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Evaluation of Multivariate Exponentially  
Weighted Moving Average Control  
Charts**

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## A Program for Design and Performance Evaluation of Multivariate Exponentially Weighted Moving Average Control Charts

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The in-control and out-of-control performance of the traditional multivariate exponentially weighted control charts is a function of a number of parameters – the dimensionality, the in-control target average run length, the weighting scheme and the non-centrality of the shifted data. This dependence on four parameters makes the provision of printed tables a daunting task. When one goes beyond the simple diagonal-weighting scheme, this list is extended to include the covariance matrix of the data and the weighting matrix, turning an already difficult task into a practical impossibility. The program addresses this difficulty by allowing the user to specify the design parameters. It then uses simulation to estimate the control limit that gives the target in-control ARL, and estimates the out-of-control ARL. Its execution on standard desktop computers is sufficiently fast to make experimentation with design choices easy.

### The general multivariate exponentially-weighted moving average chart.

Suppose that a process yield a vector of measurements that that follows a multivariate  $N(\mu, \Sigma)$  distribution. The full exponentially weighted moving average (FEWMA) chart is defined by Choi, Lee and Hawkins (2002) by the recursion

$$\begin{aligned} \mathbf{y}_0 &= \mathbf{0} \\ \mathbf{y}_n &= \mathbf{R}(\mathbf{x}_n - \mu) + (\mathbf{I} - \mathbf{R})\mathbf{y}_{n-1} \end{aligned}$$

Writing  $\Sigma_n$  for the covariance matrix of  $\mathbf{y}_n$ , we compute the squared Mahalanobis distance

$$D_n = \mathbf{y}_n' \Sigma_n^{-1} \mathbf{y}_n$$

and signal if  $D_n$  exceeds a control limit  $h$ .

Lowry *et al* (1992) first discussed multivariate exponentially weighted moving average control charts. In their definition, they restricted the weight matrix  $\mathbf{R}$  to be a multiple of the identity matrix,  $\mathbf{R} = r\mathbf{I}$ . While this choice certainly simplifies working with the multivariate EWMA by

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reducing the necessary design choices on  $\mathbf{R}$  to that of the single scalar  $r$ , doing so reduces the performance that could be obtained from a more general form. For example, Choi *et al* (2002) argue that extending  $\mathbf{R}$  to the form  $\mathbf{R} = a\mathbf{I} + b\mathbf{J}$  where  $\mathbf{J}$  is a matrix of 1's can lead to appreciably faster response to a shift in mean.

For all  $n$ ,  $y_n$  follows a multivariate normal distribution with mean vector  $\mu$ . Its covariance matrix is given recursively as

$$\begin{aligned}\Sigma_0 &= \mathbf{0}, \\ \Sigma_n &= \mathbf{R}\Sigma_{n-1}(\mathbf{I} - \mathbf{R})' + \mathbf{R}\Sigma_{n-1}\mathbf{R}'\end{aligned}$$

As  $n$  increases, this covariance matrix tends to an asymptotic 'steady state' form, provided the eigenvalues of  $\mathbf{R}$  lie between 0 and 1, as is generally the case. This steady state form is given by the system of linear equations

$$\Sigma_\infty - (\mathbf{I} - \mathbf{R})\Sigma_\infty(\mathbf{I} - \mathbf{R})' = \mathbf{R}\Sigma_\infty\mathbf{R}'$$

There are two average run lengths (ARL's) that are of interest. The 'initial state' ARL assumes that the monitoring of  $D_n$  begins with the very first observation. The 'steady state' ARL assumes that the monitoring does not begin until the FEWMA has run long enough for the covariance matrix of  $y_n$  is effectively at its steady state value  $\Sigma_\infty$ .

### Program operation

Analytical results for the ARL of the FEWMA do not appear to be to hand, and so the program operates by simulation. It has two modes of operation – the design mode is used to get the control limit  $h$  needed to give the target in-control ARL. The program also finds the out-of-control ARL at a user-specified shift in the mean vector. The second mode – evaluation – is used when the control limit  $h$  is specified and the ARL is required.

In the design mode a sequence of trial  $h$  values is generated using the Robbins-Monro (R-M) algorithm. In this, we start with some initial value  $h_0$ . After this the successive  $h_k$  values are generated according to the scheme

$$\begin{aligned}\text{Let } r_k &\text{ be the observed length of run } k \text{ using its control limit } h_k. \\ \text{If } r_k < T &\text{ (where } T \text{ is the target ARL), then define } r_{k+1} = r_k * (1 + e^{-1}a/(k+b)) \\ \text{If } r_k > T &\text{ then define } r_{k+1} = r_k * (1 - (1 - e^{-1})a/(k+b))\end{aligned}$$

The tuning constants  $a$  and  $b$  are set to 5 and 100 respectively, values that were reached after some experimentation but that are certainly not immutable.

The R-M algorithm as described would commonly be used to estimate the  $h$  having  $T$  as its upper  $(1 - e^{-1})$  fractile – the sequence  $h_k$  converges to this fractile. To the extent that the run length distribution can be approximated by a large-mean geometric distribution (which is quite close to the truth in the null case) this fractile would correspond to the  $h$  giving an ARL of  $T$ . For our purposes though, the main virtue of the R-M algorithm does not lie in this property, but rather in the fact that it produces a sequence of different  $h_k$  values that cluster around the required  $h$ . We then use this sequence of  $(h_k, r_k)$  values to fit the linear regression

$$r_k = \beta_0 + \beta_1 h_k + e_k$$

where  $e_k$  is a zero-mean error term.

The required  $h$  is then found by solving

$$T = b_0 + b_1 h$$

where  $b_0$  and  $b_1$  are the least squares estimates of the intercept and slope respectively.

An approximate 95% confidence interval for  $h$  is found by solving for the values of  $h$  at which  $T$  will be on the upper and the lower edge of the 95% confidence band for the true regression line:-

$$T = b_0 + b_1 h \pm 2 \sqrt{\frac{1}{K} + \frac{(h - \bar{h})^2}{(K-1)s^2}} \quad (*)$$

where  $K$  is the number of  $(h, r)$  pairs used in the calibration, and  $\bar{h}$  and  $s$  are the mean and standard deviation respectively of the  $h$  values.

In a design phase, the out-of-control ARL is estimated in a similar way, by regressing the observed out-of-control run lengths on the trial control limits  $h_k$  and evaluating this regression line at the estimated  $h$ . The approximate 95% confidence interval for the out-of-control case is given by using the confidence interval (\*) for this regression.

Estimating the ARL for a given  $h$  is done in a more conventional way. Data are simulated and the run lengths measured. The average is reported along with a two standard error band as the approximate confidence interval. Usually this mode will be used following a design run to investigate the out-of-control performance of the chart for different shifts, but there is nothing to prevent its use for looking at the null case for a fixed  $h$  by setting the shift vector equal to zero.

The heart of the code is the generation of sequences of random  $N(\mathbf{0}, \Sigma)$  vectors. This is done by generating vectors of  $p$  independent  $N(0, 1)$  variables. Multiplying each such vector by the Cholesky triangular factor of  $\Sigma$  then gives a vector with the desired distribution. The random normal generator uses the ratio/rejection method outlined on page 313 of Ripley (1983) (but note that Ripley's equations 2a and 2b have the rejection inequality reversed).

### Initial state or steady state

The recursive equations for the FEWMA given in the introduction implicitly define the initial state FEWMA. If the steady state is to be evaluated, then the initial  $y_0$  is sampled randomly from the steady-state distribution rather than being set to zero. Whether the initial state or steady state is used, the out-of-control ARL is estimated by adding the shift in the mean vector from the first simulated data vector onward.

### Data required

The program operates by interrogating the keyboard for its input. This information is:-

1. The dimensionality of the problem
2. The covariance matrix of the vectors  $x_n$

3. The smoothing matrix  $\mathbf{R}$ . As implemented, the program uses  $\mathbf{R}$  of the form  $a\mathbf{I}+b\mathbf{J}$ , and parameterizes this by two constants  $r$  and  $c$ . The constant  $r$  defines the total weight given to the current data vector, and  $c$  defines how this weight is to be shared between the diagonal and off-diagonal elements of  $\mathbf{R}$ . Specifically

$$a = \frac{r(1-c)}{1+(p-1)c}, \quad b = \frac{cr}{1+(p-1)c}, \quad \text{where } p \text{ is the dimensionality of the data.}$$

Setting  $c = 0$  gives the diagonal EWMA defined by Lowry *et al* (1992).

4. Whether the situation to be simulated is a initial state or steady state
5. Whether the run is a design run to estimate  $h$  and out-of-control performance, or an evaluation run to estimate out-of-control performance of a specified scheme.
6. If the former, then the in-control ARL must be provided
7. If the latter, then the value of  $h$  must be provided
8. The vector of the shifts in the mean vector in going to the out-of-control state
9. The number of runs to simulate.
10. Two integer seeds for the random number generator. If the same seeds are provided on different runs, the identical results will be obtained.

**Example and timing.**

We illustrate with an example testing the benefit to be got from off-diagonal weights in the  $\mathbf{R}$  matrix. This is of an 8-component measurement vector with all correlations equal to 0.8. Two runs were made. In both, the diagonal elements of  $\mathbf{R}$  were set to 0.1. In one, the off-diagonal elements were set to zero, giving the Lowry *et al* DEWMA; in the other the off-diagonal elements were set to 0.1.

The chart is designed for an in-control ARL of 300, and the out-of-control performance evaluated for a shift of 0.25 in the first two components and 0 in the other components. We chose the settings  $r = 0.06$ , so that the most recent observation vector is given a weight of 0.06 and the history a weight of 0.94, and  $c = 0.75$ , so that three quarters of the total weight is given to the off-diagonal elements of the vector. The output from the program (which includes an echo of the inputted answer to the keyboard queries) follows. The information supplied by the user is italicized.

```
Program to find the control limit for the
general multivariate EWMA and/or its performance
Give the number of dimensions
```

```
8
What r and c values do you want to use?
```

```
0.060 0.750
```

```
Now give the elements of the covariance matrix
(you only need to give the lower triangle)
```

```
1.000
0.800 1.000
0.800 0.800 1.000
0.800 0.800 0.800 1.000
0.800 0.800 0.800 0.800 1.000
0.800 0.800 0.800 0.800 0.800 1.000
0.800 0.800 0.800 0.800 0.800 0.800 1.000
0.800 0.800 0.800 0.800 0.800 0.800 0.800 1.000
```

Do you want initial state or steady state?

Initial state

Steady state covariance matrix

0.0257	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255
0.0255	0.0257	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255
0.0255	0.0255	0.0257	0.0255	0.0255	0.0255	0.0255	0.0255
0.0255	0.0255	0.0255	0.0257	0.0255	0.0255	0.0255	0.0255
0.0255	0.0255	0.0255	0.0255	0.0257	0.0255	0.0255	0.0255
0.0255	0.0255	0.0255	0.0255	0.0255	0.0257	0.0255	0.0255
0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0257	0.0255
0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0257

Do you want to find h or do you already know it?

(answer Yes to get h or No to do the OOC ARL)

Yes - get h and OOC ARL

What is the null ARL?

300.

Now give the vector of shifts in the mean

0.2500 0.2500 0.0000 0.0000 0.0000 0.0000 0.0000 0.0000

This gives root noncentrality 0.688

DEWMA steady state noncentrality 3.913

FEWMA steady state noncentrality 19.756

How many runs do you want simulated?

10000

Give two integer seeds less than 30000

30 40

Empiric steady-state covariance matrix

0.0257	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255
0.0255	0.0257	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255
0.0255	0.0255	0.0257	0.0255	0.0255	0.0255	0.0255	0.0255
0.0255	0.0255	0.0255	0.0257	0.0255	0.0255	0.0255	0.0255
0.0255	0.0255	0.0255	0.0255	0.0257	0.0255	0.0255	0.0255
0.0255	0.0255	0.0255	0.0255	0.0255	0.0257	0.0255	0.0255
0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0257	0.0255
0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0257
0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0255	0.0257

Current EWMA of shift

0.1937	0.1937	0.0188	0.0188	0.0188	0.0188	0.0188	0.0188
--------	--------	--------	--------	--------	--------	--------	--------

Run 1000 h 15.812 IC RL 1019. OOC RL 9.

Estimated h is 15.129 with CI 14.471 15.453

OOO ARL is 13.805 with CI 12.873 14.736

(lines of progress-report output deleted.)

Run 10000 h 15.818 IC RL 27. OOC RL 16.

Estimated h is 15.071 with CI 14.645 15.272

OOO ARL is 13.875 with CI 13.270 14.480

The program reports the steady state covariance matrix of the FEWMA. It lists three non-centrality parameters. The first is the square root of the non-centrality parameter  $(\mu - \mu_0)' \Sigma^{-1} (\mu - \mu_0)$ , where  $\mu_0$  and  $\mu$  represent the in-control and out-of-control mean vectors respectively. It also gives the asymptotic FEWMA noncentrality parameter  $(\mu - \mu_0)' \Sigma_c^{-1} (\mu - \mu_0)$  which predicts the FEWMA's ability to respond to small shifts in the direction given. The DEWMA noncentrality parameter is the corresponding figure for the diagonal EWMA with the same  $r$ . The relative magnitude of the DEWMA and FEWMA noncentralities indicates the benefit of using a non-zero  $c$ .

The program gives intermediate 'progress reports', 8 of which have been deleted from the transcript but whose format is the same as the last three lines shown. These show the most recent trial  $h$  and its in-control and out-of-control run lengths, along with the current estimates of  $h$  and the out-of-control ARL along with 95% approximate confidence intervals, which could be used to terminate the run early if the user thought the current estimates were good enough.

This run took 210 seconds on a 400 MHz Pentium computer. Note that the approximation obtained in about 20 seconds computing simulating 1000 runs was already adequate for exploratory design purposes, an illustration of how using the program makes exploration of the design choices quick and easy.

Another run with  $c = 0$  and all other parameters unchanged shows the comparative performance of the diagonal EWMA of Lowry *et al.* The out-of-control ARL of the two schemes was estimated as:

Full matrix EWMA	13.9
Diagonal EWMA	22.9

The run length using the restricted diagonal weighting matrix was 50% higher than that using the more general form, showing a substantial benefit from using a full weighting matrix  $R$ .

The program can also be checked against Table 2 of Lowry *et al.* Our reconstruction of that table (along with confidence intervals) is:-

$\lambda$		p			
		2	3	4	
0.5	r	0.06	0.06	0.06	
	h	7.876 ± 0.028	9.982 ± 0.032		
	OOA ARL	25.49 ± 0.15	28.37 ± 0.17	30.52 ± 0.19	
1.0	r	0.16	0.16	0.14	
	h	9.411 ± 0.030	11.659 ± 0.030	13.417 ±	
	OOA ARL	9.614 ± 0.05	10.78 ± 0.06	11.46 ± 0.06	
1.5	r	0.24	0.22	0.20	
	h	9.898 ± 0.027	12.063 ± 0.024	13.927 ± 0.030	
	OOA ARL	5.26 ± 0.03	5.81 ± 0.03	6.21 ± 0.03	
2.0	r	0.34	0.30	0.28	
	h	10.209 ± 0.025	12.372 ± 0.027	14.322 ± 0.036	
	OOA ARL	3.42 ± 0.02	3.80 ± 0.02	4.03 ± .02	

These values are close to those of Lowry *et al.*, though their values do not, for the most part, lie within the confidence intervals given by FEWMA. However as no precision is given with the Lowry *et al.* table, it is impossible to say whether the two sets of results agree to within random sampling fluctuations.

### Language and code

The code for FEWMA was written in FORTRAN 77 to make it as widely useful as possible. Self-contained source is an appendix to this report.

### References

Choi, S., Lee, S., and Hawkins, D. M. (2002) 'A General Multivariate Exponentially Weighted Moving Average Control Chart' Technical report 640, School of Statistics, University of Minnesota.

Lowry, C.A., Woodall, W.H., Champ, C.W. and Rigdon, S.E. (1992), 'A Multivariate Exponentially Weighted Moving Average Control Chart,' *Technometrics*, 34, 46-53.

Ripley, B. D., (1983), 'Computer generation of random variables: A tutorial', *International Statistical Review*, 51, 301—319.

### Appendix Fortran 77 FEWMA source code

```

      program fewma
c
c      Fortran 77 program to find the in-control and out-of-control
c      ARL of a general multivariate exponentially weighted moving
c      average chart.

      implicit double precision (a-h,o-z)
      parameter (maxnor = 10, maxpar=55)
      dimension sigma(maxnor,maxnor), gmsig(maxnor,maxnor),
1 sig1(maxnor,maxnor), rmat(maxnor,maxnor), rbar(maxnor,maxnor),
2 prod(maxnor,maxnor), gminv(maxnor,maxnor+2),
3 facsig(maxnor,maxnor), sigold(maxnor,maxnor),
4 dew(maxpar), work(maxpar), data(maxnor), delta(maxnor),
5 work2(maxpar), steds1(maxpar,maxpar+2), facstd(maxnor,maxnor),
6 dewd1(maxnor), work3(maxpar), work4(maxpar)
      character*60 filnam
      write(*,*) 'Program to find the control limit for the '
      write(*,*) 'general multivariate EWMA and/or its performance'
      write(*,1001) 'Give the name of the file to write results'
      read(*,'(a)') filnam
      open(11,file=filnam)
      write(11,*) ' Program to find the control limit for the '
      write(11,*) 'general multivariate EWMA and/or its performance'
      write(*,1001) 'Give the number of dimensions'
1001 format(1x,a/)

```



```

      read(*,*) nord
      write(11,1001) 'Give the number of dimensions'
      write(11,*) nord
      npar = nord * (nord+1) / 2
      call dorest(sigma,gmsig,sig1,rmat,rbar,prod,gminv,dew,work,
1 work2,work3,work4,
1 dewd1,facsig,facstd,stedsl,sigold,data,delta,nord,npar)
      end

      subroutine dorest(sigma,gmsig,sig1,rmat,rbar,prod,gminv,dew,work,
1 work2,work3,work4,
1 dewd1,facsig,facstd,stedsl,sigold,data,delta,nord,npar)
      implicit double precision (a-h,o-z)
      dimension sigma(nord,nord),gmsig(nord,nord),sig1(nord,nord),
1 rmat(nord,nord),rbar(nord,nord),prod(nord,nord),
2 gminv(nord,nord+2),dew(npar),work(npar),sigold(nord,nord),
3 facsig(nord,nord),data(nord),delta(nord),work2(npar),
4 work3(npar),work4(npar),
5 dewd1(nord),stedsl(npar,npar+2),facstd(nord,nord)

      logical steady,whchmt,over,gotin,gotout,echo,design,tripper
      character answer

      data zero/0.d0/, one /1.d0/, two /2.d0/, four /4.d0/,
1 half /0.5d0/numfac/ 5.d0/, denfac/100.d0/,einv/0.368d0/,
2 oneein/0.632d0/

      write(*,1001) 'What r and c values do you want to use?'
1001 format(1x,a/)
      read(*,*) r, c
      write(*,'(2f8.3)') r, c
      write(11,1001) 'What r and c values do you want to use?'
      write(11,'(2f8.3)') r, c
      fnord = nord
      den = one + (fnord - one) * c
      od = r * c / den
      write(*,*) 'Now give the elements of the covariance matrix'
      write(*,1001) '(you only need to give the lower triangle)'
      write(11,*) 'Now give the elements of the covariance matrix'
      write(11,*) '(you only need to give the lower triangle)'
      ai = r / den - od
      do 10 i = 1, nord
        write(*,*) ' Row',i,': '
        read(*,*) (sigma(i,j),j=1,i)
        write(11,'(10f8.3)') (sigma(i,j),j=1,i)
        rmat(i,i) = r / den
        rbar(i,i) = one - r / den
        do 10 j = 1, i-1
          sigma(j,i) = sigma(i,j)
          rmat(i,j) = od
          rmat(j,i) = od
          rbar(i,j) = -od
          rbar(j,i) = -od
10      continue
c
c      Get R sigma R'
c
      do 30 i = 1, nord
        do 30 j = 1, nord
          sum = zero

```

```

        do 40 k = 1, nord
            sum = sum + sigma(i,k) * rmat(j,k)
40         continue
        prod(i,j) = sum
30     continue

    do 50 i = 1, nord
        do 50 j = 1, nord
            sum = zero
            do 60 k = 1, nord
                sum = sum + rmat(i,k) * prod(k,j)
60         continue
            sig1(i,j) = sum
50     continue

c
c     Get triangular factor of sigma
c
    call matfac(sigma,facsig,nord)

write(* ,1001) 'Do you want initial state or steady state?'
write(11,1001) 'Do you want initial state or steady state?'
read(*,'(a)') answer
steady = answer .eq. 'S' .or. answer .eq. 's'
if (steady) then
    write(11,*) ' Steady state'
else
    write(11,*) ' Initial state'
endif

c
c     Get asymptotic covariance matrix
c
    nravl = 0
    do 510 i = 1, nord
        do 510 j = i, nord
            nravl = nravl + 1
            do 520 k = 1, npar
520         steds1(nravl,k) = zero
            steds1(nravl,nravl) = one
            work3(nravl) = sig1(i,j)
            work4(nravl) = zero
            mravl = 0
            do 530 k = 1, nord
                mravl = mravl + 1
                steds1(nravl,mravl) = steds1(nravl,mravl) - rbar(i,k) * rbar(j,k)
                do 530 m = k+1, nord
                    mravl = mravl + 1
                    steds1(nravl,mravl) = steds1(nravl,mravl) - rbar(i,k) *
1             rbar(j,m) - rbar(i,m) * rbar(j,k)
530         continue
510     continue

    echo = .false.
    call solve(steds1,work3,work4,work,work2,npar,echo)
    nravl = 0
    write(11,'(/' ' Steady state covariance matrix' ')')
    do 540 i = 1, nord
        do 550 j = i, nord
            nravl = nravl + 1
            gmsig(i,j) = work(nravl)

```

```

    gmsig(j,i) = work(nrav1)
550    continue
    write(11,'(8f9.4)') (gmsig(i,j),j=1,nord)
540    continue

    call matfac(gmsig,facstd,nord)

write(*,*) 'Do you want to find h or do you already know it?'
write(*,1001) '(answer Yes to get h or No to do the OOC ARL)'
read(*,'(a)') answer
design = answer .eq. 'Y' .or. answer .eq. 'y'
write(11,*) ' Do you want to find h or do you already know it?'
write(11,*) '(answer Yes to get h or No to do the OOC ARL)'
if (design) then
    write(11,*) ' Yes - get h and OOC ARL'
    baseh = fnord
    write(*,1001) ' What is the null ARL?'
    read(*,*) tararl
    write(11,1001) ' What is the null ARL?'
    write(11,'(f10.0)') tararl
    else
    write(11,*) ' No - I have h, just get the OOC ARL'
    write(*,1001) ' What is the in-control h?'
    write(11,*) ' What is the in-control h?'
    read(*,*) baseh
    write(11,'(f10.3)') baseh
    endif
write(*,1001) 'Now give the vector of shifts in the mean'
write(11,1001) 'Now give the vector of shifts in the mean'
read(*,*) (delta(i),i=1,nord)
write(11,'(10f8.4)') (delta(i),i=1,nord)

c
c  Get noncentrality
c
    sumdel = zero
do 890 i = 1, nord
890    sumdel = sumdel + delta(i)
do 880 i = 1, nord
880    work3(i) = ai * delta(i) + od * sumdel
    flam = zero
    flamz = zero
do 900 i = 1, nord
    sum = delta(i)
    sumz = delta(i)
do 910 j = 1, i-1
    sum = sum - facsig(i,j) * work(j)
    sumz = sumz - facstd(i,j) * work2(j)
910    continue
    work(i) = sum / facsig(i,i)
    work2(i) = sumz / facstd(i,i)
    flam = flam + work(i) ** 2
    flamz = flamz + work2(i) ** 2
900    continue
    flam = sqrt(flam)
write(*, '(' This gives root noncentrality ',f9.3)') flam
write(11, '(' This gives root noncentrality ',f9.3)') flam
dflam = flam * sqrt((two - r) / r)
write(*, '(' DEWMA steady state noncentrality',f9.3)') dflam
write(11, '(' DEWMA steady state noncentrality',f9.3)') dflam
    flamz = sqrt(flamz)

```

```

write(11, '(' FEWMA steady state noncentrality', f9.3)') flamz
write(*, '(' FEWMA steady state noncentrality', f9.3)') flamz
c
write(*, 1001) 'How many runs do you want simulated?'
write(11, 1001) 'How many runs do you want simulated?'
read(*, *) nrun
write(11, *) nrun
write(*, 1001) 'Give two integer seeds less than 30000'
read(*, *) ij, kl
write(11, 1001) 'Give two integer seeds less than 30000'
write(11, '(2i7)') ij, kl
ngap = nrun / 10
write(*, *) '.....Run starting.....'
c
tripper = .not. steady

xbar = zero
ybar = zero
ssx = zero
ssy = zero
sxy = zero
fn = zero
xbaro = zero
ybaro = zero
ssxo = zero
ssyo = zero
sxyo = zero
fno = zero
over = .false.
echo = .false.
do 20 irun = 1, nrun

do 600 i = 1, nord
  dew(i) = zero
  dewdl(i) = zero
600 continue

if (.not. steady) then
  do 610 i = 1, nord
    do 610 j = 1, nord
610 sigold(i, j) = zero
  endif

run = zero
tsqmax = zero
gotin = .not. design
gotout = .false.

c
c Loop point for generating new case
c
70 continue
run = run + one
if (run .gt. 50000) then
  write(*, *) 'Seems to be stuck. run', run, ' h', baseh, ' tsq',
1 tsq, ' tsqmax', tsqmax, ' t2sq', t2sq
  write(*, 1002) 'gmsig', gmsig
  write(*, 1002) 'gminv', gminv
  write(*, 1002) 'data', (data(ii), ii=1, nord)

```

```

        write(*,1002) 'dew', (dew(ii),ii=1,nord)
        write(*,1002) 'delta', (delta(ii),ii=1,nord)
        write(*,1002) 'work ', (work(ii),ii=1,nord)
        write(*,1002) 'work2', (work2(ii),ii=1,nord)
1002    format(/1x,a,(10g14.7))
        echo = .true.
    endif

c
c    Transform data
c
    innerc = 0
    whchmt = steady .and. run .lt. 1.1
680    continue
    call randn(data,nord,ij,kl)
    if (whchmt) call randn(dew,nord,ij,kl)
    do 640 i = 1, nord
        work2(i) = dew(i)
640    work(i) = data(i)
    do 620 i = 1, nord
        data(i) = zero
        if (whchmt) dew(i) = zero
        do 620 j = 1, nord
            if (whchmt) dew(i) = dew(i) + facstd(i,j) * work2(j)
            data(i) = data(i) + facsig(i,j) * work(j)
620    continue
    if (whchmt .and. over) then

c
c    Make sure a steady state run starts out in control
c
    innerc = innerc + 1
    if (innerc .gt. 100) then
        write(*,*) '100 tries to get a steady state start have failed'
        stop
    endif
    do 660 i = 1, nord
        dewdl(i) = zero
        do 660 j = 1, nord
660    gminv(i,j) = gmsig(i,j)
    call solve(gminv,dew,dewdl,work,work2,nord,echo)
    tsq = zero
    do 670 i = 1, nord
        tsq = tsq + dew(i) * work(i)
670    if (tsq .gt. baseh) then
        if (innerc .gt. 10) write(*,(' T squared, h, EWMA',i5,
1    (8f8.3))) tsq, baseh, (dew(i),i=1,nord)
        go to 680
        endif
    endif

c
    do 90 i = 1, nord
        work(i) = dew(i)
        work2(i) = dewdl(i)
        dew(i) = zero
        dewdl(i) = zero
90    continue
    do 95 i = 1, nord
        do 95 j = 1, nord
            dew(i) = dew(i) +rmat(i,j)*data(j) +rbar(i,j)*work(j)
            dewdl(i) = dewdl(i)+rmat(i,j)*delta(j)+rbar(i,j)*work2(j)
95    continue

```

```

    if (.not. steady) then
      do 80 i = 1, nord
        do 80 j = 1, nord
          gmsig(i,j) = sig1(i,j)
          sum = zero
          do 700 k = 1, nord
            700   sum = sum + sigold(i,k) * rbar(k,j)
          prod(i,j) = sum
        80   continue
      do 100 i = 1, nord
        do 100 j = 1, nord
          do 100 k = 1, nord
            100   gmsig(i,j) = gmsig(i,j) + rbar(i,k) * prod(k,j)
          endif
        do 110 i = 1, nord
          do 110 j = 1, nord
            sigold(i,j) = gmsig(i,j)
            110   gminv(i,j) = gmsig(i,j)

    if (tripper .and. run .gt. 500) then
      tripper = .false.
      write(11,*) ' Empiric steady-state covariance matrix'
      do 760 i = 1, nord
        760   write(11,'(8f10.4)') (gmsig(i,j),j=1,nord)
      write(11,*) ' and EWMA of shift'
      write(11,'(8f10.4)') (dewdl(i),i=1,nord)
      endif

    if (echo) write(*,*) ' dew', dew, ' dewdl',dewdl

    call solve(gminv,dew,dewdl,work,work2,nord,echo)
    tsq = zero
    t2sq = zero
    do 130 i = 1, nord
      tsq = tsq + dew(i) * work(i)
      t2sq = t2sq + (dew(i) - dewdl(i)) * (work(i) - work2(i))
    130   continue
    tsqmax = max(tsq,tsqmax)

    if (.not. gotin) then
      if (tsq .gt. baseh .or. run .gt. 50002) then

        gotin = .true.
        runic = run
        y = (run)
        x = baseh

        corrf = numfac / (float(irun) + denfac)
        if (run .lt. tararl) then
          baseh = baseh * (one + einv * corrf)
        else
          baseh = baseh * (one - oneein * corrf)
        over = .true.
        endif
        if (.not. over) go to 20
        devx = x - xbar
        devy = y - ybar
        fnl = fn + one

```

```

        xbar = xbar + devx / fnl
        ybar = ybar + devy / fnl
        ratio = fn / fnl
        ssx = ssx + ratio * devx ** 2
        ssy = ssy + ratio * devy ** 2
        sxy = sxy + ratio * devx * devy
        fn = fnl
    endif
endif
if (.not. gotout) then
    if (t2sq .gt. baseh .or. run .gt. 50002) then
        runooc = run
        gotout = .true.
        x = baseh
        y = run
        devx = x - xbaro
        devy = y - ybaro
        fnol = fno + one
        xbaro = xbaro + devx / fnol
        ybaro = ybaro + devy / fnol
        ssxo = ssxo + fno * devx ** 2 / fnol
        ssyo = ssyo + fno * devy ** 2 / fnol
        sxyo = sxyo + fno * devx * devy / fnol
        fno = fnol
    endif
endif
if (.not. (gotin .and. gotout)) go to 70
if (mod(irun,ngap) .ne. 0) go to 20

if (design) then
103  write(*,103) irun,baseh,runic,runooc
    format(' Run',i8,' h',f8.3,' IC RL',f8.0,' OOC RL',f8.0)
    write(11,103) irun,baseh,runic,runooc
    slope = sxy / ssx
    cut = ybar - slope * xbar
    resvar = (ssy - sxy**2 / ssx) / (fn - two)
    comter = four * resvar / ssx
    tarlog = tararl
    ater = slope ** 2 - comter
    bter = two * (slope * (cut - tarlog) + comter * xbar)
    cter = (cut - tarlog) ** 2 - four * resvar * (one / fn +
1  xbar ** 2 / ssx)
    predh = (tarlog - cut) / slope
    disc = bter ** 2 - four * ater * cter

    if (disc .lt. zero) then
        write(*,101) predh
        write(11,101) predh
    else
        disc = sqrt(disc)
        alow = (-bter - disc) / (two * ater)
        ahi = (-bter + disc) / (two * ater)
        write(*,101) predh,alow,ahi
        write(11,101) predh,alow,ahi
    endif
101  format(' Estimated h is',f9.3,:', ' with CI',2f9.3)
    endif

if (design) then
    slopeo = sxyo / ssxo

```

```

    cuto = ybaro - slopeo * xbaro
    resvro = (ssyo - sxyo**2 / ssxo) / (fno - two)
    predo = cuto + slopeo * predh
    seo = sqrt(resvro * (one / fno + (predh - xbaro) ** 2 / ssxo))
    write(*,102) predo,predo-two*seo,predo+two*seo
    write(11,102) predo,predo-two*seo,predo+two*seo
102  format(' OOC ARL is',f9.3,' with CI',2f9.3/)

    else

    seo = sqrt(ssyo / (fno * (fno - one)))
    write(*,104) irun,ybaro, ybaro-two*seo, ybaro+2*seo
104  format(' Run',i7,' OOC ARL is',f9.3,' with CI',2f9.3/)
    write(11,104) irun,ybaro, ybaro-two*seo, ybaro+2*seo
    endif
20  continue
    return
    end

subroutine solve(a,y1,y2,x1,x2,nord,echo)
c
c  Subroutine to solve a system of linear equations for two right sides
c
    implicit double precision (a-h,o-z)
    dimension a(nord,nord+2),x1(nord),x2(nord),y1(nord),y2(nord)
    logical echo
    do 10 i = 1, nord
        a(i,nord+1) = y1(i)
        a(i,nord+2) = y2(i)
        if (echo) write(*,'(' B4'',(8f10.4)')' ) (a(i,j),j=1,nord+2)
10    continue
    do 20 i = 1, nord-1
        do 30 j = i+1, nord
            pivot = a(j,i) / a(i,i)
            do 30 k = i, nord+2
                a(j,k) = a(j,k) - a(i,k) * pivot
30        continue
20    continue
    if (echo) write(*,*) 'Solution'
    do 40 i = nord,1,-1
        sum1 = a(i,nord+1)
        sum2 = a(i,nord+2)
        do 50 j = i+1, nord
            sum1 = sum1 - a(i,j) * x1(j)
            sum2 = sum2 - a(i,j) * x2(j)
50        continue
        x1(i) = sum1 / a(i,i)
        x2(i) = sum2 / a(i,i)
40    continue
    if (echo) then
        write(*,'(1x,7f11.5)') x1
        write(*,*)
        write(*,'(1x,7f11.5)') x2
    endif
    echo = .false.
    return
    end

subroutine matfac(sigma,factor,nord)
c

```



```

c      Subroutine to find the lower triangular factor of a symmetric matrix
c
      implicit double precision (a-h,o-z)
      dimension sigma(nord,nord),factor(nord,nord)
      data zero /0.d0/
      factor(1,1) = sqrt(sigma(1,1))
      do 10 i = 2, nord
        do 20 j = 1, i
          sum = zero
          do 30 k = 1, j-1
30          sum = sum + factor(i,k) * factor(j,k)
          if (j .lt. i) then
            factor(i,j) = (sigma(i,j) - sum) / factor(j,j)
            factor(j,i) = zero
          else
            rutarg = sigma(i,i) - sum
            if (rutarg .le. zero) then
              write(11, '(' Error in MATEFAC. Variable',i5,' rutarg',
1              g15.7)') i,rutarg
              write(11,*) ' Matrix'
              write(*, '(' Error in MATEFAC. Variable',i5,' rutarg',
1              g15.7)') i,rutarg
              write(*,*) ' Matrix'
              do 50 k = 1, nord
                write(*, '(10f8.3)') (sigma(k,m),m=1,nord)
50              write(11, '(10f8.3)') (sigma(k,m),m=1,nord)
                write(*,*) ' Factor so far'
                write(11,*) ' Factor so far'
              do 60 k = 1, i
                write(*, '(10f8.3)') (factor(k,m),m=1,k)
60              write(11, '(10f8.3)') (factor(k,m),m=1,k)
                rutarg = abs(rutarg)
              endif
              factor(i,i) = sqrt(rutarg)
            endif
          endif
        20 continue
      10 continue
      return
      end

      subroutine randn(x,nord,ij,kl)

c
c      Subroutine to produce a vector of pseudorandom N(0,1) values
c      It calls ranmar to get random uniforms
c
      parameter(nuni=200)
      implicit double precision (a-h,o-z)
      dimension x(nord),work(nuni)
      save work,index
      data index/nuni/, quart/0.25d0/, half/0.5d0/, one/1.d0/,
1 zero /0.d0/, cons/1.71552777d0/, c/0.259d0/, onep/-0.350927217d0/
      do 10 i = 1, nord
20      index = index + 2
          if (index .gt. nuni-1) then
            call ranmar(work,nuni,ij,kl)
            index = 1
          endif
          u = work(index)
          if (u .eq. zero) then
            u = 1.d-10
          endif
        10 continue
      end

```

```

        endif
        v = cons * (work(index+1) - half)
        x(i) = v / u
        z = quart * x(i) ** 2
        if (z .gt. one - u) then
            if (z .gt. c / u - onep) go to 20
            if (z .gt. -log(u)) go to 20
        endif
10     continue
    return
end

subroutine ranmar(rvec, len, ij, kl)
c     this is the random number generator proposed by george marsaglia in
c     florida state university report: fsu-scri-87-50
c     it was slightly modified by f. james to produce an array of
pseudorandom
c     numbers.
    implicit double precision(a-h,o-z)
    dimension rvec(*), u(97)
    integer i97, j97
    logical test
    save test, i97, j97, c, cd, cm, u
    data test /.false./
    integer ivec

    if( .not. test ) then
c this is the initialization routine for the random number generator
ranmar()
c note: the seed variables can have values between:      0 <= ij <= 31328
c                                                         0 <= kl <= 30081
c the random number sequences created by these two seeds are of sufficient
c length to complete an entire calculation with. for example, if several
c different groups are working on different parts of the same calculation,
c each group could be assigned its own ij seed. this would leave each group
c with 30000 choices for the second seed. that is to say, this random
c number generator can create 900 million different subsequences -- with
c each subsequence having a length of approximately 10^30.
c
c use ij = 1802 & kl = 9373 to test the random number generator. the
c subroutine ranmar should be used to generate 20000 random numbers.
c then display the next six random numbers generated multiplied by
4096*4096
c if the random number generator is working properly, the random numbers
c should be:
c         6533892.0  14220222.0  7275067.0
c         6172232.0  8354498.0   10633180.0

        i = mod(ij/177, 177) + 2
        j = mod(ij      , 177) + 2
        k = mod(kl/169, 178) + 1
        l = mod(kl,    169)

    do 2 ii = 1, 97
        s = 0.0
        t = 0.5
        do 3 jj = 1, 24
            m = mod(mod(i*j, 179)*k, 179)
            i = j
            j = k

```

```

      k = m
      l = mod(53*l+1, 169)
      if (mod(l*m, 64) .ge. 32) then
        s = s + t
      endif
      t = 0.5 * t
3     continue
2     u(ii) = s
      continue

      c = 362436.0 / 16777216.0
      cd = 7654321.0 / 16777216.0
      cm = 16777213.0 / 16777216.0

      i97 = 97
      j97 = 33

      test = .true.
      endif

do 100 ivec = 1, len
  uni = u(i97) - u(j97)
  if( uni .lt. 0.0 ) uni = uni + 1.0
  u(i97) = uni
  i97 = i97 - 1
  if(i97 .eq. 0) i97 = 97
  j97 = j97 - 1
  if(j97 .eq. 0) j97 = 97
  c = c - cd
  if( c .lt. 0.0 ) c = c + cm
  uni = uni - c
  if( uni .lt. 0.0 ) uni = uni + 1.0
  rvec(ivec) = uni
100 continue
return
end
```