

Hydrostatic Transmission for Wind Power Generation RS-0008-09

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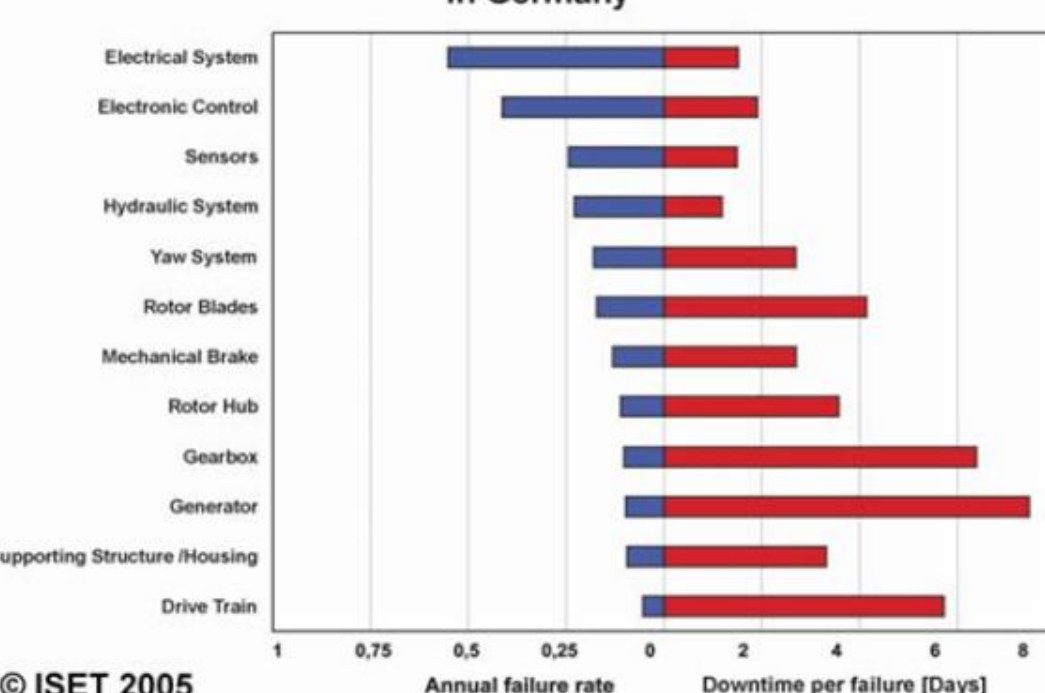
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Motivation

- DOE goal of 20% of U.S. energy from wind by 2030

Failure Rate and Down Time of WTs after Damages in the WMEP in Germany

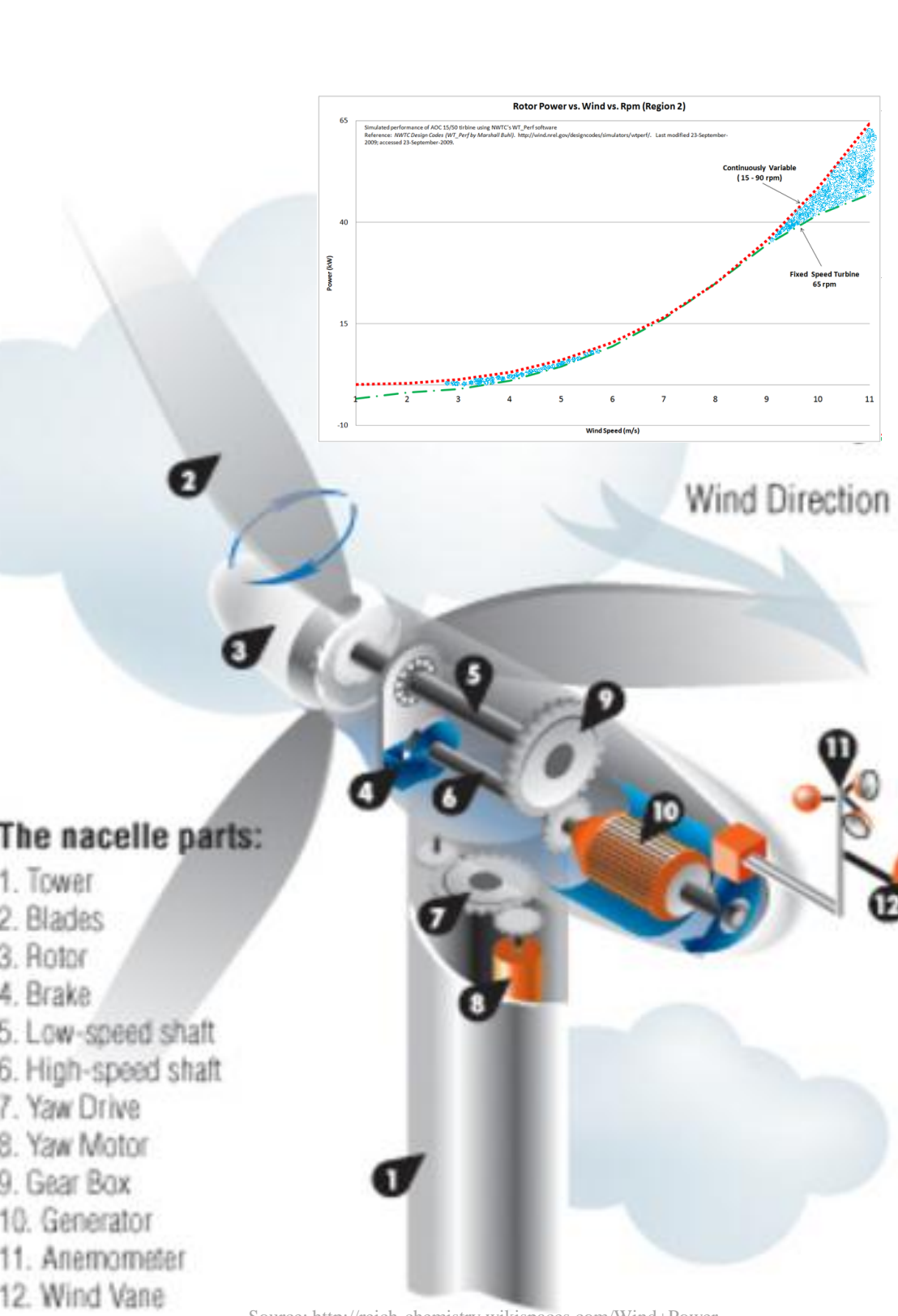


• Gearboxes and power electronics used in most conventional wind turbines have been a major cause of maintenance and premature failure

• Mid-size wind turbines (100– 1000 kW) are an underserved market niche that aligns well with the current state of the art in hydrostatic transmissions

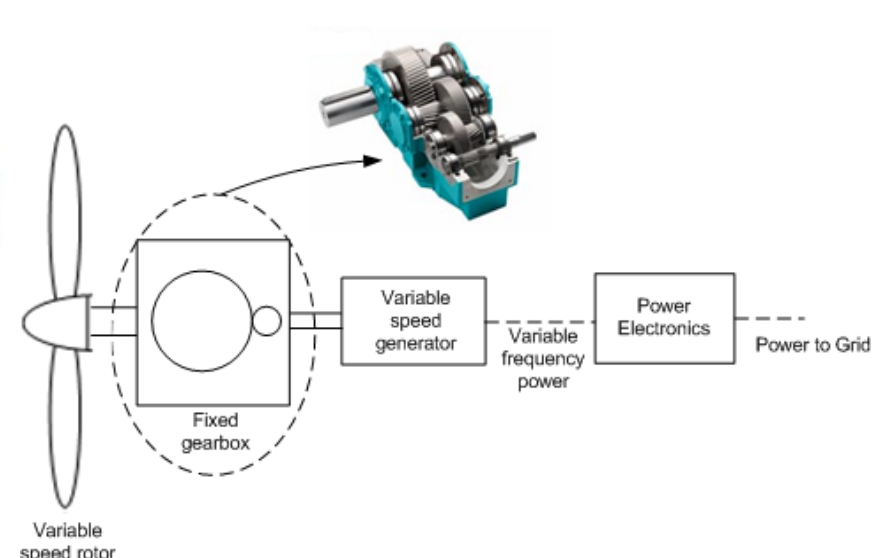
• The need of the hour is to design turbines that are simple yet reliable and robust and at the same time reduce the lifetime cost of energy

Conventional Wind Turbine

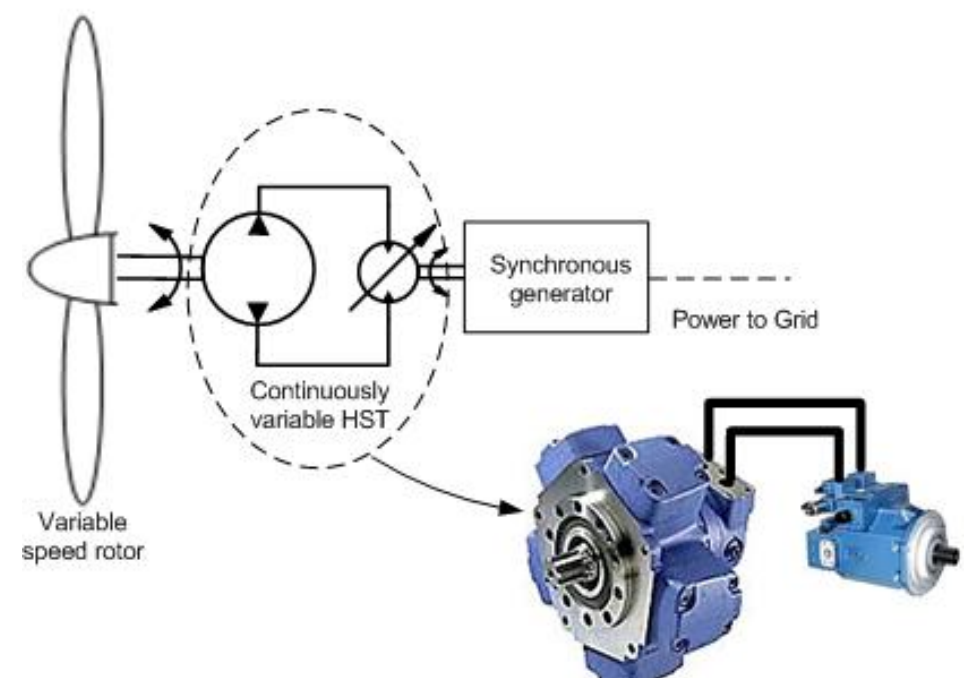


• Conventional utility scale wind turbines are mostly variable speed machines since a variable speed machine produce more energy than a fixed speed turbine

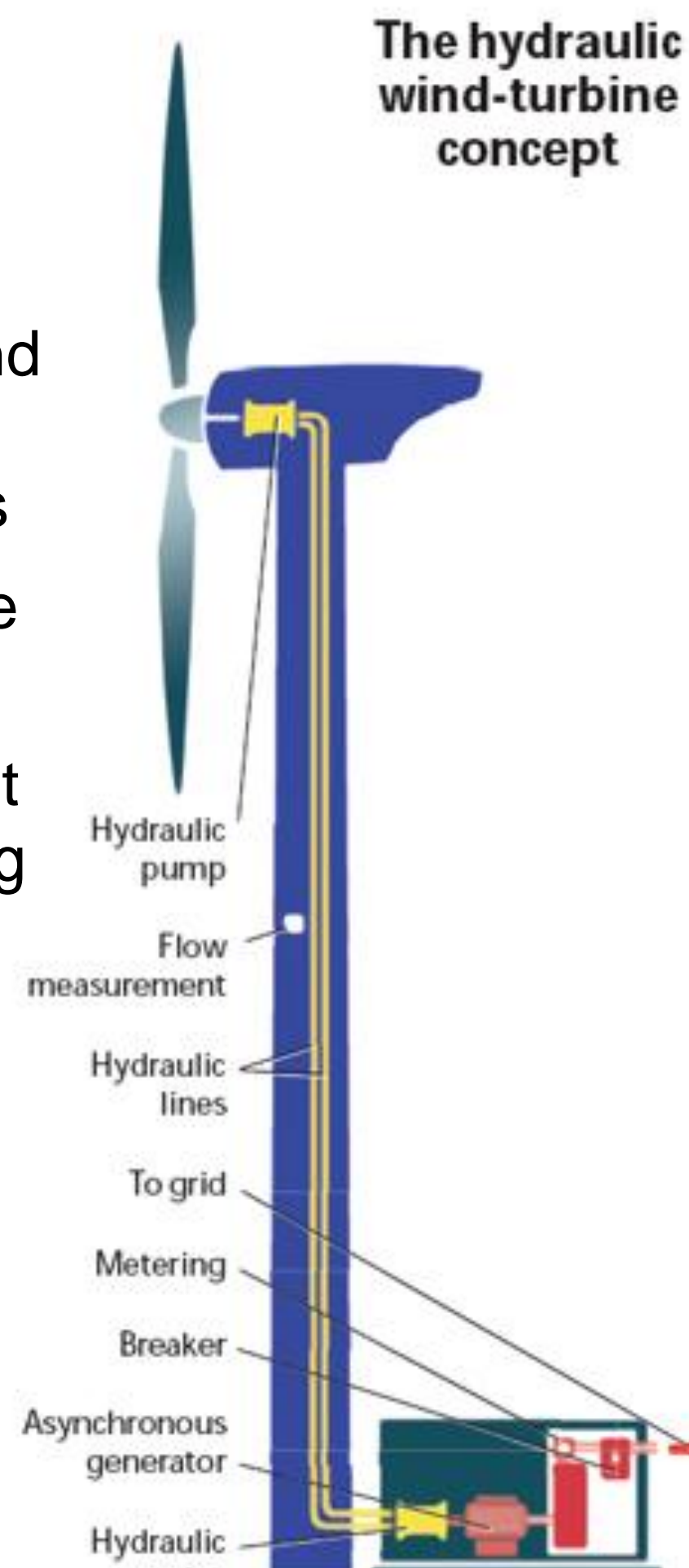
• Variable speed wind turbines require power electronics to allow the generator to operate at varying rotational speed



Hydrostatic Wind Turbine



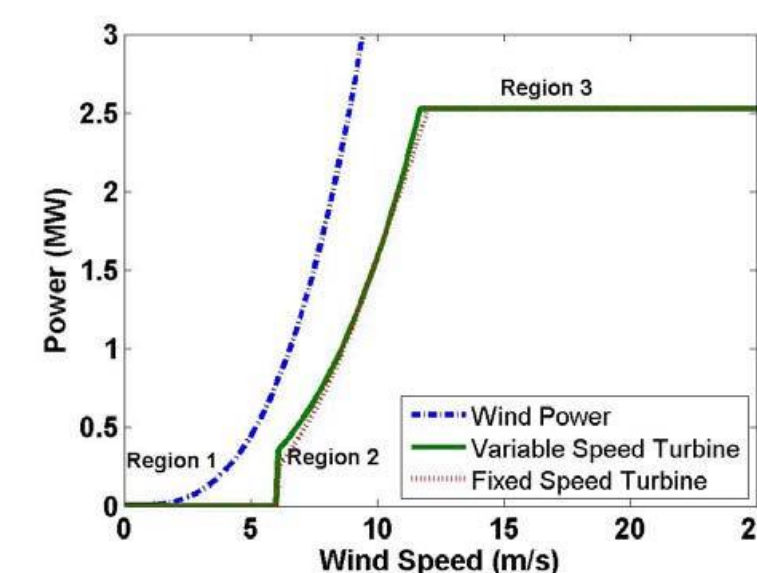
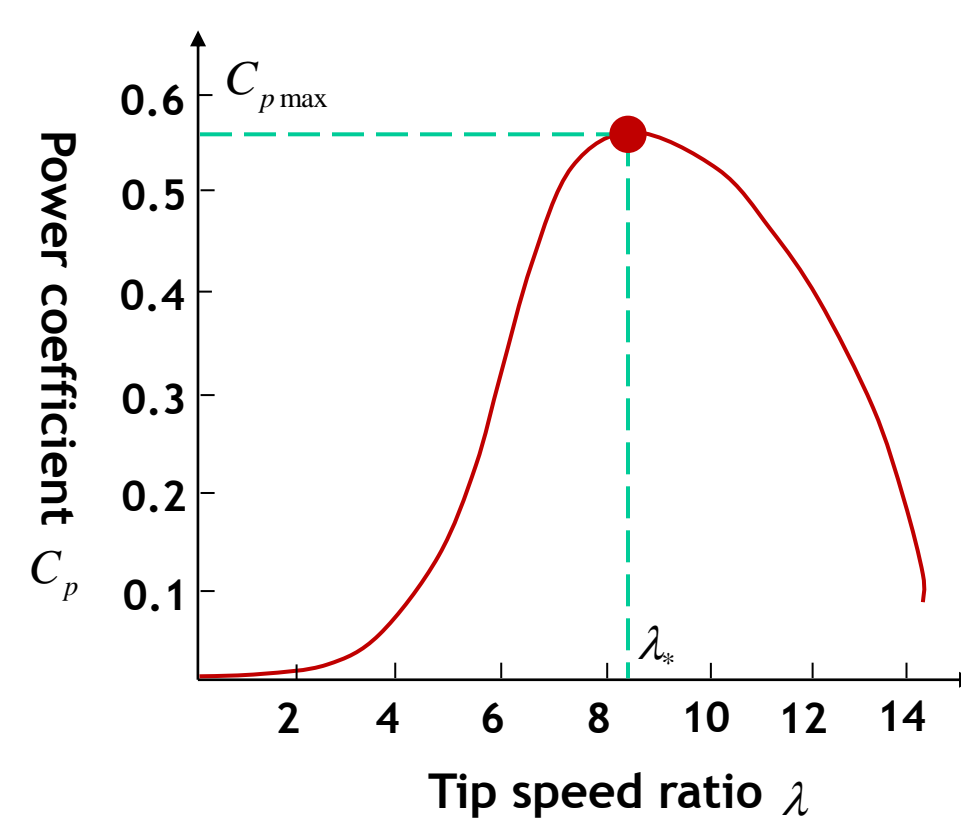
- Fluid link between turbine blades and generator in an HST wind turbine allows for more flexible layout options
- Generator can be removed from the nacelle and placed at ground level
- An HST is inherently more compliant and damped than a gearbox, reducing high stress transients through the system
- The HST decouples the wind power from the generator, allowing power spikes from the wind to be better controlled
- Loads within an HST can be carried by a fluid film, allowing theoretical infinite life



Background

• The objective of wind turbine power generation control for different wind speeds can be divided into four regions

• Wind power coefficient (C_p) is the ratio of wind power captured by the rotor, which is limited by the Betz Limit at 0.593.



$$P_{wind} = \frac{1}{2} \rho A v_{wind}^3$$

$$C_p = \frac{P_{rotor}}{P_{wind}}$$

• C_p is determined by the tip speed ratio of the rotor (TSR)

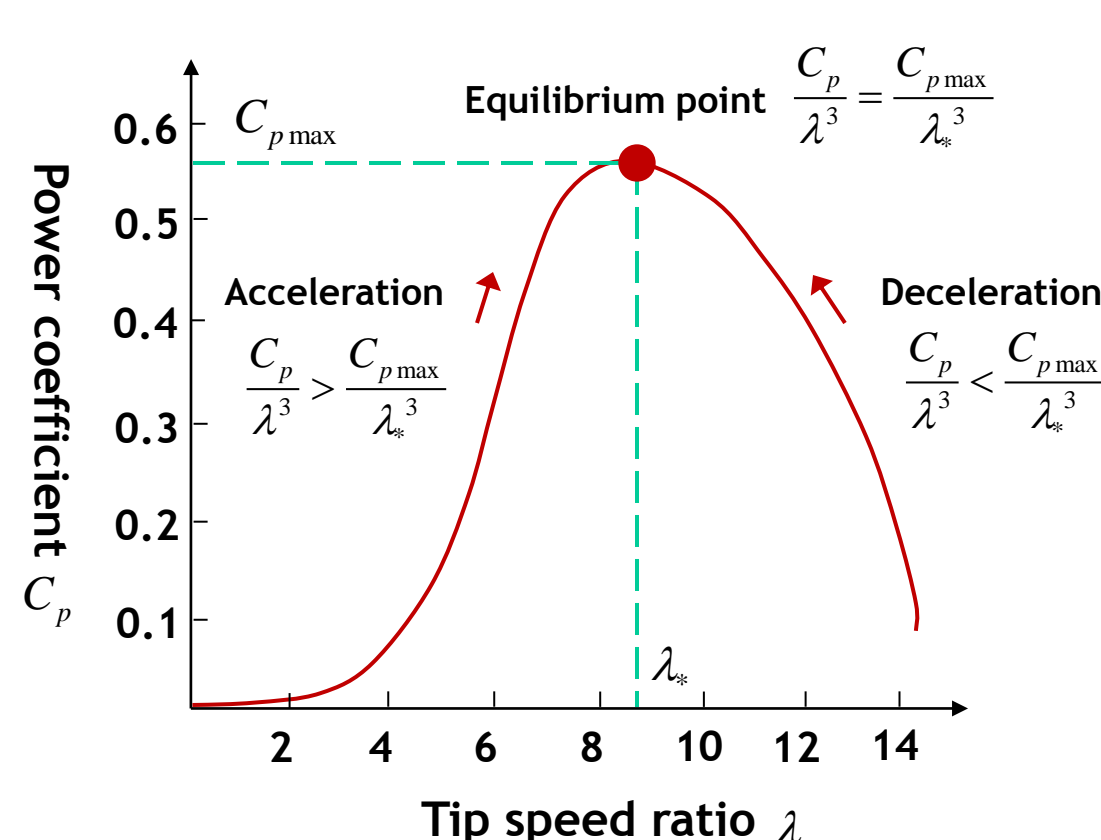
$$\lambda = \frac{\omega_{rotor} R}{v_{wind}}$$

• The objective of a controller design in region 2 is to make the rotor always work at the optimal TSR, which allows for maximum wind energy captured.

• To maintain the optimal TSR, the rotor speed needs to be adjusted in real-time given the different input wind speeds.

Control Strategy

• A control law for region 2 operation is to let the control torque (rotor shaft reacting torque) be given by



$$\tau_c = K \omega_{rotor}^2$$

where the gain K is given by

$$K = \frac{1}{2} \rho A R^3 \frac{C_{p,max}}{\lambda_0^3}$$

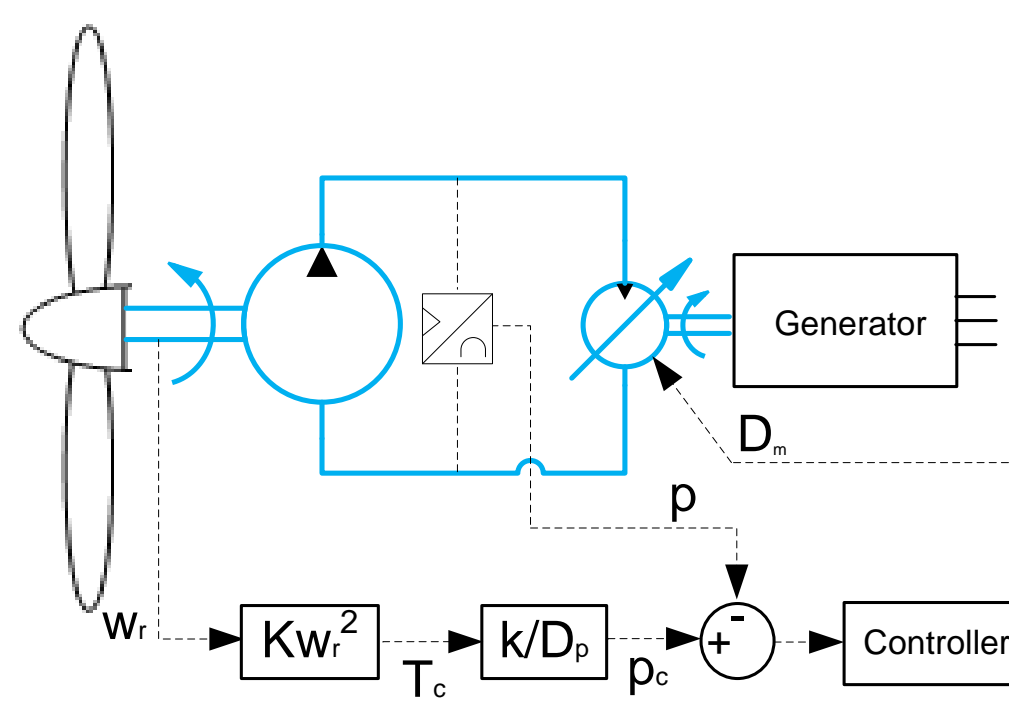
The rotor dynamic equation

$$\dot{\omega} = \frac{1}{J} (\tau_{aero} - \tau_c)$$

$$= \frac{\rho A R^3 \omega^2}{2J} \left(\frac{C_p}{\lambda^3} - \frac{C_{p,max}}{\lambda_0^3} \right)$$

• For hydrostatic wind turbine, the control strategy is to convert control torque command to pressure command, which is governed by

$$P_c = \tau_c \cdot \frac{\eta_p}{D_p}$$

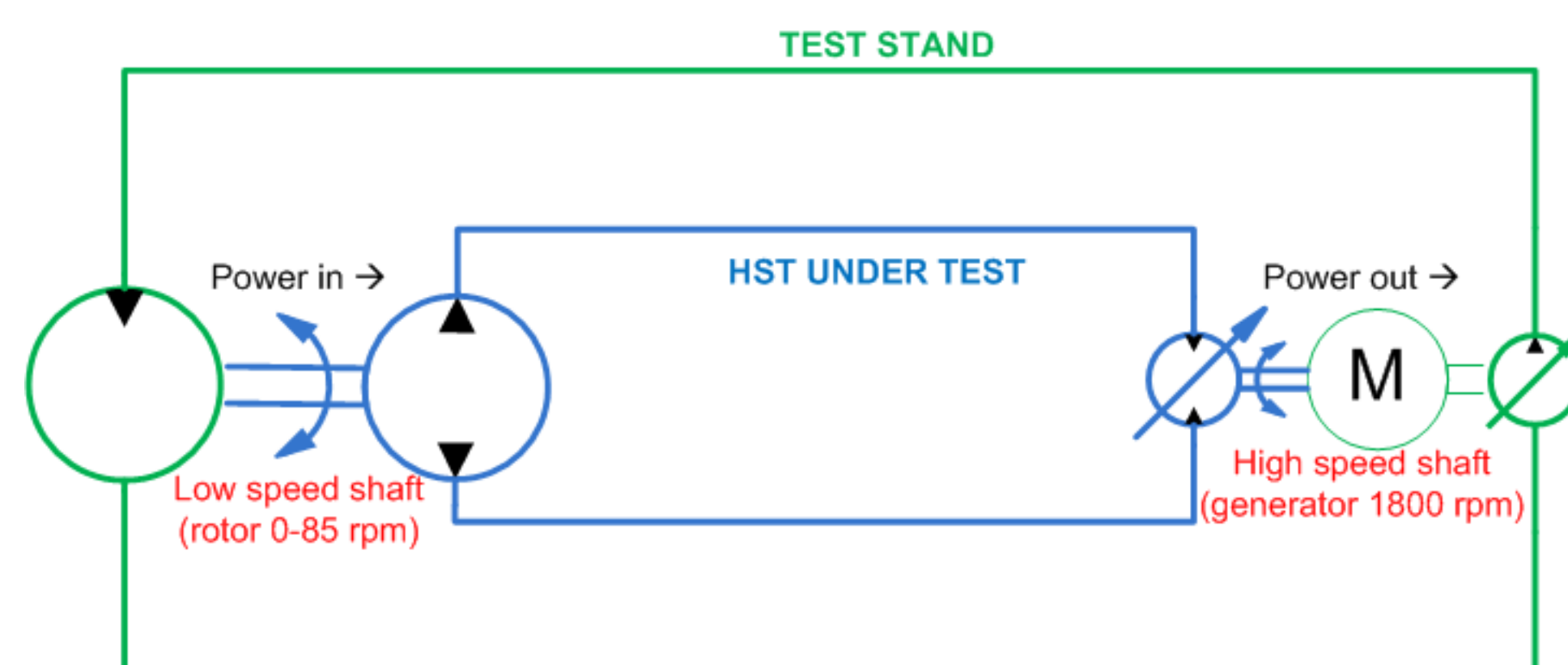


Test Stand

• In order to run repeatable tests to analyze system design and control strategy options, a test stand is being built to replicate wind turbine loads in the laboratory

• 80,000 \$ worth of in kind hardware donations and 10,000\$ in cash donations have been sanctioned by collaborating industries

• The test stand is regenerative, so it consumes less power than what is applied during testing



Simulation Results

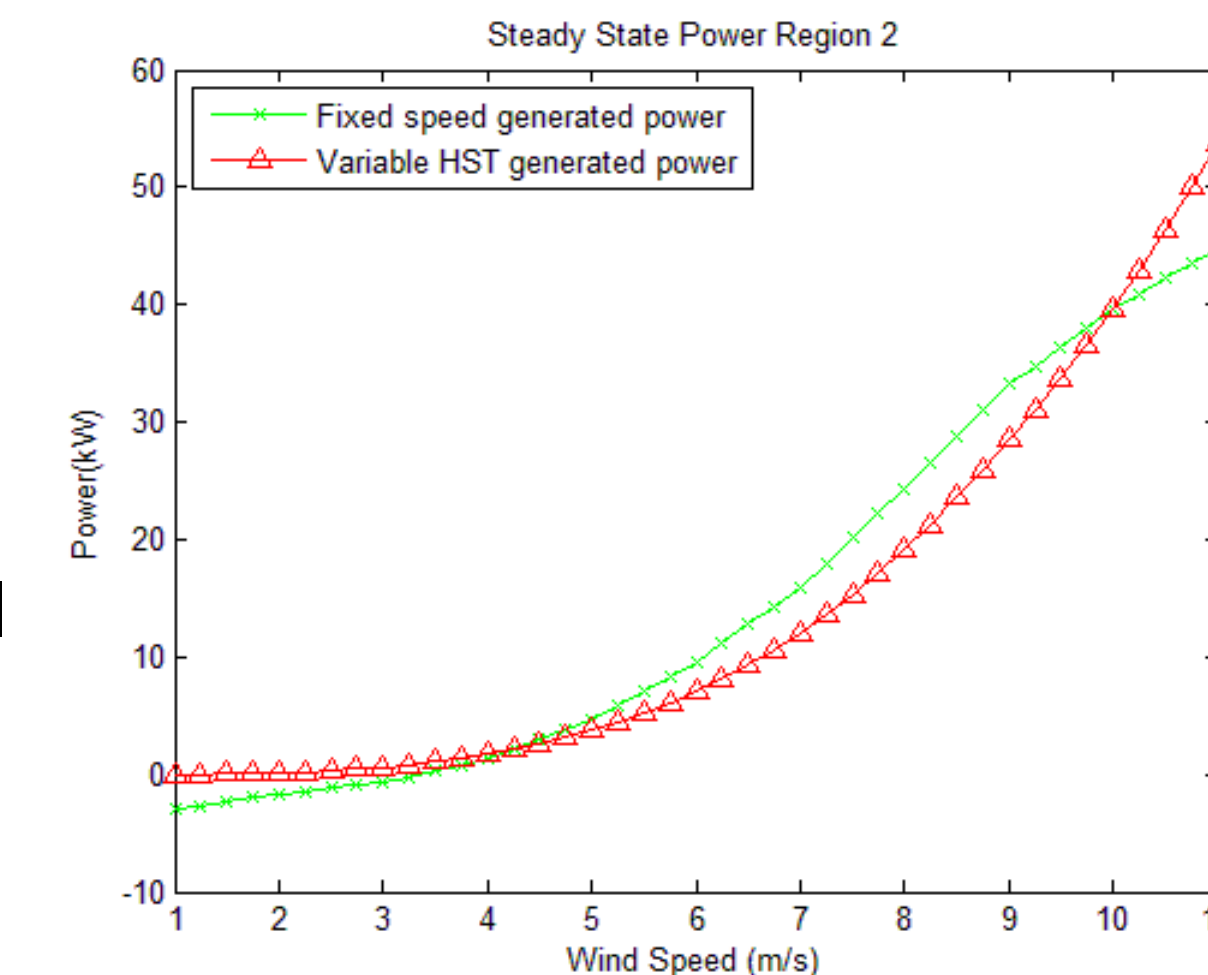
• Simulations were conducted by interfacing NREL's NWTC design code softwares with Matlab/Simulink model of continuously variable hydrostatic transmission

• AOC 15/50 50KW fixed speed turbine was chosen as a baseline turbine for this investigation

• HST using typical components modeled and simulated to steady state for range of wind speed through region 2

• Variable HST with typical component efficiencies compared with a fixed speed gearbox

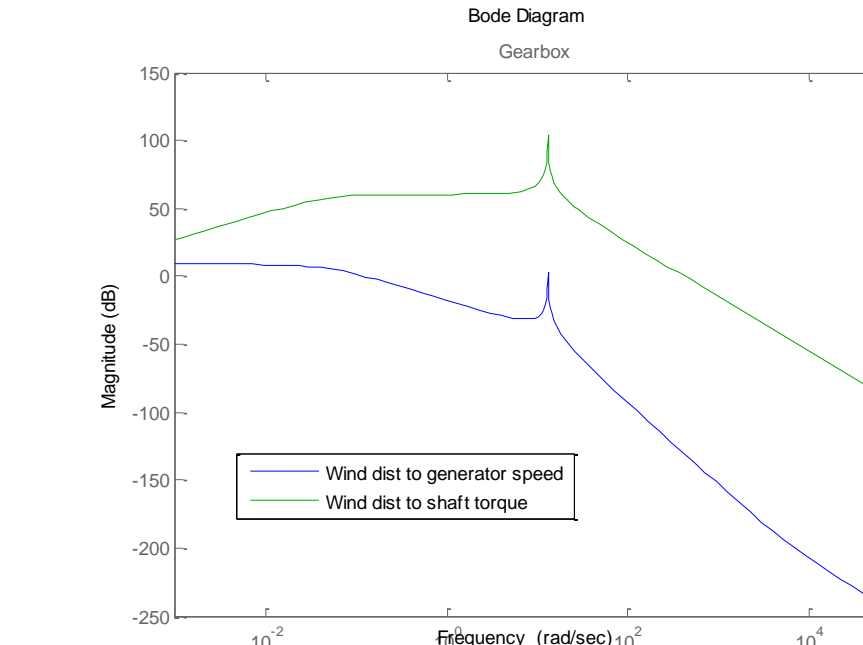
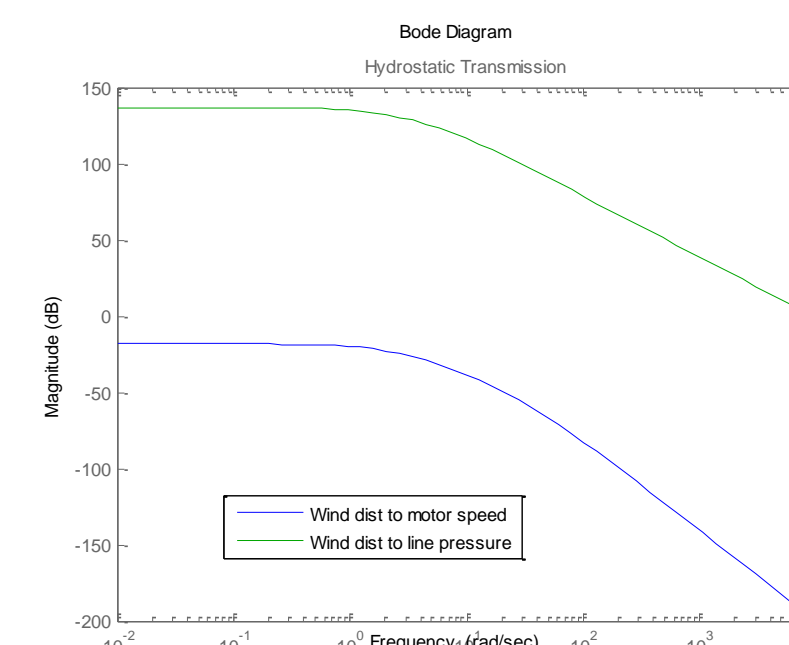
• Economic analysis conducted at University of Minnesota Morris indicate that HST technology is commercially viable given a capacity factor greater than 34.3%, which is achievable



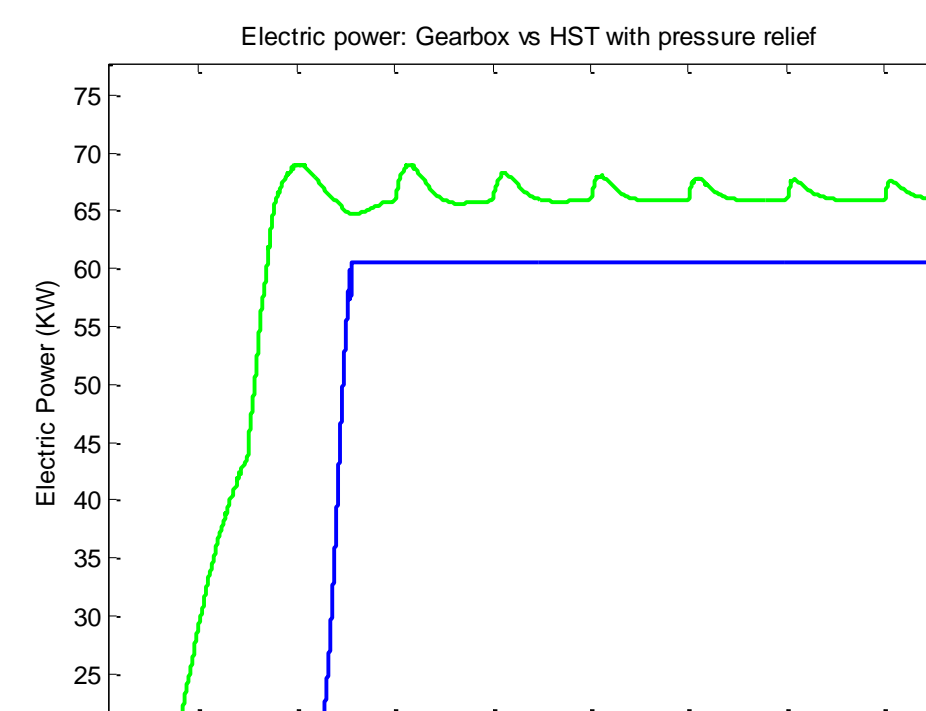
Efficiency and Profitability



• Inherent damping of HST provides smoother output torque than a rigid gearbox in dynamic conditions



• Use of pressure relief valve could make it possible to produce smoother power output for near or above rated turbulent wind conditions



Next Steps

• Develop advanced controls to optimize power generation by analyzing trade-offs between aerodynamic and mechanical efficiency

• Investigate tandem pump/motor configurations to eliminate low-efficiency displacement requirements and explore storage ideas to capture more energy

• Currently we are working on a DOE grant with a major hydraulic company and a leading wind turbine manufacturer to develop HST for off shore wind turbine applications

Industry and university collaborators

