

# Toward a stochastic description of reheating

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Based on [1705.????], with

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H. Xie (U. Wisconsin)



RICE



Congratulations!

(and thank you for the invitation)

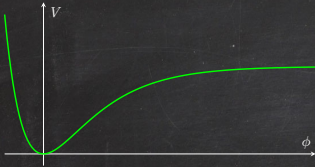


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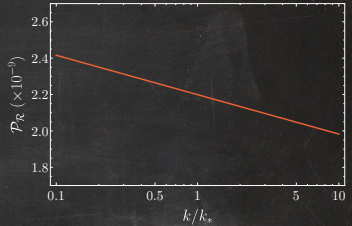
- Motivation
- Stochastic Particle Production
- Exact Results
- Conclusion

# Motivation

All you need to drive inflation ( $a \sim e^{Ht}$ ) is a scalar field,

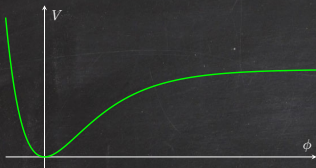


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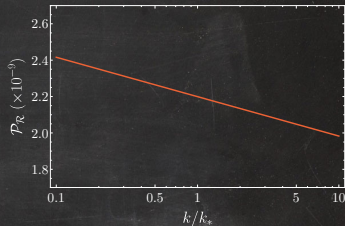


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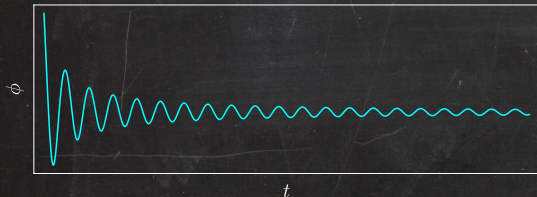
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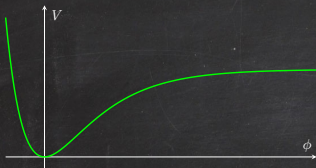


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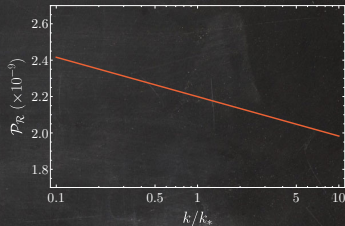


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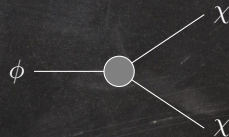
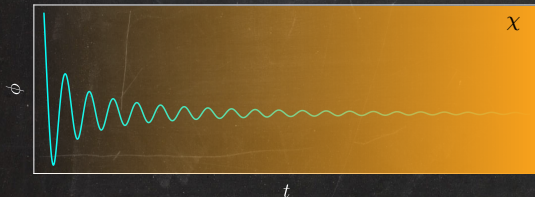
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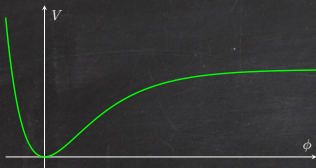


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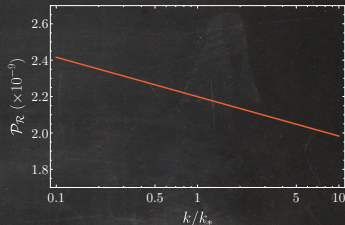


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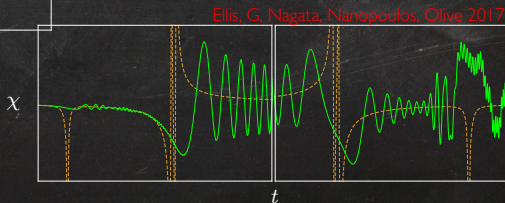
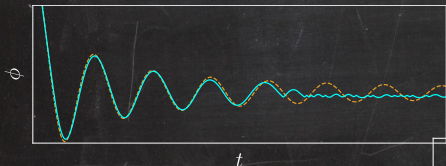
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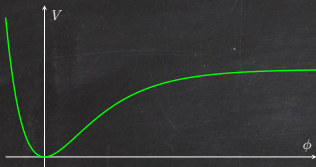


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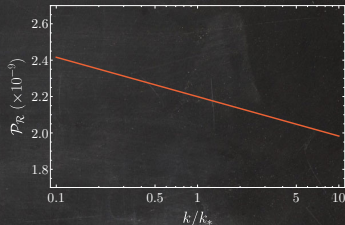


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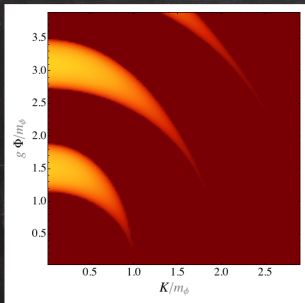


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Amin, Hertzberg, Kaiser, Karouby 2015



$$\left[ \mathbb{1} \left( \partial_\tau^2 + (k/a)^2 \right) + \mathbf{p}(\tau) \partial_\tau + \mathbf{m}(\tau) \right] \cdot \delta\chi = 0$$

$$(\mathbf{p})_b^a = 2\Gamma_{bc}^a \phi^{c'} + 3H\delta_b^a$$

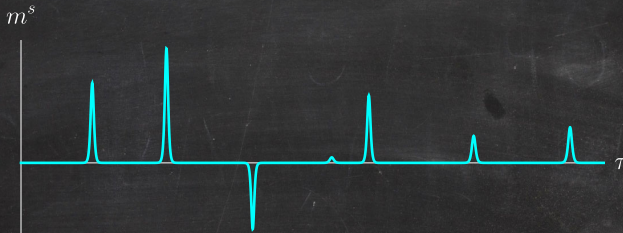
$$(\mathbf{m})_b^a = (G^{ac} V_{,c})_{,b} + \Gamma_{cd,b}^a \phi^{c'} \phi^{d'}$$



# Stochastic Particle Production

Consider  $N_f$  coupled (scalar) fields. Assume the evolution of fluctuations contains localized non-adiabatic events with random strengths at random intervals, and that the fields are otherwise free

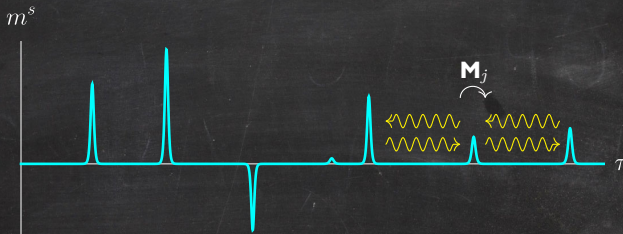
$$\left[ \mathbb{1} \partial_\tau^2 + \omega^2 + \mathbf{m}^s(\tau) \right] \cdot \chi(\tau, \mathbf{k}) = 0, \quad \omega_a^2 = k^2 + m_a^2$$



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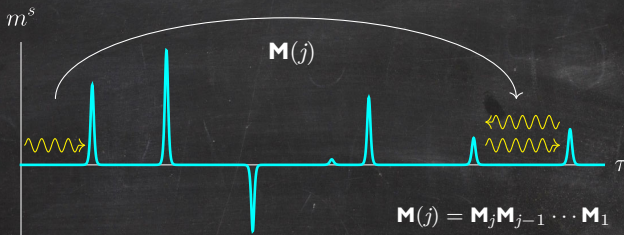
After the  $j$ -th event,

$$\chi_j^a(\tau) \equiv \frac{1}{\sqrt{2\omega_a}} \left[ \beta_j^a e^{i\omega_a \tau} + \alpha_j^a e^{-i\omega_a \tau} \right], \quad \begin{pmatrix} \beta_j \\ \alpha_j \end{pmatrix} = \mathbf{M}_j \begin{pmatrix} \beta_{j-1} \\ \alpha_{j-1} \end{pmatrix}$$

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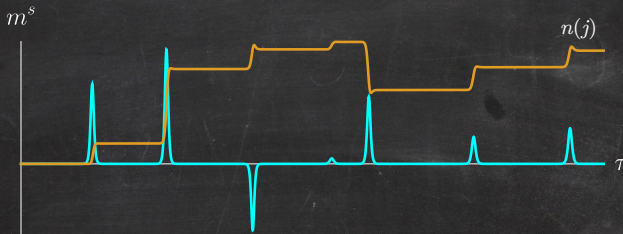
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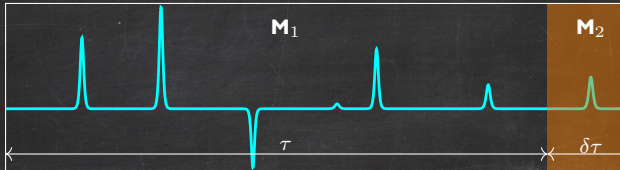


A random walk (with drift) for the occupation number

$$n_a(j) = \frac{1}{2\omega_a} \left( |\dot{\chi}_j^a|^2 + \omega_a^2 |\chi_j^a|^2 \right) - \frac{1}{2} = |\beta_j^a|^2$$

Randomness and non-adiabaticity are encoded in  $\mathbf{M}$ .

A probability distribution can be defined,  $P(\mathbf{M}; \tau)$



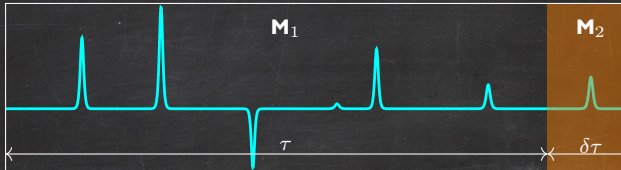
If the processes in the  $\tau$  and  $\delta\tau$  strips are uncorrelated, the distribution for  $\mathbf{M} \equiv \mathbf{M}_2\mathbf{M}_1$  satisfies

$$P(\mathbf{M}; \tau + \delta\tau) = \int d\mu(\mathbf{M}_2) P(\mathbf{M}_2^{-1}\mathbf{M}; \tau) P(\mathbf{M}_2; \delta\tau)$$

$\Rightarrow$  Markovian evolution.

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$\Rightarrow$  Markovian evolution. Moreover, as  $\delta\tau/\tau \rightarrow 0$ ,

$$\partial_\tau P(\mathbf{M}; \tau) = -\partial_{\mathbf{M}} \left[ \frac{\langle \delta \mathbf{M} \rangle_{\mathbf{M}_2}}{\delta\tau} P(\mathbf{M}; \tau) \right] + \frac{1}{2!} \partial_{\mathbf{M}}^2 \left[ \frac{\langle \delta \mathbf{M}^2 \rangle_{\mathbf{M}_2}}{\delta\tau} P(\mathbf{M}; \tau) \right] + \dots$$

(Fokker-Planck)

A general transfer matrix can be parametrized as

$$\mathbf{M} = \begin{pmatrix} \mathbf{u} & 0 \\ 0 & \mathbf{u}^* \end{pmatrix} \begin{pmatrix} \sqrt{1+\mathbf{n}} & \sqrt{\mathbf{n}} \\ \sqrt{\mathbf{n}} & \sqrt{1+\mathbf{n}} \end{pmatrix} \begin{pmatrix} \mathbf{v} & 0 \\ 0 & \mathbf{v}^* \end{pmatrix}$$

where  $\mathbf{u}, \mathbf{v} \in U(N_f)$ , and  $\mathbf{n} = \text{diag}(n_1, n_2, \dots) \Rightarrow N_f(2N_f + 1)$  variables in FP equation!

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Late-time equilibrium  $\Rightarrow$  maximal entropy

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### The Maximum Entropy Ansatz

Assume the building block  $P$  maximizes the Shannon entropy

$$S[P] = - \int P(\mathbf{M}_2; \delta\tau) \ln P(\mathbf{M}_2; \delta\tau) d\mu(\mathbf{M}_2)$$

subject to the constraints:

- The local mean particle production rate is known and fixed,  $\mu_j \equiv \frac{1}{N_f} \frac{\langle n_j \rangle \delta\tau}{\delta\tau}$
- Coarse-grained continuity,  $\mathbf{M}_{\tau+\delta\tau} \xrightarrow{\delta\tau \rightarrow 0} \mathbf{M}_{\tau}$

Consequences (Mello, Pereyra, Kumar 1988; Amin, Baumann 2016):

- 1  $P$  is independent of  $\mathbf{u}$ ,

$$dP(\{\mathbf{u}, \mathbf{n}, \mathbf{v}\}) = P(\{\mathbf{n}, \mathbf{v}\}) d\mu(\mathbf{u})$$

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$$\frac{1}{\mu} \frac{\partial}{\partial \tau} P(n_a; \tau) = \sum_{a=1}^{N_f} \left[ (1 + 2n_a) + \frac{1}{N_f + 1} \sum_{b \neq a} \frac{n_a + n_b + 2n_a n_b}{n_a - n_b} \right] \frac{\partial P}{\partial n_a} + \frac{2}{N_f + 1} \sum_{a=1}^{N_f} n_a (1 + n_a) \frac{\partial^2 P}{\partial n_a^2}$$

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- 3 A closed set of equations for the moments of  $n = \sum_a n_a$  can be obtained. It implies

$$\partial_\tau \langle \ln(1 + n) \rangle \xrightarrow{\tau \rightarrow \infty} \frac{2N_f}{N_f + 1} \mu$$

$$\partial_\tau \text{Var}[\ln(1 + n)] \xrightarrow{\tau \rightarrow \infty} \frac{4}{N_f + 1} \mu$$

i.e. exponential growth for the occupation number

# Exact Results

Consider the approximation

$$m_{ab}^s(\tau) = 2\sqrt{\omega_a\omega_b} \sum_{j=1}^{N_s} \Lambda_{ab}(\tau_j) \delta(\tau - \tau_j),$$

where  $\tau_j$  are uniformly distributed, and

$$\langle \Lambda_{ab} \rangle = 0, \quad \langle \Lambda_{ab} \Lambda_{cd} \rangle = \sigma_{ab}^2 (\delta_{ac} \delta_{bd} + \delta_{ad} \delta_{bc})$$

The transfer matrix takes the form

$$\mathbf{M}_j = \mathbb{1} + i \underbrace{\begin{pmatrix} \mathbf{a}_j^* & 0 \\ 0 & \mathbf{a}_j \end{pmatrix} \begin{pmatrix} \Lambda_j & \Lambda_j \\ -\Lambda_j & -\Lambda_j \end{pmatrix} \begin{pmatrix} \mathbf{a}_j & 0 \\ 0 & \mathbf{a}_j^* \end{pmatrix}}_{\mathbf{m}_j}, \quad \mathbf{a}_j \equiv \text{diag}(e^{i\omega_1\tau_j}, e^{i\omega_2\tau_j}, \dots)$$

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Will focus on the total occupation number. Define  $\mathbf{R} = \mathbf{M}\mathbf{M}^\dagger$ :

$$n(j) = \frac{1}{4} \text{Tr} [\mathbf{M}(j)\mathbf{M}^\dagger(j) - \mathbb{1}] \equiv \frac{1}{4} \text{Tr} [\mathbf{R}(j) - \mathbb{1}]$$

Algorithm:

1 Parametrize  $\mathbf{R}$

$$\mathbf{R} = \begin{pmatrix} \mathbf{u} & 0 \\ 0 & \mathbf{u}^* \end{pmatrix} \begin{pmatrix} \mathbf{f} & \tilde{\mathbf{f}} \\ \tilde{\mathbf{f}} & \mathbf{f} \end{pmatrix} \begin{pmatrix} \mathbf{u}^\dagger & 0 \\ 0 & \mathbf{u}^\top \end{pmatrix}, \quad \begin{aligned} \mathbf{f} &= 2n + 1 \\ \tilde{\mathbf{f}} &= \sqrt{\mathbf{f}^2 - 1} \end{aligned}$$



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- 2 Solve for first and second order perturbations in terms of previous value of  $\mathbf{R}$

$$\mathbf{R}(j+1) = \mathbf{R}(j) + \delta\mathbf{R},$$

$$\delta\mathbf{R} = \mathbf{R}(j)\mathbf{m}_{j+1}^\dagger + \text{h.c.} + \mathbf{m}_{j+1}\mathbf{R}(j)\mathbf{m}_{j+1}^\dagger.$$

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3 Calculate correlators

$$\langle \delta f_a^{(1)} \delta f_b^{(1)} \rangle_{\delta\tau} = 2\tilde{f}_a \tilde{f}_b \sum_{c,d} \sigma_{cd}^2 \left( u_{ac}^\dagger u_{ad}^\dagger u_{cb} u_{db} + u_{bc}^\dagger u_{bd}^\dagger u_{ca} u_{da} \right)$$

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- 4 Write and solve the FP equation

## Single field

Only two parameters,  $f$  and  $u = e^{i\phi}$ . Computation is straightforward,

$$\langle \delta f^{(1)} \delta f^{(1)} \rangle = 2\tilde{f}^2 \sigma^2$$

$$\langle \delta f^{(1)} \delta \phi^{(1)} \rangle = 0$$

$$\langle \delta \phi^{(1)} \delta \phi^{(1)} \rangle = \frac{\sigma^2}{2\tilde{f}^2} (2\tilde{f}^2 + f^2)$$

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The FP equation is

$$\frac{1}{\sigma^2} \frac{\partial}{\partial \tau} P(f; \tau) = \frac{\partial}{\partial f} \left[ (f^2 - 1) \frac{\partial}{\partial f} P(f; \tau) \right]$$

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$$\langle \delta \phi^{(1)} \delta \phi^{(1)} \rangle = \frac{\sigma^2}{2\tilde{f}^2} (2\tilde{f}^2 + f^2)$$

No  $\phi$  dependence!  $\Rightarrow$  maximum entropy

The FP equation is

$$\frac{1}{\sigma^2} \frac{\partial}{\partial \tau} P(n; \tau) = \frac{\partial}{\partial n} \left[ n^2 \frac{\partial}{\partial n} P(n; \tau) \right]$$

## Single field

Only two parameters,  $f$  and  $u = e^{i\phi}$ . Computation is straightforward,

$$\langle \delta f^{(1)} \delta f^{(1)} \rangle = 2\tilde{f}^2 \sigma^2$$

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with solution

$$P(n; \tau) dn = \frac{1}{\sqrt{4\pi\sigma^2\tau}} \exp \left[ -\frac{(\ln n - \sigma^2\tau)^2}{4\sigma^2\tau} \right] d \ln n$$



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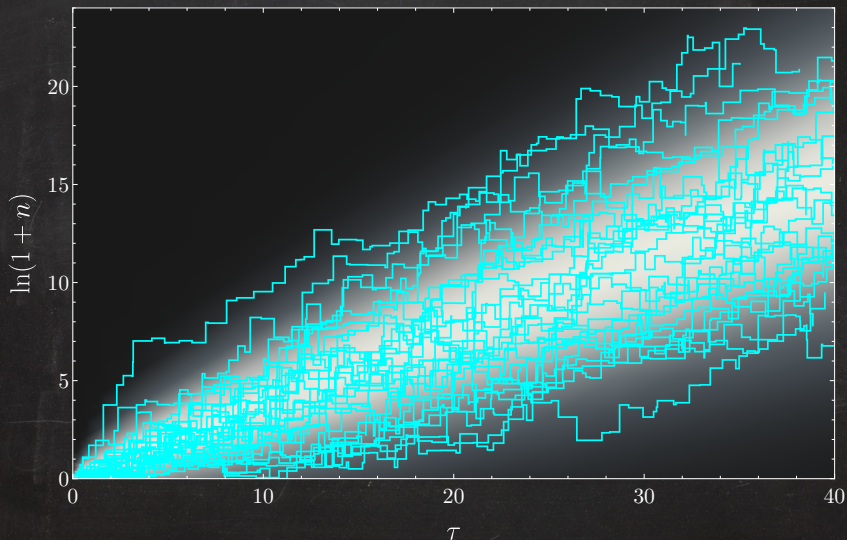
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$$\Rightarrow n = e^{\sigma^2\tau} - 1$$



## Two fields

Six parameters now,  $f_1, f_2$  and

$$\mathbf{u}(\phi, \theta, \psi, \varphi) = e^{-\frac{i}{2}\phi} \begin{bmatrix} \cos \frac{\theta}{2} e^{-\frac{i}{2}(\varphi+\psi)} & -\sin \frac{\theta}{2} e^{-\frac{i}{2}(\varphi-\psi)} \\ \sin \frac{\theta}{2} e^{\frac{i}{2}(\varphi-\psi)} & \cos \frac{\theta}{2} e^{\frac{i}{2}(\varphi+\psi)} \end{bmatrix}$$

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$\Rightarrow$  need 27 correlators

Let

$$\langle (\Lambda_{11})^2 \rangle_{\delta\tau} = \sigma_1^2, \quad \langle (\Lambda_{22})^2 \rangle_{\delta\tau} = \sigma_2^2, \quad \langle (\Lambda_{12})^2 \rangle_{\delta\tau} = \langle (\Lambda_{21})^2 \rangle_{\delta\tau} = \sigma_{\perp}^2.$$

## Two fields

Six parameters now,  $f_1, f_2$  and

$$\mathbf{u}(\phi, \theta, \psi, \varphi) = e^{-\frac{i}{2}\phi} \begin{bmatrix} \cos \frac{\theta}{2} e^{-\frac{i}{2}(\varphi+\psi)} & -\sin \frac{\theta}{2} e^{-\frac{i}{2}(\varphi-\psi)} \\ \sin \frac{\theta}{2} e^{\frac{i}{2}(\varphi-\psi)} & \cos \frac{\theta}{2} e^{\frac{i}{2}(\varphi+\psi)} \end{bmatrix}$$

\(\Rightarrow\) need 27 correlators

$$\langle \delta f_1^{(1)} \delta f_1^{(1)} \rangle = \tilde{f}_1^2 \gamma_1(\theta),$$

$$\langle \delta f_1^{(1)} \delta f_2^{(1)} \rangle = 2\tilde{f}_1 \tilde{f}_2 \cos(2\psi) \gamma_2(\theta),$$

$$\langle \delta f_1^{(1)} \delta \theta^{(1)} \rangle = -\frac{2\tilde{f}_1}{\Delta Y} [\tilde{f}_1 + \tilde{f}_2 \cos(2\psi)] \gamma_3(\theta),$$

$$\langle \delta f_1^{(1)} \delta \psi^{(1)} \rangle = -\tilde{f}_1 \sin(2\psi) \left( \frac{\tilde{f}_2}{\tilde{f}_1} \gamma_3(\theta) - 2\frac{\tilde{f}_1}{\Delta Y} \gamma_4(\theta) \cot \theta \right),$$

$$\langle \delta f_1^{(1)} \delta \varphi^{(1)} \rangle = -2\frac{\tilde{f}_1 \tilde{f}_2}{\Delta Y} \sin(2\psi) \gamma_5(\theta) \csc \theta,$$

$$\langle \delta f_1^{(1)} \delta \rho^{(1)} \rangle = \tilde{f}_1 \frac{\tilde{f}_2}{\tilde{f}_1} \sin(2\psi) \gamma_6(\theta),$$

$$\langle \delta f_2^{(1)} \delta f_2^{(1)} \rangle = \tilde{f}_2^2 \gamma_1(\theta),$$

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$$\langle \delta f_2^{(1)} \delta \rho^{(1)} \rangle = -\tilde{f}_2 \frac{\tilde{f}_1}{\tilde{f}_2} \sin(2\psi) \gamma_6(\theta),$$

$$\langle \delta \theta^{(1)} \delta \theta^{(1)} \rangle = 2\sigma_1^2 + \frac{1}{\Delta F} (\tilde{f}_1 + \tilde{f}_2 + 2\tilde{f}_1 \tilde{f}_2 \cos(2\psi)) \gamma_7(\theta),$$

$$\langle \delta \theta^{(1)} \delta \psi^{(1)} \rangle = \frac{1}{\Delta Y} \left[ \frac{\tilde{f}_1 \tilde{f}_2}{\tilde{f}_1} \gamma_8(\theta) + \frac{\tilde{f}_2 \tilde{f}_1}{\tilde{f}_2} \gamma_9(\theta) \right] \sin(2\psi) - \cot \theta \langle \delta \theta^{(1)} \delta \varphi^{(1)} \rangle,$$

$$\langle \delta \theta^{(1)} \delta \varphi^{(1)} \rangle = \frac{2\tilde{f}_1 \tilde{f}_2 \sin(2\psi)}{\Delta F} \gamma_5(\theta) \csc \theta,$$

$$\langle \delta f_1^{(2)} \rangle = \frac{1}{\Delta Y} [\tilde{f}_1^2 \gamma_1(\theta) - (\tilde{f}_1 \tilde{f}_2 - 1) \gamma_3(\theta)],$$

$$\langle \delta \theta^{(1)} \delta \varphi^{(1)} \rangle = \frac{1}{4\Delta Y} \left[ \left( \tilde{f}_1 \frac{\tilde{f}_2}{\tilde{f}_1} - \tilde{f}_2 \frac{\tilde{f}_1}{\tilde{f}_2} \right) (\sigma_1^2 - \sigma_2^2) \sin \theta + 4 \left( \tilde{f}_1 \frac{\tilde{f}_2}{\tilde{f}_1} + \tilde{f}_2 \frac{\tilde{f}_1}{\tilde{f}_2} \right) \sin(2\psi) \right],$$

$$\langle \delta \psi^{(1)} \delta \psi^{(1)} \rangle = \frac{1}{4} \left[ \left( \frac{\tilde{f}_1}{\tilde{f}_2} \right)^2 \gamma_1(\theta) + \left( \frac{\tilde{f}_2}{\tilde{f}_1} \right)^2 \gamma_2(\theta) \right] - \frac{\tilde{f}_1 \tilde{f}_2}{\Delta Y} \left[ \sigma_1^2 + \sigma_2^2 + 2 \sin^2 \theta \sigma_1^2 - \cos \theta \left( 2 \langle \delta \psi^{(1)} \delta \varphi^{(1)} \rangle + \cos \theta \langle \delta \varphi^{(1)} \delta \varphi^{(1)} \rangle \right) \right],$$

$$\langle \delta \psi^{(1)} \delta \varphi^{(1)} \rangle = -\frac{1}{\Delta Y} \left( \frac{\tilde{f}_1 \tilde{f}_2}{\tilde{f}_1 \tilde{f}_2} \gamma_4(\theta) \right) \left[ \sigma_1^2 + \sigma_2^2 - 3\sigma_1^2 \sin^2 \theta - \cos \theta \langle \delta \varphi^{(1)} \delta \varphi^{(1)} \rangle \right],$$

$$\langle \delta \varphi^{(1)} \delta \varphi^{(1)} \rangle = \frac{1}{4} \left[ \left( \frac{\tilde{f}_1}{\tilde{f}_2} \right)^2 \gamma_1(\theta) + \left( \frac{\tilde{f}_2}{\tilde{f}_1} \right)^2 \gamma_2(\theta) \right] - \frac{\tilde{f}_1 \tilde{f}_2}{\Delta Y} \left[ \sigma_1^2 + \sigma_2^2 - 3\sigma_1^2 \sin^2 \theta - \cos \theta \langle \delta \varphi^{(1)} \delta \varphi^{(1)} \rangle \right],$$



$$\langle \delta \rho^{(1)} \delta \rho^{(1)} \rangle = \frac{1}{4} \left[ \left( \frac{\tilde{f}_1}{\tilde{f}_2} \right)^2 \gamma_1(\theta) + \left( \frac{\tilde{f}_2}{\tilde{f}_1} \right)^2 \gamma_2(\theta) \right] - \frac{\tilde{f}_1 \tilde{f}_2}{\Delta Y} \left[ \sigma_1^2 + \sigma_2^2 + 2 \sin^2 \theta \sigma_1^2 - \cos \theta \left( 2 \langle \delta \rho^{(1)} \delta \varphi^{(1)} \rangle + \cos \theta \langle \delta \varphi^{(1)} \delta \varphi^{(1)} \rangle \right) \right],$$

$$\langle \delta \rho^{(1)} \delta \psi^{(1)} \rangle = \frac{1}{4} \left[ \left( \frac{\tilde{f}_1}{\tilde{f}_2} \right)^2 \gamma_1(\theta) + \left( \frac{\tilde{f}_2}{\tilde{f}_1} \right)^2 \gamma_2(\theta) \right] \cos \theta - \frac{1}{2} \left[ \frac{\tilde{f}_1}{\tilde{f}_2} + \frac{\tilde{f}_2}{\tilde{f}_1} - 2\frac{\tilde{f}_1 \tilde{f}_2}{\tilde{f}_1 \tilde{f}_2} \cos(2\psi) \right] \gamma_3(\theta),$$

$$\langle \delta \rho^{(1)} \delta \varphi^{(1)} \rangle = \frac{1}{4} \left[ \left( \frac{\tilde{f}_1}{\tilde{f}_2} \right)^2 \gamma_1(\theta) + \left( \frac{\tilde{f}_2}{\tilde{f}_1} \right)^2 \gamma_2(\theta) \right] \csc \theta - \frac{1}{2} \sin(2\psi) \left( \sigma_1^2 + \sigma_2^2 - 3\sigma_1^2 \right) + \frac{1}{\Delta Y} \left( \langle \delta \theta^{(1)} \delta \theta^{(1)} \rangle - \langle \delta f_1^{(1)} \delta \theta^{(1)} \rangle \right) + \frac{1}{2} \sin(2\psi) \langle \delta \varphi^{(1)} \delta \varphi^{(1)} \rangle,$$

$$\langle \delta \rho^{(1)} \delta \theta^{(1)} \rangle = \frac{1}{8} \left( \frac{\tilde{f}_1}{\tilde{f}_2} + \frac{\tilde{f}_2}{\tilde{f}_1} \right) \left( \sigma_1^2 + \sigma_2^2 - 2\sigma_1^2 \right) \sin^2 \theta \sin(2\psi) - \frac{1}{2} \left( \frac{\tilde{f}_1}{\tilde{f}_2} \langle \delta f_1^{(1)} \delta \varphi^{(1)} \rangle - \frac{\tilde{f}_2}{\tilde{f}_1} \langle \delta f_2^{(1)} \delta \varphi^{(1)} \rangle \right) - \frac{1}{2} \left( \frac{\tilde{f}_1}{\tilde{f}_2} \langle \delta f_1^{(1)} \delta \psi^{(1)} \rangle + \frac{\tilde{f}_2}{\tilde{f}_1} \langle \delta f_2^{(1)} \delta \psi^{(1)} \rangle \right),$$

$$- \frac{1}{2} \left( \frac{\tilde{f}_1}{\tilde{f}_2} \langle \delta f_1^{(1)} \delta \varphi^{(1)} \rangle + \frac{\tilde{f}_2}{\tilde{f}_1} \langle \delta f_2^{(1)} \delta \varphi^{(1)} \rangle \right) \cos \theta + \frac{1}{2} \sin \theta \langle \delta \theta^{(1)} \delta \varphi^{(1)} \rangle - \cos \theta \langle \delta \varphi^{(1)} \delta \varphi^{(1)} \rangle,$$

$$- \frac{1}{2} \left( \frac{\tilde{f}_1}{\tilde{f}_2} - \frac{\tilde{f}_2}{\tilde{f}_1} \right) \left[ \frac{1}{4} \left( \langle \delta \varphi^{(1)} \delta \varphi^{(1)} \rangle \sin^2 \theta - \langle \delta \theta^{(1)} \delta \theta^{(1)} \rangle \right) \sin 2\psi + \frac{1}{2} \langle \delta \varphi^{(1)} \delta \theta^{(1)} \rangle \sin \theta \cos 2\psi \right],$$

$$\langle \delta \rho^{(2)} \rangle = \frac{1}{\Delta Y} \left( \langle \delta f_2^{(1)} \delta \varphi^{(1)} \rangle - \langle \delta f_1^{(1)} \delta \varphi^{(1)} \rangle \right) - \cot \theta \langle \delta \theta^{(1)} \delta \varphi^{(1)} \rangle,$$

$$\langle \delta \rho^{(2)} \rangle = 0$$

## Two fields

Six parameters now,  $f_1, f_2$  and

$$\mathbf{u}(\phi, \theta, \psi, \varphi) = e^{-\frac{i}{2}\phi} \begin{bmatrix} \cos \frac{\theta}{2} e^{-\frac{i}{2}(\varphi+\psi)} & -\sin \frac{\theta}{2} e^{-\frac{i}{2}(\varphi-\psi)} \\ \sin \frac{\theta}{2} e^{\frac{i}{2}(\varphi-\psi)} & \cos \frac{\theta}{2} e^{\frac{i}{2}(\varphi+\psi)} \end{bmatrix}$$

Solution of full FP equation can be bypassed,

$$\begin{aligned} \partial_\tau \langle \ln(1+n) \rangle &= \left\langle \frac{1}{2(1+n)} \sum_{a=1}^{N_f} \frac{\langle \delta f_a \rangle \delta \tau}{\delta \tau} - \frac{1}{8(1+n)^2} \sum_{a,b=1}^{N_f} \frac{\langle \delta f_a \delta f_b \rangle \delta \tau}{\delta \tau} \right\rangle \\ &\xrightarrow{\tau \rightarrow \infty} \left\langle l(\theta) - \frac{1}{2} \gamma(\theta) \right\rangle \end{aligned}$$

with

$$\begin{aligned} \gamma(\theta) &= 2 \left[ \cos^4 \left( \frac{\theta}{2} \right) \sigma_1^2 + \sin^4 \left( \frac{\theta}{2} \right) \sigma_2^2 + 4 \sin^2 \left( \frac{\theta}{2} \right) \cos^2 \left( \frac{\theta}{2} \right) \sigma_\perp^2 \right] \\ l(\theta) &= 2 \left[ \cos^2 \left( \frac{\theta}{2} \right) \sigma_1^2 + \sin^2 \left( \frac{\theta}{2} \right) \sigma_2^2 + \sigma_\perp^2 \right] \end{aligned}$$

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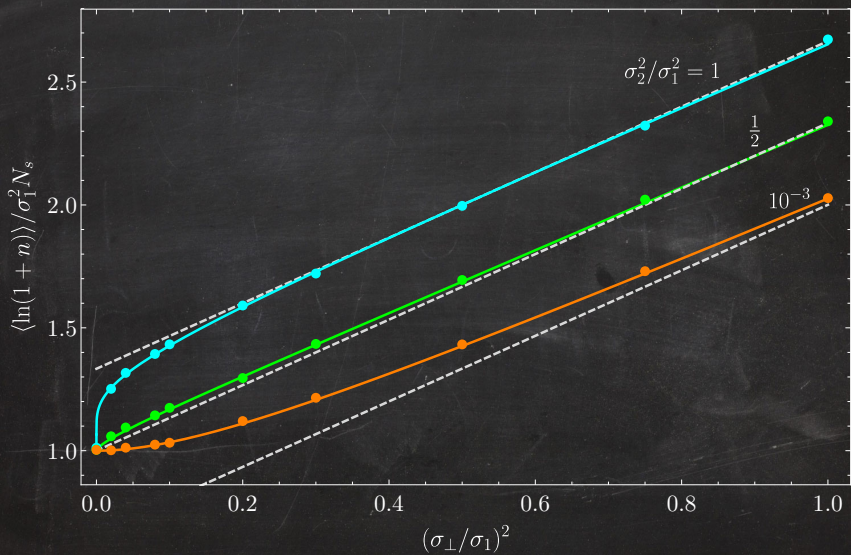
$$\begin{aligned} \partial_\tau \langle \ln(1+n) \rangle &= \left\langle \frac{1}{2(1+n)} \sum_{a=1}^{N_f} \frac{\langle \delta f_a \rangle \delta \tau}{\delta \tau} - \frac{1}{8(1+n)^2} \sum_{a,b=1}^{N_f} \frac{\langle \delta f_a \delta f_b \rangle \delta \tau}{\delta \tau} \right\rangle \\ &\xrightarrow{\tau \rightarrow \infty} \left\langle l(\theta) - \frac{1}{2} \gamma(\theta) \right\rangle \end{aligned}$$

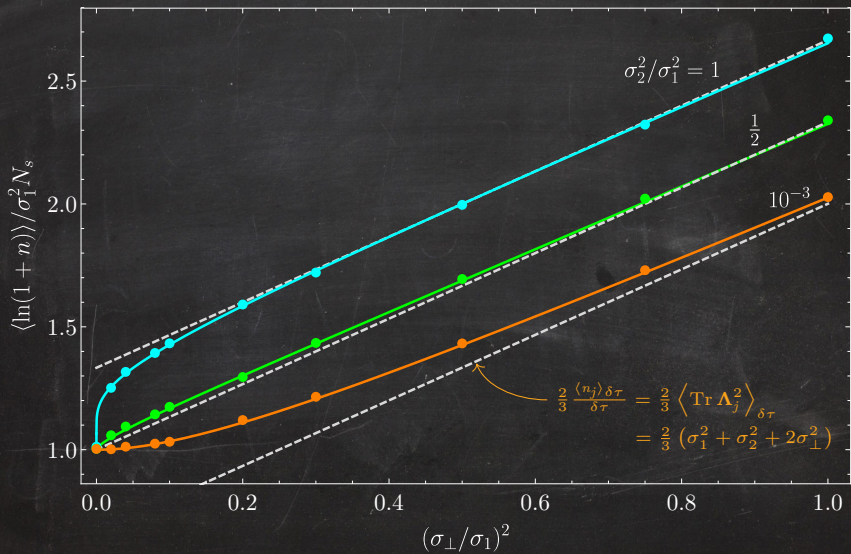
with

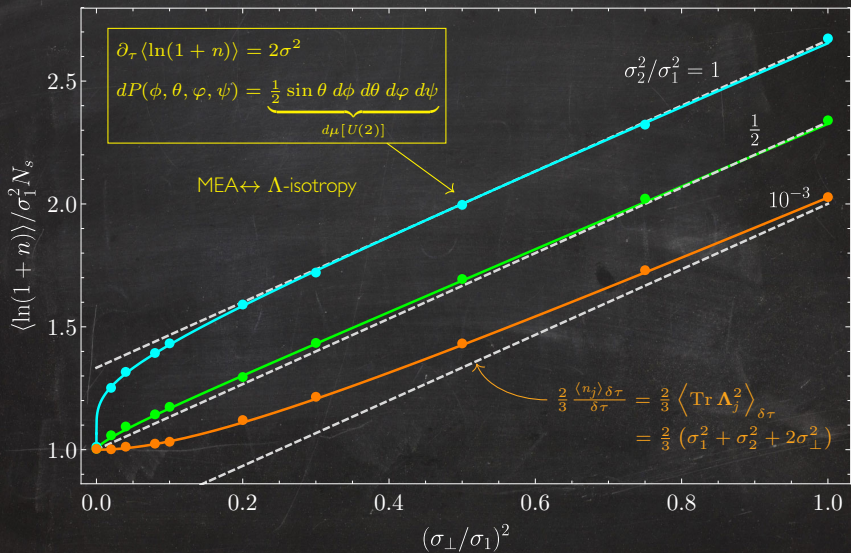
$$\int P \, d\mathbf{f} \, d\phi \, d\varphi \, d\psi = \frac{1}{\mathcal{N}} \frac{\sin \theta}{Q \sin^2 \theta + 1} \exp \left[ 2\nu \operatorname{arctanh} \left( \sqrt{\frac{Q}{1+Q}} \cos \theta \right) \right]$$

$$Q = \frac{\sigma_1^2 + \sigma_2^2 - 4\sigma_\perp^2}{8\sigma_\perp^2}, \quad \nu = \frac{|\sigma_1^2 - \sigma_2^2|}{8\sigma_\perp^2 \sqrt{|Q|(1+Q)}}$$









$N_f$  fields

$N_f(N_f + 1)$  parameters now,  $f_1, f_2, \dots, f_{N_f}$  and (Tilma, Sudarshan 2002)

$$\mathbf{u} = \left( \prod_{2 \leq k \leq N} \mathbf{A}(k) \right) \cdot [SU(N-1)] \cdot e^{i\lambda_{N^2-1} \alpha_{N^2-1}}, \quad \mathbf{A}(k) = e^{i\lambda_3 \alpha_{(2k-3)}} e^{i\lambda_{(k-1)^2+1} \alpha_{2(k-1)}}$$

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$\Rightarrow$  need  $\mathcal{O}(N_f^4)$  correlators!

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$$\sigma^2 = \begin{pmatrix} \sigma_1^2/2 & \sigma_\perp^2 & \cdots & \sigma_\perp^2 \\ \sigma_\perp^2 & \sigma_2^2/2 & \cdots & \sigma_\perp^2 \\ \vdots & \vdots & \ddots & \vdots \\ \sigma_\perp^2 & \sigma_\perp^2 & \cdots & \sigma_2^2/2 \end{pmatrix}$$

$\Rightarrow$  Results depend only on the angle  $\theta = \alpha_{2(N_f-1)}$  and

$$\mathcal{F}(\Omega_{N_f}) = \mathcal{F}(\Omega_{N_f-1}) \cos^4(\alpha_{2(N_f-2)}/2) + \sin^4(\alpha_{2(N_f-2)}/2)$$

with  $\mathcal{F}(\Omega_2) = 1$

$N_f$  fields

$N_f(N_f + 1)$  parameters now,  $f_1, f_2, \dots, f_{N_f}$  and (Tilma, Sudarshan 2002)

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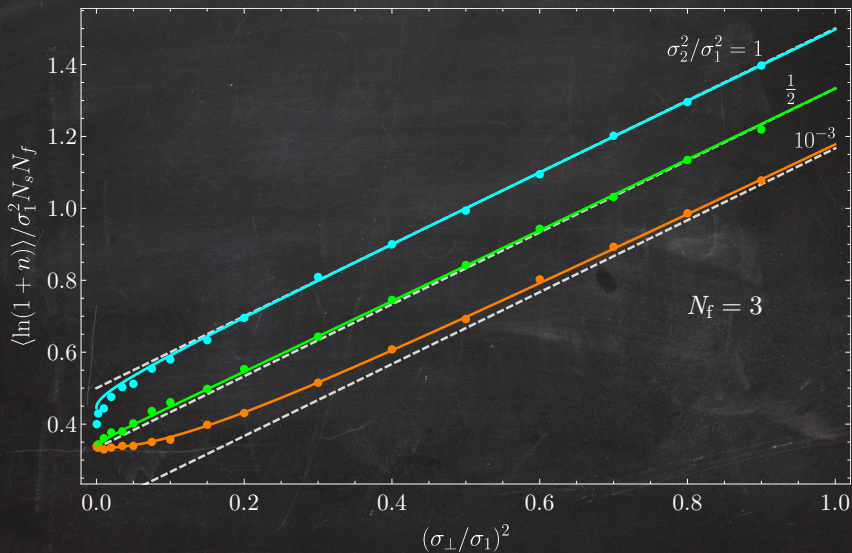
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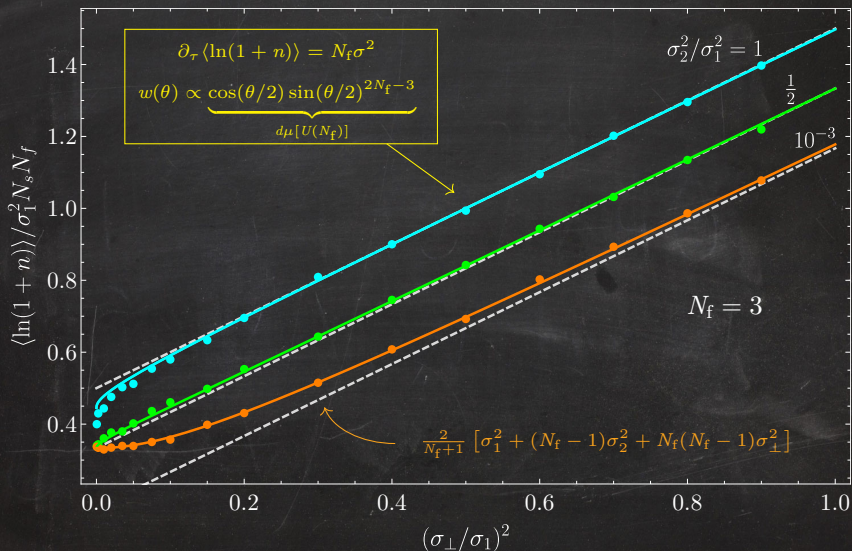
$$\partial_\tau \langle \ln(1+n) \rangle = \left\langle l(\theta) - \frac{1}{2} \gamma(\theta, \Omega_{N_f}) \right\rangle$$

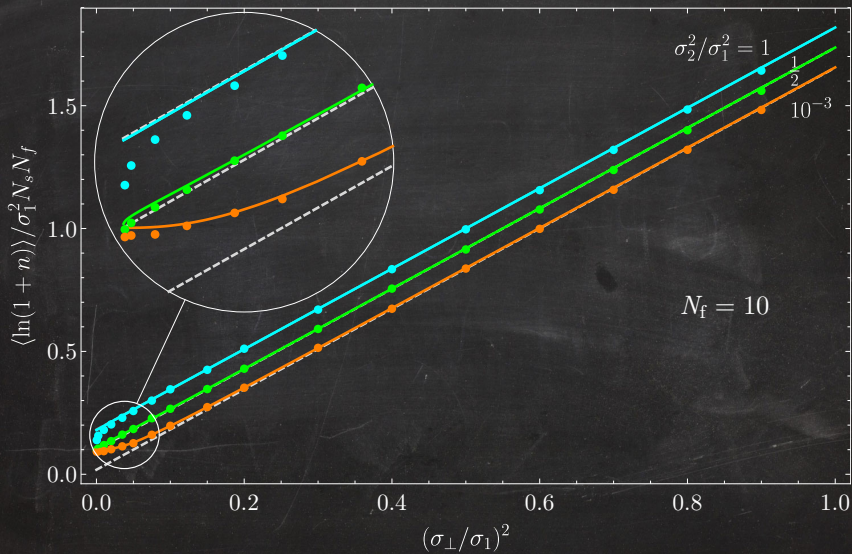
$$l(\theta) = 2 \left[ \sigma_1^2 \cos^2(\theta/2) + \sigma_2^2 \sin^2(\theta/2) + \sigma_\perp^2 (N_f - 1) \right]$$

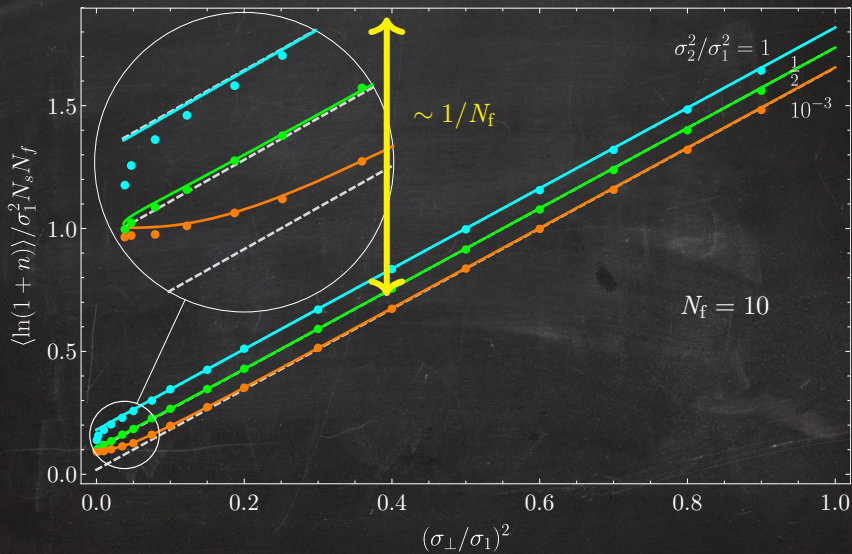
$$\gamma(\theta, \Omega_{N_f}) = 2 \left[ \sigma_1^2 \cos^4(\theta/2) + \sigma_2^2 \sin^4(\theta/2) \mathcal{F}_\Omega + 2\sigma_\perp^2 (1 - \cos^4(\theta/2) - \sin^4(\theta/2) \mathcal{F}_\Omega) \right]$$











## Conclusion

- Avoid relying on detailed model building, and take a coarse grained approach to the particle production in the early universe
- MEA captures the universal features arising from a Central Limit Theorem (concentration of measure)...
- ...as long as there's no hierarchy of couplings
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Thank you