

CONDITIONAL SIGN-SOLVABILITY

By

Richard A. Brualdi

Keith L. Chavey

and

Bryan L. Shader

IMA Preprint Series # 940

April 1992

Conditional Sign-Solvability

Richard A. Brualdi*
Department of Mathematics
University of Wisconsin
Madison, WI 53706

Keith L. Chavey
Department of Mathematics/Computer Systems
University of Wisconsin
River Falls, WI 54022

Bryan L. Shader†
Department of Mathematics
University of Wyoming
Laramie, WY 82071

March 24, 1992

Abstract

Sign-solvable linear systems were introduced by economists in modelling economic systems where only qualitative information is known. We introduce the idea of a conditionally sign-solvable linear system $Ax = b$ by relaxing the definition of sign-solvability so as not to require that each linear system with the same sign pattern as $Ax = b$

*Research partially supported by NSF Grant DMS-8901445 and NSA Grant MDA904-89-H-2060. This paper was written while the author was a member of the Institute for Mathematics and its Applications (IMA), University of Minnesota. I thank the IMA for its support.

†This paper was written while the author was a Postdoctoral Fellow at the IMA.

has a solution. Conditional sign-solvability is more widely applicable than sign-solvability. We show that the study of conditional sign-solvability reduces to the study of L -matrices and matrices that we call conditionally S^* -matrices. Some basic properties of conditionally S^* -matrices are obtained.

1 Introduction

The *sign* of a real number a is defined by

$$\text{sign } a = \begin{cases} 0 & \text{if } a = 0 \\ +1 & \text{if } a > 0 \\ -1 & \text{if } a < 0 \end{cases}$$

The *sign pattern* of an m by n matrix $A = [a_{ij}]$ is the m by n matrix $\text{sign } A = [\text{sign } a_{ij}]$ obtained from A by replacing each entry by its sign.

Consider a linear system of equations $Ax = b$ where

$$\text{sign } A = \begin{bmatrix} -1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \\ 1 & 1 & 1 \end{bmatrix} \text{ and } \text{sign } b = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}. \quad (1)$$

This linear system may or may not have a solution depending on the magnitudes of the entries of A and b . Suppose $Ax = b$ has a solution $u = (u_1, u_2, u_3)^T$. In order that the first three equations are satisfied, u_1, u_2 , and u_3 must have the same sign. In order that the last equation is also satisfied,

$$\text{sign } u = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

Thus if $Ax = b$ has a solution, we have determined its sign pattern knowing only the sign patterns of A and b .

The *qualitative class* of a matrix B is the set $\mathcal{Q}(B)$ of all matrices with the same sign pattern as B . We define a linear system of equations $Ax = b$ to be *conditionally sign-solvable* provided

$$\{\tilde{u} : \text{there exists } \tilde{A} \in \mathcal{Q}(A) \text{ and } \tilde{b} \in \mathcal{Q}(b) \text{ with } \tilde{A}\tilde{u} = \tilde{b}\} \quad (2)$$

is a nonempty set which is contained in a single qualitative class $\mathcal{Q}(u)$. If $Ax = b$ is conditionally sign-solvable, then (2) is the *qualitative solution class*

of $Ax = b$ and is denoted by $\mathcal{Q}(Ax = b)$. It follows easily that $\mathcal{Q}(Ax = b)$ is the entire qualitative class $\mathcal{Q}(u)$.

The linear system $Ax = b$ is *sign-solvable* provided it is conditionally sign-solvable and $\tilde{A}x = \tilde{b}$ is solvable for each \tilde{A} in $\mathcal{Q}(A)$ and each \tilde{b} in $\mathcal{Q}(b)$. A linear system $Ax = b$ satisfying (1) is conditionally sign-solvable where $\mathcal{Q}(Ax = b) = \mathcal{Q}((1, 1, 1)^T)$, but it is not sign-solvable.

The study of sign-solvable linear systems was begun by economists [S 47], [L 63], [G 64] and is further studied in [BMQ 68], [KL 81], [KLM 83], and [M 82]. The original motivation was to be able to predict the sign pattern of the solution of a linear system of equations arising from a model of an economic system when only qualitative information is known about its coefficients. Since the linear system arises from a model of a known economic system, it is presumed to have a solution. Hence it seems to us sign-solvability is unnecessarily restrictive, and that a conditional sign-solvable system is a more accurate description of a linear system for which the sign pattern of the solution can be predicted from qualitative information.

Fundamental to the study of sign-solvable linear systems are the classes of L -matrices and of S -matrices. We show that the study of conditionally sign-solvable linear systems reduces to the study of L -matrices and matrices that we call conditionally S^* -matrices. We investigate some of the basic properties of this new class of matrices.

2 Characterization of Conditional Sign-Solvability

Let A be an m by n matrix. Then A is an L -matrix provided that each matrix in $\mathcal{Q}(A)$ has linearly independent rows. We say that the matrix A is a *nearly L -matrix* provided that A is not an L -matrix but each of the $m - 1$ by n matrices obtained from A by deleting a row is an L -matrix. The matrix A is a *conditionally S^* -matrix*, abbreviated a CS^* -matrix provided that

- (i) A has no row of all zeros,
- (ii) A^T is a nearly L -matrix, and
- (iii) $\{\tilde{u} \neq 0 : \text{there exists } \tilde{A} \in \mathcal{Q}(A) \text{ with } \tilde{A}\tilde{u} = 0\} \subseteq \mathcal{Q}(u) \cup \mathcal{Q}(-u)$ for some m by 1 column vector u .

If A is a CS^* -matrix, then by (ii) the vector u in (iii) has no zero entries. If each entry of u is positive, then A is a *conditionally S -matrix*, abbreviated

CS-matrix. Thus a matrix A with no zero rows is a CS-matrix if and only if A^T is not an L -matrix and for each \tilde{A} in $\mathcal{Q}(A)$ the right nullspace of \tilde{A} is either trivial or is spanned by a vector with only positive entries. If w is a column vector with no zero entries, then the matrix $[w \ -w]$ with two columns is a CS-matrix.

An S -matrix, respectively S^* -matrix, is a CS-matrix, respectively, CS^* -matrix, with the property that every matrix in its qualitative class has a nontrivial right nullspace. Clearly, if A is an m by n CS-matrix, then $n \leq m + 1$, and if $n = m + 1$, then A is an S -matrix. It is not difficult to show that an S -matrix with m rows has exactly $m + 1$ columns [KL 81], [KLM 83]. The matrix

$$\left[\begin{array}{c|c} -1 & \\ -1 & \\ \vdots & \\ -1 & \end{array} \middle| I_m \right]$$

is an S -matrix for each positive integer m .

It follows from our introductory example that

$$A = \begin{bmatrix} -1 & 1 & 1 & 0 \\ 1 & -1 & 1 & 0 \\ 1 & 1 & -1 & 0 \\ 1 & 1 & 1 & -1 \end{bmatrix} \quad (3)$$

is a CS-matrix. A matrix obtained from a CS-matrix by repeating rows is a CS-matrix.

A *signing* of order n is a nonzero diagonal matrix $D = \text{diag}(d_1, d_2, \dots, d_n)$ each of whose diagonal entries d_i equals 0, 1 or -1 . A *strict signing* is a signing each of whose diagonal entries equals 1 or -1 . Let A be an m by n matrix. If D is a (strict) signing of order m and E is a (strict) signing of order n , then DA is a (strict) *row signing* of A and AE is a (strict) *column signing* of A . A vector u is *unsigned* provided $u \neq 0$ and each of the nonzero entries of u has the same sign. A vector u is *balanced* provided it is not unsigned.

The following lemma is an easy consequence of the definitions.

Lemma 2.1 *Let A be an m by n matrix. Then*

- (i) *A is an L -matrix if and only if every row signing of A contains a unsigned column [KLM 83];*
- (ii) *A is a nearly L -matrix if and only if there is a signing D such that each column of DA is balanced and every such signing is strict;*

- (iii) *A is a CS*-matrix if and only if A has no zero rows and there exists a strict signing D such that AD and A(-D) are the only column signings of A each of whose rows is balanced;*
- (iv) *A is a CS-matrix if and only if A has no zero rows and AI_n = A and A(-I_n) = -A are the only column signings of A each of whose rows is balanced.*
- (v) *A is a CS*-matrix if and only if there exists a strict signing D such that AD is a CS-matrix.*

By definition the transpose of a CS*-matrix is a nearly L-matrix, but the converse does not hold. For example, consider the matrix

$$A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}.$$

It is easy to verify that the only signings D such that each row of AD is balanced are $\pm \text{diag}(1, -1, 1, -1)$ and $\pm \text{diag}(1, -1, -1, 1)$. Thus by (ii) of Lemma 2.1 A^T is a nearly L-matrix, and by (iii) A is not a CS*-matrix.

Conditional sign-solvability can also be characterized in terms of signings.

Lemma 2.2 *Let $Ax = b$ be a linear system where A is an m by n matrix. Then $Ax = b$ is conditionally sign-solvable if and only if there exists a unique signing of the form $D = \text{diag}(d_1, \dots, d_n, 1)$ such that each row of $[A \ - b]D$ is balanced.*

Proof. Let $u = (u_1, u_2, \dots, u_n)^T$ be a column vector and let D be the signing $\text{diag}(d_1, d_2, \dots, d_n, 1)$ where $\text{sign } u_i = d_i$ for $i = 1, 2, \dots, n$. Then clearly if there exists \tilde{A} in $\mathcal{Q}(A)$ and \tilde{b} in $\mathcal{Q}(b)$ such that $\tilde{A}u = \tilde{b}$, then each row of $[A \ - b]D$ is balanced.

Now let D be a signing of the form $\text{diag}(d_1, d_2, \dots, d_n, 1)$. If each row of $[A \ - b]D$ is balanced, then there exists \tilde{A} in $\mathcal{Q}(A)$ and \tilde{b} in $\mathcal{Q}(b)$ such that $u = (d_1, d_2, \dots, d_n)^T$ satisfies $\tilde{A}u = \tilde{b}$. The lemma now follows. \square

Suppose that $Ax = b$ is conditionally sign-solvable. If \tilde{A} is in $\mathcal{Q}(A)$ and \tilde{b} is in $\mathcal{Q}(b)$, and if $\tilde{A}x = \tilde{b}$ is solvable, then it is easy to see that the columns of \tilde{A} are linearly independent and the solution is unique. Thus if $Ax = b$ is sign-solvable, then A^T is an L-matrix. If \tilde{A} is in $\mathcal{Q}(A)$, then it can happen that there does not exist a \tilde{b} in $\mathcal{Q}(b)$ such that $\tilde{A}x = \tilde{b}$ is solvable. For instance, suppose we take $\tilde{A} = \text{sign } A$ in our introductory example (1). Then the

leading submatrix of \tilde{A} of order 3 is invertible and hence $\tilde{A}x = \tilde{b}$ does not have a solution for any \tilde{b} in $\mathcal{Q}(b)$. Thus if $Ax = b$ is only conditionally sign-solvable, then we cannot use the above argument to conclude that A^T is an L -matrix. However, the conclusion does hold.

Theorem 2.3 *If $Ax = b$ be a conditionally sign-solvable linear system, then A^T is an L -matrix.*

Proof. Let A be an m by n matrix. Suppose that A^T is not an L -matrix. We prove that $Ax = b$ is not conditionally sign-solvable by showing that there does not exist a unique signing of the form $D = \text{diag}(d_1, \dots, d_n, 1)$ such that each row of $[A \ -b]D$ is balanced, and then applying Lemma 2.2. We may assume that there exists some diagonal matrix $D = \text{diag}(d_1, \dots, d_n, 1)$ such that each row of $[A \ -b]D$ is balanced, for otherwise we are done. By (i) of Lemma 2.1 there exists a signing $E = \text{diag}(e_1, \dots, e_n)$ such that each row of AE is balanced.

After permutations of the columns of A , we may assume that $E = E_1 \oplus O$ where E_1 is a strict signing of order ℓ where $1 \leq \ell \leq n$. After row permutations we may assume that $[A \ -b]$ has the form

$$\left[\begin{array}{c|c|c} A_1 & A_3 & -b^1 \\ \hline O & A_2 & -b^2 \end{array} \right]$$

where A_1 is a k by ℓ matrix with no zero rows. Each row of the matrices

$$[A \ -b]\text{diag}(e_1, \dots, e_\ell, d_{\ell+1}, \dots, d_n, 1)$$

and

$$[A \ -b]\text{diag}(-e_1, \dots, -e_\ell, d_{\ell+1}, \dots, d_n, 1)$$

is balanced and the theorem follows. \square

Corollary 2.4 *Let $Ax = b$ be a linear system where A is a square matrix. Then $Ax = b$ is conditionally sign-solvable if and only if it is sign-solvable.*

Proof. Suppose that $Ax = b$ is conditionally sign-solvable. By Theorem 2.3 A is an L -matrix. Hence each matrix \tilde{A} in $\mathcal{Q}(A)$ is invertible. Thus $\tilde{A}x = \tilde{b}$ is always solvable and $Ax = b$ is sign-solvable. The converse is obvious. \square

The main result of this paper is that recognizing the conditional sign-solvability of solvable linear systems is equivalent to recognizing L -matrices and CS^* -matrices. First we prove the following lemma.

Lemma 2.5 *Let $Ax = b$ be a linear system of the form*

$$\begin{aligned} A_1 x^1 + A_3 x^2 &= b^1 \\ A_2 x^2 &= 0 \end{aligned} \tag{4}$$

where $[A_1 \ -b^1]$ is a CS*-matrix and A_2^T is an L-matrix. Then $Ax = b$ is conditionally sign-solvable.

Proof. Suppose that A has n columns and A_1 has ℓ columns. Let D be a signing of the form $D = \text{diag}(d_1, \dots, d_n, 1)$. Since A_2^T is an L-matrix, each row of $[A \ -b]D$ is balanced if and only if $d_{\ell+1} = \dots = d_n = 0$ and each row of $[A_1 \ -b^1]\text{diag}(d_1, \dots, d_\ell, 1)$ is balanced. Since $[A_1 \ -b^1]$ is a CS*-matrix, the lemma follows from (iii) of Lemma 2.1 and Lemma 2.2. \square

Let B be a p by q matrix. Let α be a subset of $\{1, 2, \dots, p\}$ and β be a subset of $\{1, 2, \dots, q\}$. Then the submatrix of B determined by the rows with index in α and the columns with index in β is denoted by $A[\alpha, \beta]$. The submatrix of B determined by the rows with index not in α and columns with index not in β is denoted by $A[\bar{\alpha}, \bar{\beta}]$. If b is a p by 1 column vector, then we shorten $b[\alpha, \{1\}]$ to $b[\alpha]$.

Theorem 2.6 *Let $Ax = b$ be a linear system where $A = [a_{ij}]$ is an m by n matrix and b is an m by 1 column vector. Let $u = (u_1, u_2, \dots, u_n)^T$ be an n by 1 column vector satisfying $Au = b$, and let*

$$\beta = \{j : u_j \neq 0\} \text{ and } \alpha = \{i : a_{ij} \neq 0 \text{ for some } j \in \beta\}.$$

Then $Ax = b$ is conditionally sign-solvable if and only if the matrix

$$\begin{bmatrix} A[\alpha, \beta] & -b[\alpha] \end{bmatrix}$$

is a CS*-matrix and the matrix

$$A[\bar{\alpha}, \bar{\beta}]^T$$

is an L-matrix.

Proof. Without loss of generality we may assume that

$$\beta = \{1, 2, \dots, \ell\} \text{ and } \alpha = \{1, 2, \dots, k\}$$

for some nonnegative integers k and ℓ . Thus

$$A = \begin{bmatrix} A_1 & A_3 \\ O & A_2 \end{bmatrix}$$

where A_1 is a k by ℓ matrix with no zero rows, and $u_i = 0$ if and only if $\ell + 1 \leq i \leq n$. The linear system $Ax = b$ can be written as

$$\begin{aligned} A_1 x^1 + A_3 x^2 &= b^1 \\ A_2 x^2 &= 0 \end{aligned}$$

where

$$x^1 = x[\{1, 2, \dots, \ell\}] \text{ and } x^2 = x[\{\ell + 1, \dots, n\}],$$

and

$$b^1 = b[\{1, 2, \dots, k\}].$$

It follows from Lemma 2.5 that if $[A_1 \ - b^1]$ is a CS*-matrix and A_2^T is an L -matrix, then $Ax = b$ is conditionally sign-solvable.

Now assume that $Ax = b$ is conditionally sign-solvable. By Lemma 2.2 there is a unique signing of the form $D = \text{diag}(d_1, \dots, d_n, 1)$ such that each row of $[A \ - b]D$ is balanced. Since $Au = b$ we have $d_i = \text{sign } u_i$ for $i = 1, 2, \dots, n$. If $E = \text{diag}(e_1, \dots, e_\ell, 1)$ is a signing such that each row of $[A_1 \ - b^1]E$ is balanced, then each row of

$$[A \ - b]\text{diag}(e_1, \dots, e_\ell, 0, \dots, 0, 1)$$

is balanced. It now follows from (ii) of Lemma 2.1 that $[A_1 \ - b^1]$ is a CS*-matrix. If $F = \text{diag}(f_{\ell+1}, \dots, f_n)$ is a signing such that each row of $A_2 F$ is balanced, then each row of

$$[A \ - b]\text{diag}(d_1, \dots, d_\ell, f_{\ell+1}, \dots, f_n, 1)$$

is balanced. It follows from (i) of Lemma 2.1 that A_2 is an L -matrix. \square

Since a CS*-matrix with the property that every matrix in its qualitative class has a nontrivial right nullspace is an S^* -matrix, Theorem 2.6 immediately implies the following [KLM 83].

Corollary 2.7 *Let $Ax = b$ be a linear system where $A = [a_{ij}]$ is an m by n matrix and b is an m by 1 column vector. Let $u = (u_1, u_2, \dots, u_n)^T$ be an n by 1 column vector satisfying $Au = b$, and let*

$$\beta = \{j : u_j \neq 0\} \text{ and } \alpha = \{i : a_{ij} \neq 0 \text{ for some } j \in \beta\}.$$

Then $Ax = b$ is sign-solvable if and only if the matrix

$$\begin{bmatrix} A[\alpha, \beta] & -b[\alpha] \end{bmatrix}$$

is an S^* -matrix and the matrix

$$A[\bar{\alpha}, \bar{\beta}]^T$$

is an L -matrix.

3 BCS*-matrices

Let M be an m by n CS-matrix. If u is a 1 by n nonzero row vector, then clearly

$$\begin{bmatrix} M \\ u \end{bmatrix}$$

is a CS-matrix if and only if u is balanced. Thus it is natural to consider CS-matrices, respectively CS^* -matrices, for which each matrix obtained by deleting a row is not a CS-matrix, respectively not a CS^* -matrix. We call such matrices *barely CS-* and *barely CS^* -matrices*, abbreviated BCS- and BCS*-matrices. Thus M is a BCS*-matrix if and only if M is a CS^* -matrix and for each $i = 1, 2, \dots, m$ there exists a signing D_i such that row i is the only row of MD_i which is not balanced. In particular, if M is a BCS*-matrix, then no two rows of sign M are equal or opposites. Any S^* -matrix, respectively S -matrix, is an example of a BCS*-matrix, respectively BCS-matrix.

An L -matrix A is a *barely L -matrix* [BCS 92] provided each matrix obtained from A by deleting a column is not an L -matrix. An L -matrix A is *L -decomposable* [BCS 92] provided there exist permutation matrices P and Q such that

$$A = P \begin{bmatrix} A_1 & O \\ A_3 & A_2 \end{bmatrix} Q,$$

where A_1 and A_2 are (non-vacuous) L -matrices. If A is not L -decomposable, then A is *L -indecomposable*. The L -indecomposable, barely L -matrices are fundamental in the study of L -matrices. The following result is contained in [BCS 92].

Lemma 3.1 *Let A be an m by n L -matrix. Then A is an L -indecomposable, barely L -matrix if and only if for each integer j with $1 \leq j \leq n$ there exists a strict row signing of A whose only unsigned column is column j .*

A BCS*-matrix with n columns can have exponentially many rows. For example, let B be a 2^{n-1} by n matrix whose rows are all the 1 by n row vectors of 1's and -1 's with first entry equal to 1 and whose first row is the all 1's vector. It is easy to check that B^T is an L -indecomposable, barely L -matrix. Let A be the $2^{n-1} - 1$ by n matrix obtained from B by deleting its first row. Then it is also easy to check that A is a CS-matrix. If $v = (v_1, v_2, \dots, v_n)$ is a row of A , then $D = \text{diag}(v_1, v_2, \dots, v_{n-1}, v_n)$ is a signing such that vD is the only row of AD which is not balanced. Therefore A is a BCS-matrix. In general, any matrix obtained from B by deleting a row of B is a BCS*-matrix. This observation suggests that the problem of recognizing matrices which are not CS-matrices is an NP-complete problem.¹ In contrast, there is a polynomial algorithm to recognize whether or not a matrix is an S -matrix [KLM 83], [M 82].

We now generalize the above construction.

Theorem 3.2 *Let $B = [b_{ij}]$ be an m by n matrix such that B^T is an L -indecomposable, barely L -matrix. Let i be an integer such that each entry in row i of B is different from zero. Then the matrix A obtained from B by deleting row i is a BCS*-matrix, and $D = \text{diag}(b_{i1}, b_{i2}, \dots, b_{in})$ is a strict signing such that each row of AD is balanced.*

Proof. Since B^T is an L -indecomposable, barely L -matrix, it follows from Lemma 3.1 that for each row i' of A there exists a strict column signing of A whose only unsigned row is row i' . Thus it suffices to show that A is a CS*-matrix. Let E be a signing such that each row of AE is balanced. Suppose that E is not a strict signing. We may assume that $E = E_1 \oplus O$ where E_1 is a strict signing of order $\ell < n$. We may further assume that $i = 1$ and

$$B = \begin{bmatrix} B_1 & B_3 \\ O & B_2 \end{bmatrix}$$

where B_1 has ℓ columns and no zero rows. Since B^T is L -indecomposable, B_2^T is not an L -matrix. Hence there exists a signing F of order $n - \ell$ such that each row of B_2F is balanced. Since row 1 of B has no zero entries, one of the column signings $B(E_1 \oplus F)$ and $B(E_1 \oplus -F)$ of B has all of its rows balanced. This contradicts the assumption that B^T is an L -matrix. Hence E is a strict signing. Since B^T is an L -matrix and each entry of the first row

¹It is easy to see that this problem is in the class NP: certify that a matrix A is not a conditionally S -matrix by giving either an unbalanced row of A or a signing $D \neq \pm I_n$ such that all rows of AD are balanced.

of B is different from zero, $E = \pm D$. Since B^T is a barely L -matrix, each row of AD is balanced and hence A is a CS^* -matrix. \square

We now show that every BCS^* -matrix can be obtained by the above construction.

Theorem 3.3 *Let A be an m by n BCS^* -matrix and let $D = \text{diag}(d_1, d_2, \dots, d_n)$ be a signing such that each row of AD is balanced. Let*

$$B = \left[\begin{array}{cccc} A & & & \\ d_1 & d_2 & \cdots & d_n \end{array} \right].$$

Then each entry of the last row of B is different from zero, and B^T is an L -indecomposable, barely L -matrix.

Proof. It follows from (i) and (iii) of Lemma 2.1 that B^T is an L -matrix and each entry of the last row of B is different from zero. By Lemma 3.1 it suffices to show that for each integer i with $1 \leq i \leq m+1$ that there is a strict column signing of B whose only unsigned row is row i . If $i = m+1$, BD is such a strict column signing of B . Now assume that $1 \leq i \leq m$. Since A is a BCS^* -matrix, there exists a signing E such that row i is the only unsigned row of AE . First suppose that E is not a strict signing. Without loss of generality we may assume that $E = E_1 \oplus O$ where E_1 is a strict signing of order $\ell < n$. Further by permuting rows of A we may assume that $i = 1$ and that A has the form

$$\left[\begin{array}{cc} A_1 & A_3 \\ O & A_2 \end{array} \right],$$

where A_1 is a k by ℓ matrix with no zero rows. By (iii) of Lemma 2.1 there exists a strict signing D such that each row of AD is balanced. Let $D = D_1 \oplus D_2$ where D_1 and D_2 are strict signings of orders ℓ and $n - \ell$, respectively. Both $A(E_1 \oplus D_2)$ and $A(E_1 \oplus (-D_2))$ are strict column signings of A all of whose rows, except possibly the first row, are balanced. Since A is a CS^* -matrix, the first row of one of these strict column signings of A must be unsigned. Hence we may assume that E is a strict signing. Since E is a strict signing, $E \neq \pm D$ and hence row i is the only unsigned row of BE . \square

It follows from Theorems 3.2 and 3.3 that the study of BCS^* -matrices is essentially equivalent to the study of L -indecomposable, barely L -matrices having a column with no zero entries.

4 Concluding Remarks

Let A be an m by n matrix whose columns are the vectors v_1, v_2, \dots, v_n . Then v_1, v_2, \dots, v_n are the vertices of an $(n - 1)$ -simplex whose relative interior contains the origin if and only if the right nullspace of A is spanned by a vector u each of whose entries is positive. It follows that A is a CS-matrix if and only if there is a matrix in $\mathcal{Q}(A)$ with linearly dependent columns, and for each matrix \tilde{A} in $\mathcal{Q}(A)$ with linearly dependent column vectors, its column vectors are the vertices of a $(n - 1)$ -simplex whose relative interior contains the origin. This generalizes the observation in [KL 81] that an m by $m + 1$ matrix is an S -matrix if and only if for each \tilde{A} in $\mathcal{Q}(A)$, the columns of \tilde{A} are the vertices of a simplex whose interior contains the origin.

There is a significant computational difference between the relationship of S^* -matrices to S -matrices and that of CS^* -matrices to CS -matrices. If A is an m by $m + 1$ S^* -matrix, then to find a strict signing D such that AD is an S -matrix we need only find a nonzero vector $u = (u_1, u_2, \dots, u_{m+1})^T$ such that $Au = 0$ and let

$$D = \text{diag}(\text{sign } u_1, \text{sign } u_2, \dots, \text{sign } u_{m+1}).$$

Now let A be an m by n CS^* -matrix. There may not exist an n by 1 nonzero vector u such that $Au = 0$. Finding a strict signing D such that AD is a CS -matrix is equivalent to first finding a matrix \tilde{A} in $\mathcal{Q}(A)$ with rank less than n and then finding a nonzero solution of $\tilde{A}x = 0$. Finding an \tilde{A} in $\mathcal{Q}(A)$ with rank less than n seems to be a difficult problem in general. This is suggested by the next theorem and the observation that if a matrix \tilde{A} in $\mathcal{Q}(A)$ has rank n , then there is an open subset X of $\mathcal{Q}(A)$ containing \tilde{A} such that all matrices in X have rank n .

Theorem 4.1 *Let A be an m by n CS^* -matrix which is not an S^* -matrix. Then the set of all matrices \tilde{A} in $\mathcal{Q}(A)$ such that the rank of \tilde{A} equals n is a dense subset of $\mathcal{Q}(A)$.*

Proof. Suppose that there exists a matrix \tilde{A} and an open subset X of $\mathcal{Q}(A)$ containing \tilde{A} such that X contains only matrices of rank $n - 1$. Let u be an n by 1 nonzero column vector with $\tilde{A}u = 0$. Since A is a CS^* -matrix, u has no zero entries. Without loss of generality

$$\tilde{A} = \begin{bmatrix} Y \\ Z \end{bmatrix}$$

where Y is an $n - 1$ by n matrix of rank $n - 1$. For any matrix \tilde{Z} in $\mathcal{Q}(Z)$ sufficiently close to Z , the matrix

$$\begin{bmatrix} Y \\ \tilde{Z} \end{bmatrix}$$

has rank $n - 1$, and hence $\tilde{Z}u = 0$. Since u has no zero entries, we conclude that Z has no nonzero entries. Since a CS*-matrix has no zero rows, it follows that Z is vacuous. Hence A is an S^* -matrix contradicting the hypothesis of the theorem. \square

If A is an m by n nearly L -matrix and Y is a m by p matrix, then

$$\begin{bmatrix} A & Y \end{bmatrix}$$

is a nearly L -matrix if and only if it is not an L -matrix. Thus it is also natural to consider nearly L -matrices for which each matrix obtained by deleting a column is not a nearly L -matrix. Let A be such a nearly L -matrix. While the left nullspace of a matrix \tilde{A} in $\mathcal{Q}(A)$ is trivial or contains nonzero vectors of only one sign pattern or its negative, the number of different sign patterns as \tilde{A} varies over the qualitative class of A can be exponentially large. For example, let A_k be the matrix of order $2k$ defined by

$$\begin{bmatrix} G & O & \cdots & O & F \\ F & G & \cdots & O & O \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ O & O & \cdots & G & O \\ O & O & \cdots & F & G \end{bmatrix}$$

where

$$G = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} \text{ and } F = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}.$$

It is easy to verify that the only signings D for which each column of DA_k is balanced are those of the form $D = \text{diag}(c_1, c_1, c_2, c_2, \dots, c_k, c_k)$ where each c_i equals ± 1 . Thus A_k is a nearly L -matrix and there are 2^k different sign patterns in the left nullspaces of matrices in $\mathcal{Q}(A_k)$. For each column of A_k there is a nonstrict signing which balances each of the other columns of A_k . For instance, if $E = \text{diag}(-1, 0, 1, \dots, 1)$, then only column 1 of EA_k is not balanced, while if $E' = \text{diag}(0, 0, 1, \dots, 1)$ then only column 2 of $E'A_k$ is not balanced. Hence each matrix obtained from A_k by deleting a column is not a nearly L -matrix.

References

- [BCS 92] R.A. Brualdi, K.L. Chavey, and B.L. Shader. *Rectangular L-matrices*, submitted.
- [G 64] W. M. Gorman. A wider scope for qualitative economics. *Reviews of Economic Studies*, 31:65–68, 1964.
- [KL 81] V. Klee and R. Ladner. Qualitative matrices: Strong sign-solvability and weak satisfiability, 293–320. *Computer assisted analysis and model simplification*, H. Greenberg and J. Maybee eds., Academic Press, New York, 1981.
- [KLM 83] V. Klee, R. Ladner, and R. Manber. Signsolvability revisited. *Linear Algebra and its Applications*, 59:131–157, 1983.
- [BMQ 68] L. Bassett, J. Maybee, and J. Quirk. Qualitative economics and the scope of the correspondence principle. *Econometrica*, 36:544–563, 1968.
- [L 63] K. Lancaster. The theory of qualitative linear systems. *Econometrica*, 33:395–408, 1963.
- [M 82] R. Manber. Graph-theoretical approach to qualitative solvability of linear systems. *Linear Algebra and its Applications*, 48:457–470, 1982.
- [S 47] P. A. Samuelson. *Foundations of economic analysis*. Harvard University Press, 1947.

#	Author/s	Title
866	Gui-Qiang Chen and Tai-Ping Liu,	Zero relaxation and dissipation limits for hyperbolic conservation laws
867	Gui-Qiang Chen and Jian-Guo Liu,	Convergence of second-order schemes for isentropic gas dynamics
868	Aleksander M. Simon and Zbigniew J. Grzywna,	On the Larché-Cahn theory for stress-induced diffusion
869	Jerzy Łuczka, Adam Gadomski and Zbigniew J. Grzywna,	Growth driven by diffusion
870	Mitchell Luskin and Tsorng-Whay Pan,	Nonplanar shear flows for nonaligning nematic liquid crystals
871	Mahmoud Affouf,	Unique global solutions of initial-boundary value problems for thermodynamic phase transitions
872	Richard A. Brualdi and Keith L. Chavey,	Rectangular L -matrices
873	Xinfu Chen, Avner Friedman and Bei Hu,	The thermistor problem with zero-one conductivity II
874	Raoul LePage,	Controlling a diffusion toward a large goal and the Kelly principle
875	Raoul LePage,	Controlling for optimum growth with time dependent returns
876	Marc Hallin and Madan L. Puri,	Rank tests for time series analysis a survey
877	V.A. Solonnikov,	Solvability of an evolution problem of thermocapillary convection in an infinite time interval
878	Horia I. Ene and Bogdan Vernescu,	Viscosity dependent behaviour of viscoelastic porous media
879	Kaushik Bhattacharya,	Self-accommodation in martensite
880	D. Lewis, T. Ratiu, J.C. Simo and J.E. Marsden,	The heavy top: a geometric treatment
881	Leonid V. Kalachev,	Some applications of asymptotic methods in semiconductor device modeling
882	David C. Dobson,	Phase reconstruction via nonlinear least-squares
883	Patricio Aviles and Yoshikazu Giga,	Minimal currents, geodesics and relaxation of variational integrals on mappings of bounded variation
884	Patricio Aviles and Yoshikazu Giga,	Partial regularity of least gradient mappings
885	Charles R. Johnson and Michael Lundquist,	Operator matrices with chordal inverse patterns
886	B.J. Bayly,	Infinitely conducting dynamos and other horrible eigenproblems
887	Charles M. Elliott and Stefan Luckhaus,	'A generalised diffusion equation for phase separation of a multi-component mixture with interfacial free energy'
888	Christian Schmeiser and Andreas Unterreiter,	The derivation of analytic device models by asymptotic methods
889	LeRoy B. Beasley and Norman J. Pullman,	Linear operators that strongly preserve the index of imprimitivity
890	Jerry Donato,	The Boltzmann equation with lie and cartan
891	Thomas R. Hoffend Jr., Peter Smereka and Roger J. Anderson,	A method for resolving the laser induced local heating of moving magneto-optical recording media
892	E.G. Kalnins, Willard Miller, Jr. and Sanchita Mukherjee,	Models of q -algebra representations: the group of plane motions
893	T.R. Hoffend Jr. and R.K. Kaul,	Relativistic theory of superpotentials for a nonhomogeneous, spatially isotropic medium
894	Reinhold von Schwerin,	Two metal deposition on a microdisk electrode
895	Vladimir I. Oliker and Nina N. Uraltseva,	Evolution of nonparametric surfaces with speed depending on curvature, III. Some remarks on mean curvature and anisotropic flows
896	Wayne Barrett, Charles R. Johnson, Raphael Loewy and Tamir Shalom,	Rank incrementation via diagonal perturbations
898	Mingxiang Chen, Xu-Yan Chen and Jack K. Hale,	Structural stability for time-periodic one-dimensional parabolic equations
899	Hong-Ming Yin,	Global solutions of Maxwell's equations in an electromagnetic field with the temperature-dependent electrical conductivity
900	Robert Grone, Russell Merris and William Watkins,	Laplacian unimodular equivalence of graphs
901	Miroslav Fiedler,	Structure-ranks of matrices
902	Miroslav Fiedler,	An estimate for the nonstochastic eigenvalues of doubly stochastic matrices
903	Miroslav Fiedler,	Remarks on eigenvalues of Hankel matrices
904	Charles R. Johnson, D.D. Olesky, Michael Tsatsomeros and P. van den Driessche,	Spectra with positive elementary symmetric functions
905	Pierre-Alain Gremaud,	Thermal contraction as a free boundary problem
906	K.L. Cooke, Janos Turi and Gregg Turner,	Stabilization of hybrid systems in the presence of feedback delays
907	Robert P. Gilbert and Yongzhi Xu,	A numerical transmutation approach for underwater sound propagation
908	LeRoy B. Beasley, Richard A. Brualdi and Bryan L. Shader,	Combinatorial orthogonality
909	Richard A. Brualdi and Bryan L. Shader,	Strong hall matrices
910	Håkan Wennerström and David M. Anderson,	Difference versus Gaussian curvature energies; monolayer versus bilayer curvature energies applications to vesicle stability
911	Shmuel Friedland,	Eigenvalues of almost skew symmetric matrices and tournament matrices
912	Avner Friedman, Bei Hu and J.L. Velazquez,	A Free Boundary Problem Modeling Loop Dislocations in Crystals
913	Ezio Venturino,	The Influence of Diseases on Lotka-Volterra Systems
914	Steve Kirkland and Bryan L. Shader,	On Multipartite Tournament Matrices with Constant Team Size

- 915 **Richard A. Brualdi and Jennifer J.Q. Massey**, More on Structure-Ranks of Matrices
- 916 **Douglas B. Meade**, Qualitative Analysis of an Epidemic Model with Directed Dispersion
- 917 **Kazuo Murota**, Mixed Matrices Irreducibility and Decomposition
- 918 **Richard A. Brualdi and Jennifer J.Q. Massey**, Some Applications of Elementary Linear Algebra in Combinations
- 919 **Carl D. Meyer**, Sensitivity of Markov Chains
- 920 **Hong-Ming Yin**, Weak and Classical Solutions of Some Nonlinear Volterra Integrodifferential Equations
- 921 **B. Leinkuhler and A. Ruehli**, Exploiting Symmetry and Regularity in Waveform Relaxation Convergence Estimation
- 922 **Xinfu Chen and Charles M. Elliott**, Asymptotics for a Parabolic Double Obstacle Problem
- 923 **Yongzhi Xu and Yi Yan**, An Approximate Boundary Integral Method for Acoustic Scattering in Shallow Oceans
- 924 **Yongzhi Xu and Yi Yan**, Source Localization Processing in Perturbed Waveguides
- 925 **Kenneth L. Cooke and Janos Turi**, Stability, Instability in Delay Equations Modeling Human Respiration
- 926 **F. Bethuel, H. Brezis, B.D. Coleman and F. Hélein**, Bifurcation Analysis of Minimizing Harmonic Maps Describing the Equilibrium of Nematic Phases Between Cylinders
- 927 **Frank W. Elliott, Jr.**, Signed Random Measures: Stochastic Order and Kolmogorov Consistency Conditions
- 928 **D.A. Gregory, S.J. Kirkland and B.L. Shader**, Pick's Inequality and Tournaments
- 929 **J.W. Demmel, N.J. Higham and R.S. Schreiber**, Block LU Factorization
- 930 **Victor A. Galaktionov and Juan L. Vazquez**, Regional Blow-Up in a Semilinear Heat Equation with Convergence to a Hamilton-Jacobi Equation
- 931 **Bryan L. Shader**, Convertible, Nearly Decomposable and Nearly Reducible Matrices
- 932 **Dianne P. O'Leary**, Iterative Methods for Finding the Stationary Vector for Markov Chains
- 933 **Nicholas J. Higham**, Perturbation theory and backward error for $AX - XB = C$
- 934 **Z. Strakos and A. Greenbaum**, Open questions in the convergence analysis of the lanczos process for the real symmetric eigenvalue problem
- 935 **Zhaojun Bai**, Error analysis of the lanczos algorithm for the nonsymmetric eigenvalue problem
- 936 **Pierre-Alain Gremaud**, On an elliptic-parabolic problem related to phase transitions in shape memory alloys
- 937 **Bojan Mohar and Neil Robertson**, Disjoint essential circuits in toroidal maps
- 938 **Bojan Mohar**, Convex representations of maps on the torus and other flat surfaces
- 939 **Bojan Mohar and Svatopluk Poljak** Eigenvalues in combinatorial optimization
- 940 **Richard A. Brualdi, Keith L. Chavey and Bryan L. Shader**, Conditional sign-solvability
- 941 **Roger Fosdick and Ying Zhang**, The torsion problem for a nonconvex stored energy function
- 942 **René Ferland and Gaston Giroux**, An unbounded mean-field intensity model: Propagation of the convergence of the empirical laws and compactness of the fluctuations
- 943 **Wei-Ming Ni and Izumi Takagi**, Spike-layers in semilinear elliptic singular Perturbation Problems
- 944 **Henk A. Van der Vorst and Gerard G.L. Sleijpen**, The effect of incomplete decomposition preconditioning on the convergence of conjugate gradients
- 945 **S.P. Hastings and L.A. Peletier**, On the decay of turbulent bursts
- 946 **Apostolos Hadjidimos and Robert J. Plemmons**, Analysis of p -cyclic iterations for Markov chains
- 947 **ÅBjörck, H. Park and L. Eldén**, Accurate downdating of least squares solutions
- 948 **E.G. Kalnins, William Miller, Jr. and G.C. Williams**, Recent advances in the use of separation of variables methods in general relativity
- 949 **G.W. Stewart**, On the perturbation of LU , Cholesky and QR factorizations
- 950 **G.W. Stewart**, Gaussian elimination, perturbation theory and Markov chains
- 951 **G.W. Stewart**, On a new way of solving the linear equations that arise in the method of least squares
- 952 **G.W. Stewart**, On the early history of the singular value decomposition
- 953 **G.W. Stewart**, On the perturbation of Markov chains with nearly transient states
- 954 **Umberto Mosco**, Composite media and asymptotic dirichlet forms
- 955 **Walter F. Mascarenhas**, The structure of the eigenvectors of sparse matrices
- 956 **Walter F. Mascarenhas**, A note on Jacobi being more accurate than QR
- 957 **Raymond H. Chan, James G. Nagy and Robert J. Plemmons**, FFT-based preconditioners for Toeplitz-Block least squares problems
- 958 **Zhaojun Bai**, The CSD, GSVD, their applications and computations
- 959 **D.A. Gregory, S.J. Kirkland and N.J. Pullman**, A bound on the exponent of a primitive matrix using Boolean rank
- 960 **Richard A. Brualdi, Shmuel Friedland and Alex Pothén**, Sparse bases, elementary vectors and nonzero minors of compound matrices
- 961 **J.W. Demmel**, Open problems in numerical linear algebra
- 962 **James W. Demmel and William Gragg**, On computing accurate singular values and eigenvalues of acyclic matrices
- 963 **James W. Demmel**, The inherent inaccuracy of implicit tridiagonal QR
- 964 **J.J.L. Velázquez**, Estimates on the $(N - 1)$ -dimensional Hausdorff measure of the blow-up set for a semilinear heat equation