LF}(u_h^T, u_h^{T_e}) \right) U''(s - u) dx dt ds d\lambda'. \end{aligned}$$

Since  $U$  is convex, and the numerical flux is monotone, by (2.4b), the above quantity is nonnegative. This proves the lemma.  $\square$

**Lemma 5.2.** *We have*

$$E_2^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq 0.$$

*Proof.* The result immediately follows from the nonnegativity of the function  $\varphi$  and the convexity of the entropy  $U$ .  $\square$

**Lemma 5.3.** *Suppose that the condition (2.1a) on the triangulations is satisfied. Then we have*

$$E_3^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq 0.$$

*Proof.* The result directly follows from Lemma 4.5 and the fact that  $\mathbb{P}'_h \varphi$  is a nonnegative piecewise constant function.  $\square$

**Lemma 5.4.** *Suppose that the condition (2.1a) on the triangulations is satisfied. Then we have*

$$E_4^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq 0.$$

The proof of this result is similar to that of the preceding lemma.

**Lemma 5.5.** *Suppose that the condition (2.1b) on the triangulations is satisfied. Then we have*

$$E_5^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq C \frac{\delta_1}{(\varepsilon_x + \varepsilon_t) \delta_1^{1/2}},$$

where the constant  $C$  depends on  $k, d, \sigma$ , and  $\|u_0\|_{L^2(\mathbb{R}^d)}$  only.

*Proof.* We have, by definition,

$$\begin{aligned} E_5^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) &= - \int_0^\tau \int_{\mathbb{R}^d} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T \varepsilon_1(u_h) \mathbb{P}'_h(\nabla' \hat{u}_h \cdot \nabla' \hat{\Pi}'_h[U'(u_h - u)(\varphi - \mathbb{P}'_h \varphi)]) dt' dx' dt dx \\ &\leq \int_0^\tau \int_{\mathbb{R}^d} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T \varepsilon_1(u_h) \|\nabla' \hat{u}_h\|_{\mathbb{P}_h} \|\Gamma\|_{L^\infty(T)} dt' dx' dt dx, \end{aligned}$$

where  $\Gamma = \nabla' \hat{\Pi}'_h[U'(u_h - u)(\varphi - \mathbb{P}'_h \varphi)]$ . Since, on each  $(d+1)$ -simplex  $T_\ell$ ,

$$\begin{aligned} \Gamma &= \nabla'(\hat{\Pi}'_h[U'(u_h - u)(\varphi - \mathbb{P}'_h \varphi)]) \\ &= \sum_{i=1}^{d+2} U'(u_{h,\ell,i} - u)(\varphi_{\ell,i} - \mathbb{P}'_h \varphi) \nabla' \Psi_i^{T_\ell}(t', x'), \end{aligned}$$

and since  $|\nabla' \Psi_i^{T_\ell}| \leq c_0/\rho_T$  on  $T$  and  $|U'| \leq 1$ , by (3.1), we have

$$|\Gamma| \leq \frac{c_0}{\rho_T} \sum_{i=1}^{d+2} |\varphi_{\ell,i} - \mathbb{P}'_h \varphi|,$$

which yields by (2.1b)

$$\int_0^\tau \int_{\mathbb{R}^d} |\Gamma| \leq c_0 \frac{h_T}{\rho_T} \frac{1}{\varepsilon_x + \varepsilon_t} \leq c_0 \frac{\sigma}{\varepsilon_x + \varepsilon_t}.$$

Finally, using the definition of  $\varepsilon_1$ , we get

$$\begin{aligned} E_5^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) &\leq \frac{c_0 \sigma}{\varepsilon_x + \varepsilon_t} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T \varepsilon_1(u_h) \|\nabla' \hat{u}_h\|_{\mathbb{P}_h} dx' dt' \\ &= \frac{c_0 \sigma}{\varepsilon_x + \varepsilon_t} \delta_1 \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |A'(u_h)| dx' dt'. \end{aligned}$$

The result follows easily from the *a priori* estimate of Lemma 4.1. This completes the proof.  $\square$

**Lemma 5.6.** *Suppose that the conditions (2.1b), (2.1c) on the triangulations and (2.4b) on the coefficients  $C_e^{LF}$  are satisfied. Then, we have*

$$E_6^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq C \frac{\delta_2}{(\varepsilon_x + \varepsilon_t)h^{1/2}},$$

where the constant  $C$  depends on  $k, d, \sigma, \bar{c}, c_*$ , and  $\|u_0\|_{L^2(\mathbb{R}^d)}$  only.

*Proof.* Proceeding as in the preceding lemma, we obtain

$$\begin{aligned} E_6^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) &\leq \frac{C}{\varepsilon_x + \varepsilon_t} \delta_2 \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_{\partial T} |f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T}| d\lambda' \\ &\leq \frac{C}{\varepsilon_x + \varepsilon_t} \delta_2 \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e |C_e^{LF}(u_h^T - u_h^{T_e}) - \frac{1}{2}(\tilde{f}(u_h^T) - \tilde{f}(u_h^{T_e})) \cdot n_{e,T}| d\lambda'. \end{aligned}$$

By (2.4b), we have

$$E_6^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq \frac{C}{\varepsilon_x + \varepsilon_t} \delta_2 c_* \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e |u_h^T - u_h^{T_e}| d\lambda'.$$

The result then follows from the Cauchy-Schwarz inequality, Corollary 4.2, and condition (2.1c).  $\square$

**Lemma 5.7.** *We have*

$$E_7^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq C \left( \frac{h}{\varepsilon \delta_1} + \frac{h}{(\varepsilon_x + \varepsilon_t) \delta_1^{1/2}} \right),$$

where  $C$  depends on  $k, d$ , and  $\|u_0\|_{L^2(\mathbb{R}^d)}$  only.

*Proof.* A simple application of Lemma 4.4 gives us

$$\begin{aligned} E_7^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) &\leq C \frac{h}{\varepsilon} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |A'(u_h)| \|\nabla' \hat{u}_h\|_{\mathbb{P}_h} dx' dt' \\ &\quad + \frac{Ch}{\varepsilon_x + \varepsilon_t} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |A'(u_h)| dx' dt'. \end{aligned}$$

The proof then follows from the Cauchy-Schwarz inequality and the *a priori* estimates of Lemma 4.1.  $\square$

**Lemma 5.8.** *Suppose that the condition (2.4b) on the coefficients  $C_e^{LF}$  and the condition (2.1c) on the triangulations are satisfied. Then we have*

$$E_8^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq C \left( \frac{h}{\varepsilon \delta_2} + \frac{h^{1/2}}{\varepsilon_x} \right),$$

where  $C$  depends on  $k, d, c^*, \bar{c}$  and  $\|u_0\|_{L^2(\mathbb{R}^d)}$  only.

*Proof.* The proof is similar to the proof of the previous result. After a straightforward application of Lemma 4.4, we get

$$\begin{aligned} E_8^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) &\leq C \frac{h}{\varepsilon} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e |f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T}| \|\nabla_e \hat{u}_h^T\|_{\mathbb{P}_h} d\lambda' \\ &\quad + C \frac{h}{\varepsilon_x + \varepsilon_t} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \sum_{e \in \partial T} \int_e |f_{e,T}^{LF}(u_h^T, u_h^{T_e}) - \tilde{f}(u_h^T) \cdot n_{e,T}| d\lambda'. \end{aligned}$$

The first term is estimated using directly the definition of  $\varepsilon_2$  and the *a priori* estimates of Lemma 4.1. The second term has already been studied in Lemma 5.6.

□

**Lemma 5.9.** *Assume that the condition (2.1b) on the triangulations is satisfied. Then we have*

$$E_9^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) \leq C \left( \frac{\delta}{\varepsilon \delta_1} + \frac{\delta^{1/2}}{(\varepsilon_x + \varepsilon_t)} \right),$$

where  $C$  depends on  $d, k, \sigma$ , and  $\|u_0\|_{\mathbb{R}^d}$  only.

*Proof.* By definition, we have

$$\begin{aligned} E_9^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) &= -\delta \int_0^\tau \int_{\mathbb{R}^d} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T A'(u_h) \tilde{A}' \left( u_h, \Pi'_h[U'(u_h - u) \varphi] \right) dx' dt' dt dx \\ &\leq \delta \int_0^\tau \int_{\mathbb{R}^d} \sum_{n=0}^{N_r-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |A'(u_h)| |\tilde{A}' \left( u_h, \Pi'_h[U'(u_h - u) \varphi] \right)| dx' dt' dt dx. \end{aligned}$$

Taking into account the linearity of  $\tilde{A}'(u_h, \cdot)$  and the definition of  $\Pi'_h$ , we get

$$\begin{aligned} \Gamma &= \tilde{A}'(u_h, \Pi'_h[U'(u_h - u) \varphi]) \\ &= \sum_{i=1}^{N_{d+1,k}} U'(u_{h,i} - u) \varphi_i \tilde{A}'(u_h, \Psi_i^T(t', x')) \\ &= \sum_{i=1}^{N_{d+1,k}} (U'(u_{h,i} - u) \varphi_i - U'(u_h - u) \varphi) \tilde{A}'(u_h, \Psi_i^T(t', x')) \end{aligned}$$

since  $\sum_{i=1}^{N_{d+1,k}} \Psi_i^T(t', x') \equiv 1$  on  $T$ . Moreover, since  $|\tilde{A}'(u_h, \Psi_i^T(t', x'))| \leq C/\rho_T$  on  $T$ , we obtain

$$\begin{aligned} |\Gamma| &\leq \frac{C}{\rho_T} \sum_{i=1}^{N_{d+1,k}} |U'(u_{h,i} - u) \varphi_i - U'(u_h - u) \varphi| \\ &\leq \frac{C}{\rho_T} \sum_{i=1}^{N_{d+1,k}} |U'(u_{h,i} - u) - U'(u_h - u)| \varphi + \frac{C}{\rho_T} \sum_{i=1}^{N_{d+1,k}} |\varphi_i - \varphi|, \end{aligned}$$

where we have used the fact that  $|U'| \leq 1$  by (3.1). Thus,

$$\int_0^\tau \int_{\mathbb{R}^d} |\Gamma| \leq C \frac{h_T}{\rho_T} \left( \frac{1}{\varepsilon} \|\nabla' \hat{u}_h\|_{\mathbb{P}_h} + \frac{1}{\varepsilon_x + \varepsilon_t} \right) \leq C \sigma \left( \frac{1}{\varepsilon} \|\nabla' \hat{u}_h\|_{\mathbb{P}_h} + \frac{1}{\varepsilon_x + \varepsilon_t} \right),$$

by condition (2.1b). Now, we can write

$$\begin{aligned} E_9^{\varepsilon_x, \varepsilon_t}(u_h, u; \tau) &\leq C \frac{\delta}{\varepsilon} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |A(u_h)| \|\nabla' \hat{u}_h\|_{\mathbb{P}_h} dx' dt' \\ &\quad + C \frac{\delta}{\varepsilon_x + \varepsilon_t} \sum_{n=0}^{N_\tau-1} \sum_{T \in \mathcal{T}_{h,n}} \int_T |A(u_h)| dx' dt'. \end{aligned}$$

The result follows by using the *a priori* estimates of Lemma 4.1.  $\square$

**6. Proof of Theorem 2.1.** We are now ready to prove our main result. Inserting into Lemma 3.1 all the estimates of the lemmas obtained in §5, we obtain

$$\begin{aligned} \int_{\mathbb{R}^d} U(u_h(\tau, x) - u(\tau, x)) dx &\leq \sqrt{e} \int_{\mathbb{R}^d} U(u_{0h}(x) - u_0(x)) dx \\ &\quad + C \left( \varepsilon + \frac{1}{\varepsilon} \left( \frac{h}{\delta_1} + \frac{h}{\delta_2} + \frac{\delta}{\delta_1} \right) \right) \\ &\quad + C \left( \varepsilon_x + \varepsilon_t + \frac{1}{\varepsilon_x + \varepsilon_t} \left( \frac{\delta_1}{\delta_1^{1/2}} + \frac{\delta_2}{h^{1/2}} + \frac{h}{\delta_1^{1/2}} + h^{1/2} + \delta^{1/2} \right) \right). \end{aligned}$$

From this inequality, it is clear that we must take  $\delta = h$  and  $\delta_1 = \delta_2 = \delta^*$ .

Now, consider the function  $B(w) = |w| - U(w)$ . By definition (3.1) of  $G$ ,  $B(w) \geq 0$  and

$$B(w) = \varepsilon (|w/\varepsilon| - G(w/\varepsilon)) \leq \varepsilon \sup_{v \in \mathbb{R}} ||v| - G(v)| \leq \varepsilon \sup_{|v| \leq 1} ||v| - G(v)| = c_0 \varepsilon.$$

This implies that  $|w| - c_0 \varepsilon \leq U(w) \leq |w|$ , and so

$$\begin{aligned} \|u_h(\tau, \cdot) - u(\tau, \cdot)\|_{L^1(\mathbb{R}^d)} &\leq \sqrt{e} \|u_{0h} - u_0\|_{L^1(\mathbb{R}^d)} + C \left( \varepsilon + \frac{1}{\varepsilon} \frac{h}{\delta^*} \right) \\ &\quad + C \left( \varepsilon_x + \varepsilon_t + \frac{1}{\varepsilon_x + \varepsilon_t} \left( \frac{\delta^*}{h^{1/2}} + h^{1/2} \right) \right). \end{aligned}$$

Minimizing over  $\varepsilon$  and over  $\varepsilon_x + \varepsilon_t$ , we obtain

$$\|u_h(\tau, \cdot) - u(\tau, \cdot)\|_{L^1(\mathbb{R}^d)} \leq \sqrt{e} \|u_{0h} - u_0\|_{L^1(\mathbb{R}^d)} + C \left( \frac{h^{1/2}}{(\delta^*)^{1/2}} + \frac{(\delta^*)^{1/2}}{h^{1/4}} + h^{1/4} \right).$$

The result of Theorem 2.1 is obtained by minimizing over  $\delta^*$ .

**Acknowledgments.** The authors would like to thank Claes Johnson for bringing to their attention the SCDG method and for fruitful discussions.

## REFERENCES

1. B. Cockburn, F. Coquel & P. LeFloch, *An error estimate for high-order accurate finite volume methods for scalar conservation laws*, Math. Comp. (to appear).
2. R.J. DiPerna, *Measure-valued solutions to conservations laws*, Arch. Rat. Mech. Anal. **88** (1985), 223-270.
3. T.J.R. Hughes & M. Mallet, *A new finite element formulation for computational fluid dynamics : IV. A discontinuity-capturing operator for multidimensional advective-diffusive systems*, Comput. Methods Appl. Mech. Engrg. **58** (1986), 329-336.
4. J. Jaffré, C. Johnson & A. Szepessy, *Convergence of the discontinuous Galerkin finite element method for hyperbolic conservation laws*, Preprint 1993-11, Dept. of Mathematics, Chalmers University of Technology (1993).
5. C. Johnson, *Streamline Diffusion finite element methods for Fluid Flow*, in preparation, 1991.
6. C. Johnson, A. Szepessy & P. Hansbo, *On the convergence of shock-capturing streamline diffusion finite element methods for hyperbolic conservation laws*, Math. Comp. **54** (1990), 107-129.
7. S.N. Kruskov, *First order quasilinear equations in several independent variables*, Math. USSR Sbornik **10** (1970), 217-243.
8. N.N. Kuznetsov, *Accuracy of some approximate methods for computing the weak solutions of a first-order quasi-linear equation*, USSR Comp. Math. and Math. Phys. **16** (1976), 105-119.
9. A. Szepessy, *Convergence of a shock-capturing streamline diffusion finite element method for scalar conservation laws in two space dimensions*, Math. Comp. **53** (1989), 527-545.
10. ———, *Convergence of a streamline diffusion finite element method for a conservation law with boundary conditions*, RAIRO Model. Math. Anal. Numer. **25** (1991), 749-783.
11. ———, *An existence result for scalar conservation laws using measure-valued solution*, Comm. in Partial Diff. Eq. **14** (1989), 1329-1350.

#	Author/s	Title
1063	Eduardo Casas & Jiongmin Yong	Maximum principle for state-constrained optimal control problems governed by quasilinear elliptic equations
1064	Suzanne M. Lenhart & Jiongmin Yong	Optimal control for degenerate parabolic equations with logistic growth
1065	Suzanne Lenhart	Optimal control of a convective-diffusive fluid problem
1066	Enrique Zuazua	Weakly nonlinear large time behavior in scalar convection-diffusion equations
1067	Caroline Fabre, Jean-Pierre Puel & Enrike Zuazua	Approximate controllability of the semilinear heat equation
1068	M. Escobedo, J.L. Vazquez & Enrike Zuazua	Entropy solutions for diffusion-convection equations with partial diffusivity
1069	M. Escobedo, J.L. Vazquez & Enrike Zuazua	A diffusion-convection equation in several space dimensions
1070	F. Fagnani & J.C. Willems	Symmetries of differential systems
1071	Zhangxin Chen, Bernardo Cockburn, Joseph W. Jerome & Chi-Wang Shu	Mixed-RKDG finite element methods for the 2-D hydrodynamic model for semiconductor device simulation
1072	M.E. Bradley & Suzanne Lenhart	Bilinear optimal control of a Kirchhoff plate
1073	Héctor J. Sussmann	A cornucopia of abnormal subriemannian minimizers. Part I: The four-dimensional case
1074	Marek Rakowski	Transfer function approach to disturbance decoupling problem
1075	Yuncheng You	Optimal control of Ginzburg-Landau equation for superconductivity
1076	Yuncheng You	Global dynamics of dissipative modified Korteweg-de Vries equations
1077	Mario Taboada & Yuncheng You	Nonuniformly attracting inertial manifolds and stabilization of beam equations with structural and Balakrishnan-Taylor damping
1078	Michael Böhm & Mario Taboada	Global existence and regularity of solutions of the nonlinear string equation
1079	Zhangxin Chen	BDM mixed methods for a nonlinear elliptic problem
1080	J.J.L. Velázquez	On the dynamics of a closed thermosyphon
1081	Frédéric Bonnans & Eduardo Casas	Some stability concepts and their applications in optimal control problems
1082	Hong-Ming Yin	$\mathcal{L}^{2,\mu}(Q)$ -estimates for parabolic equations and applications
1083	David L. Russell & Bing-Yu Zhang	Smoothing and decay properties of solutions of the Korteweg-de Vries equation on a periodic domain with point dissipation
1084	J.E. Dunn & K.R. Rajagopal	Fluids of differential type: Critical review and thermodynamic analysis
1085	Mary Elizabeth Bradley & Mary Ann Horn	Global stabilization of the von Kármán plate with boundary feedback acting via bending moments only
1086	Mary Ann Horn & Irena Lasiecka	Global stabilization of a dynamic von Kármán plate with nonlinear boundary feedback
1087	Vilmos Komornik	Decay estimates for a petrovski system with a nonlinear distributed feedback
1088	Jesse L. Barlow	Perturbation results for nearly uncoupled Markov chains with applications to iterative methods
1089	Jong-Shenq Guo	Large time behavior of solutions of a fast diffusion equation with source
1090	Tongwen Chen & Li Qiu	$\mathcal{H}_\infty$ design of general multirate sampled-data control systems
1091	Satyanad Kichenassamy & Walter Littman	Blow-up surfaces for nonlinear wave equations, I
1092	Nahum Shimkin	Asymptotically efficient adaptive strategies in repeated games, Part I: certainty equivalence strategies
1093	Caroline Fabre, Jean-Pierre Puel & Enrique Zuazua	On the density of the range of the semigroup for semilinear heat equations
1094	Robert F. Stengel, Laura R. Ray & Christopher I. Marrison	Probabilistic evaluation of control system robustness
1095	H.O. Fattorini & S.S. Sritharan	Optimal chattering controls for viscous flow
1096	Kathryn E. Lenz	Properties of certain optimal weighted sensitivity and weighted mixed sensitivity designs
1097	Gang Bao & David C. Dobson	Second harmonic generation in nonlinear optical films
1098	Avner Friedman & Chaocheng Huang	Diffusion in network
1099	Xinfu Chen, Avner Friedman & Tsuyoshi Kimura	Nonstationary filtration in partially saturated porous media
1100	Walter Littman & Baisheng Yan	Rellich type decay theorems for equations $P(D)u = f$ with $f$ having support in a cylinder
1101	Satyanad Kichenassamy & Walter Littman	Blow-up surfaces for nonlinear wave equations, II
1102	Nahum Shimkin	Extremal large deviations in controlled I.I.D. processes with applications to hypothesis testing
1103	A. Narain	Interfacial shear modeling and flow predictions for internal flows of pure vapor experiencing film condensation
1104	Andrew Teel & Laurent Praly	Global stabilizability and observability imply semi-global stabilizability by output feedback
1105	Karen Rudie & Jan C. Willems	The computational complexity of decentralized discrete-event control problems

- 1106 **John A. Burns & Ruben D. Spies**, A numerical study of parameter sensitivities in Landau-Ginzburg models of phase transitions in shape memory alloys
- 1107 **Gang Bao & William W. Symes**, Time like trace regularity of the wave equation with a nonsmooth principal part
- 1108 **Lawrence Markus**, A brief history of control
- 1109 **Richard A. Brualdi, Keith L. Chavey & Bryan L. Shader**, Bipartite graphs and inverse sign patterns of strong sign-nonsingular matrices
- 1110 **A. Kersch, W. Morokoff & A. Schuster**, Radiative heat transfer with quasi-monte carlo methods
- 1111 **Jianhua Zhang**, A free boundary problem arising from swelling-controlled release processes
- 1112 **Walter Littman & Stephen Taylor**, Local smoothing and energy decay for a semi-infinite beam pinned at several points and applications to boundary control
- 1113 **Srdjan Stojanovic & Thomas Svobodny**, A free boundary problem for the Stokes equation via nonsmooth analysis
- 1114 **Bronislaw Jakubczyk**, Filtered differential algebras are complete invariants of static feedback
- 1115 **Boris Mordukhovich**, Discrete approximations and refined Euler-Lagrange conditions for nonconvex differential inclusions
- 1116 **Bei Hu & Hong-Ming Yin**, The profile near blowup time for solution of the heat equation with a nonlinear boundary condition
- 1117 **Jin Ma & Jiongmin Yong**, Solvability of forward-backward SDEs and the nodal set of Hamilton-Jacobi-Bellman Equations
- 1118 **Chaocheng Huang & Jiongmin Yong**, Coupled parabolic and hyperbolic equations modeling age-dependent epidemic dynamics with nonlinear diffusion
- 1119 **Jiongmin Yong**, Necessary conditions for minimax control problems of second order elliptic partial differential equations
- 1120 **Eitan Altman & Nahum Shimkin**, Worst-case and Nash routing policies in parallel queues with uncertain service allocations
- 1121 **Nahum Shimkin & Adam Shwartz**, Asymptotically efficient adaptive strategies in repeated games, part II: Asymptotic optimality
- 1122 **M.E. Bradley**, Well-posedness and regularity results for a dynamic Von Kármán plate
- 1123 **Zhangxin Chen**, Finite element analysis of the 1D full drift diffusion semiconductor model
- 1124 **Gang Bao & David C. Dobson**, Diffractive optics in nonlinear media with periodic structure
- 1125 **Steven Cox & Enrique Zuazua**, The rate at which energy decays in a damped string
- 1126 **Anthony W. Leung**, Optimal control for nonlinear systems of partial differential equations related to ecology
- 1127 **H.J. Sussmann**, A continuation method for nonholonomic path-finding problems
- 1128 **Yung-Jen Guo & Walter Littman**, The null boundary controllability for semilinear heat equations
- 1129 **Q. Zhang & G. Yin**, Turnpike sets in stochastic manufacturing systems with finite time horizon
- 1130 **I. Györi, F. Hartung & J. Turi**, Approximation of functional differential equations with time- and state-dependent delays by equations with piecewise constant arguments
- 1131 **I. Györi, F. Hartung & J. Turi**, Stability in delay equations with perturbed time lags
- 1132 **F. Hartung & J. Turi**, On the asymptotic behavior of the solutions of a state-dependent delay equation
- 1133 **Pierre-Alain Gremaud**, Numerical optimization and quasiconvexity
- 1134 **Jie Tai Yu**, Resultants and inversion formula for  $N$  polynomials in  $N$  variables
- 1135 **Avner Friedman & J.L. Velázquez**, The analysis of coating flows in a strip
- 1136 **Eduardo D. Sontag**, Control of systems without drift via generic loops
- 1137 **Yuan Wang & Eduardo D. Sontag**, Orders of input/output differential equations and state space dimensions
- 1138 **Scott W. Hansen**, Boundary control of a one-dimensional, linear, thermoelastic rod
- 1139 **Robert Lipton & Bogdan Vernescu**, Homogenization of two phase emulsions with surface tension effects
- 1140 **Scott Hansen & Enrique Zuazua**, Exact controllability and stabilization of a vibrating string with an interior point mass
- 1141 **Bei Hu & Jiongmin Yong**, Pontryagin Maximum principle for semilinear and quasilinear parabolic equations with pointwise state constraints
- 1142 **Mark H.A. Davis**, A deterministic approach to optimal stopping with application to a prophet inequality
- 1143 **M.H.A. Davis & M. Zervos**, A problem of singular stochastic control with discretionary stopping
- 1144 **Bernardo Cockburn & Pierre-Alain Gremaud**, An error estimate for finite element methods for scalar conservation laws
- 1145 **David C. Dobson & Fadil Santosa**, An image enhancement technique for electrical impedance tomography
- 1146 **Jin Ma, Philip Protter, & Jiongmin Yong**, Solving forward-backward stochastic differential equations explicitly — a four step scheme
- 1147 **Yong Liu**, The equilibrium plasma subject to skin effect
- 1148 **Ulrich Hornung**, Models for flow and transport through porous media derived by homogenization
- 1149 **Avner Friedman, Chaocheng Huang, & Jiongmin Yong**, Effective permeability of the boundary of a domain
- 1150 **Gang Bao**, A uniqueness theorem for an inverse problem in periodic diffractive optics
- 1151 **Angelo Favini, Mary Ann Horn, & Irena Lasiecka**, Global existence and uniqueness of regular solutions to the dynamic von Kármán system with nonlinear boundary dissipation