

THE MAXIMAL GENERIC NUMBER
OF PURE NASH EQUILIBRIA

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Abstract

For finite pure strategy sets S_1, \dots, S_n , if $E \subset S = S_1 \times \dots \times S_n$ is the set of pure strategy Nash equilibria for an open set of payoff vectors, then $\#E \leq \#S / (\max_i \#S_i)$. There is an open set of payoff vectors for which there are $\#S / (\max_i \#S_i)$ pure Nash equilibria.

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A normal form game can have as many pure strategy Nash equilibria as there are pure strategy vectors, if each agent's payoff never depends on her own choice of strategy, but this phenomenon is not robust with respect to perturbations of payoffs. This note characterizes the largest sets of pure strategy vectors that are the sets of pure strategy equilibria for open sets of payoffs. In addition to resolving a point of curiosity, this and related results have implications for the worst case running times of algorithms that compute all Nash equilibria.

Several recent papers deal with the number of Nash equilibria possessed by normal form games. Fixing strategy spaces, McKelvey and McLennan (1994) characterize the maximal (as the payoffs are varied) number of regular totally mixed equilibria. It is a longstanding open problem to show that for two agents, each with k pure strategies, there is an open dense subset of payoffs on which there are at most $2^k - 1$ Nash equilibria. Quinn and Shubik confirm¹ this conjecture for the case $k = 3$. Extending earlier results, Stanford (1993) characterizes the asymptotic (as the strategy spaces of at least two agents increase in size) probability that a "randomly selected" payoff vector will have exactly m pure strategy equilibria. Stanford (1994) extends this analysis to symmetric two person games, differentiating between symmetric and asymmetric equilibria.

Let the set of agents be $I = \{1, \dots, n\}$. Let finite strategy sets S_1, \dots, S_n be given, and let $S = S_1 \times \dots \times S_n$. We say that $E \subset S$ is *thin* if, for any distinct $s, t \in E$, there are at least two i such that $s_i \neq t_i$. That is, there do not exist distinct $s, t \in E$ with $s_j = t_j$ for all j except some particular agent i .

Lemma: If $u_1, \dots, u_n \in \mathbb{R}^S$ are payoffs such that $u_i(s) \neq u_i(t)$ for all i and all distinct $s, t \in S$, and E is the set of pure Nash equilibria for u_1, \dots, u_n , then E is thin.

Proof: Otherwise there exist $s, t \in E$ and an agent i such that $s_i \neq t_i$ while $(s_j)_{j \neq i} = (t_j)_{j \neq i}$. The hypothesis does not allow both s_i and t_i to be best responses to $(s_j)_{j \neq i}$. ■

¹ Personal communication.

Proposition: If E is nonempty and thin, then there is an open set of $(u_1, \dots, u_n) \in (\mathbb{R}^S)^I$ for which E is the set of pure Nash equilibria.

Proof: Let $E_0 = E$, and define E_1, \dots, E_n inductively by

$$E_k = \{s \in S - (E_0 \cup \dots \cup E_{k-1}) : \text{there is } t \in (E_0 \cup \dots \cup E_{k-1}) \text{ such that}$$

$$s_i \neq t_i \text{ for exactly one } i \}.$$

Evidently E_0, \dots, E_n is a partition of S . Define (u_1, \dots, u_n) by setting $u_i(s) = -k$ for all i and $s \in E_k$. Then it is easily seen that E will be the set of pure Nash equilibria for all vectors of payoffs in a neighborhood of (u_1, \dots, u_n) . ■

We say that a thin set is *maximal* if there is no thin proper superset. We say that a thin set is *svelte* if there is no thin set with a larger number of elements. It seems reasonable to conjecture that maximal thin sets are svelte, but I do not know if this is the case.

Our main result is:

Theorem: Assume that $\#S_1 \geq \dots \geq \#S_n$. Then:

- A. Svelte subsets of S have $\#S_2 \times \dots \times \#S_n$ elements;
- B. There are $\#S_n$ pairwise disjoint svelte sets.

Proof: We argue by induction on n . Both claims are trivial when $n = 1$, so assume they have been established for the case of $n - 1$ agents. Let $S_n = \{s_n^1, \dots, s_n^m\}$. If E is svelte, then $E = \cup_{h=1}^m F_h \times \{s_n^h\}$, where F_1, \dots, F_m are pairwise disjoint thin subsets of $S_1 \times \dots \times S_{n-1}$, so svelte subsets of S have at most $(\#S_2 \times \dots \times \#S_{n-1}) \times \#S_n$ elements. If, on the other hand, F_1, \dots, F_m are pairwise disjoint thin subsets of $S_1 \times \dots \times S_{n-1}$, then for each $q = 1, \dots, m$,

$$E_q = (F_1 \times \{s_n^{q+1}\}) \times \dots \times (F_{m-q} \times \{s_n^m\}) \times (F_{m-q+1} \times \{s_n^1\}) \times \dots \times (F_m \times \{s_n^q\})$$

is thin, and E_1, \dots, E_m are pairwise disjoint. ■

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