

**THE NULL BOUNDARY CONTROLLABILITY FOR  
SEMILINEAR HEAT EQUATIONS**

By

**Yung-Jen Guo**

and

**Walter Littman**

**IMA Preprint Series # 1128**

April 1993

# The null boundary controllability for semilinear heat equations

YUNG-JEN GUO and WALTER LITTMAN

School of Mathematics, University of Minnesota

**Abstract.** We consider the null boundary controllability for one-dimensional semilinear heat equations. We obtain null boundary controllability results for semilinear equations when the initial data is bounded continuous and sufficiently small. In this work, we also prove a version of the nonlinear Cauchy-Kowalevski Theorem

**1. Introduction.** The aim of this work is to study the null boundary controllability problem for one-dimensional semilinear heat equations. First, we consider the following initial boundary value problem for a semilinear heat equation with Dirichlet boundary conditions: find  $w(x, t)$  such that

$$w_t - w_{xx} = f(w, x) \quad \text{on } (0, 1) \times (0, \infty) \quad (1.1)$$

$$w(0, t) = 0 \quad \text{for } t \geq 0 \quad (1.2)$$

$$w(x, 0) = w_0(x) \quad \text{for } x \in (0, 1] \quad (1.3)$$

$$w(1, t) = h(t) \quad \text{for } t \geq 0 \quad (1.4)$$

where  $f(s, x)$  is an analytic function in both arguments in a neighborhood of the origin and belongs locally to Gevrey class 2 in its first argument and is Hölder continuous in its second argument such that  $f(0, x) = 0$  and  $D_1 f(0, x) = 0$  for all  $x \in [0, 1]$ . We also consider the semilinear equation

$$w_t - w_{xx} = f(w, w_x, x) \quad \text{on } (0, 1) \times (0, \infty) \quad (1.5)$$

instead of (1.1) where  $f$  is analytic in all arguments near  $(0, 0, 0)$  and belongs locally to Gevrey class 2 in the first two arguments and is Hölder continuous in  $x$  such that  $f(0, 0, x) = 0$ ,  $D_1 f(0, 0, x) = 0$ ,  $D_2 f(0, 0, x) = 0$  for all  $x \in [0, 1]$ . The problem of null boundary controllability for (1.1)–(1.4) or (1.2)–(1.5) which we are going to solve is: given

---

The second author was partial supported by NSF grand DMS 90-02919.

$T > 0$ , is it possible, for every initial data  $w_0$  which is sufficient small and in an appropriate space, to find a corresponding controller  $h(t)$  so that the solution of the resulting problem vanishes for  $t \geq T$ ?

The method we use here is, to some extent, based on the work of W. Littman and L. Markus[17].

Our method proceeds roughly as follows:

- (1) Extend the domain of the initial data  $w_0$  to be  $[0, 2]$  so that the extended  $w_0$  is still small. Also extend the domain of  $f$  to the interval  $[0, 2]$  such that all properties of  $f$  are preserved.
- (2) With the modified initial data  $w_0$ , solve the initial-boundary value problem (1.1)-(1.3) or (1.5) & (1-2)-(1-3) with  $w(2, t) = 0$  for  $x \in [0, 2]$  and  $t \in [0, \infty)$ .
- (3) Let  $\psi$  be a cut-off function satisfying  $\psi(t) = 1$  for  $t \leq T/2$  and  $\psi(t) = 0$  for  $t \geq T$ .

Set

$$g(t) = w_x(0, t)\psi(t)$$

where  $w$  is the solution of Step 2.

- (4) Solve the Cauchy problem

$$\begin{aligned} u_t - u_{xx} &= f(u, x) \quad \text{on } (0, 2) \times (0, \infty) \\ u(0, t) &= 0, \quad u_x(0, t) = g(t) \quad \text{for } t \geq 0 \end{aligned}$$

in the  $x$ -direction to get a solution which vanishes for  $t \geq T$  and equals the solution  $w$  for  $t \leq T/2$ .

- (5) The control function is then obtained by setting  $h(t) = u(1, t)$ .

Steps 1-3 are more or less standard. The main difficulty is Step 4. To solve the Cauchy problem in Step 4, we use a nonlinear Ovcyannikov Theorem (or called nonlinear Cauchy-Kowalevski Theorem, see, e.g., [1,10,17,21,22]). To apply this theorem, we need  $g$  to be of Gevrey class 2 in  $t$  for  $t > 0$ . What this means is that there exist positive constants  $C, H$  such that

$$\left| \frac{\partial^n g}{\partial t^n}(t) \right| \leq CH^n(2n)! \quad \text{for } t > 0, n \geq 0.$$

By direct computation, the set of these Gevrey functions forms an algebra which is closed under differentiation with respect to  $t$ . Furthermore, it is possible to choose  $\psi$  in Step 3 to be a Gevrey class 2 function (such function can be explicitly written, see[4]). Thus  $g$  may be obtained as a Gevrey class 2 function as long as the solution of Step 2 is a Gevrey class 2 function.

We note that the definition of Gevrey functions which we use here differs a little from that of the definition used in [17, 24] but it is the same as the one used in [3,11].

We remark that the controller  $h(t)$  is not necessarily unique. The null boundary controllability may also be obtained by other continuous controllers.

The paper is organized as follows. Section 2 is devoted to state the modified nonlinear Ovcyannikov Theorem for system of differential equations and its proof is given in Section 3. Because the way this theorem is used in this paper, the roles of the variables  $x$  and  $t$  are reversed from those in the usual statements, making  $x$  the "time variable". In Section 4, we define a scale of Banach spaces of Gevrey class which will be used to solve the problem in Step 4; and in Section 5, we actually solve the problem under the assumption that  $g(t)$  is of Gevrey class 2 in  $t > 0$ . Because we need the existence in the whole unit  $x$ -interval (not just a small part of it), it is necessary to keep track of all constants and to check the proof carefully to ensure that by making  $g(t)$  small, we get existence in the whole unit  $x$ -interval. Finally, we obtain the null controllability result for (1.1)–(1.4) in Section 6. The "sufficient small" assumption on the initial data can be eliminated under certain conditions. See remark after the proof of Theorem 6.1. In section 7, we use the same method to obtain null boundary controllability for (1.2)–(1.5).

A great many decisive developments in the controllability theory of the linear heat equation were initiated by H. O. Fattorini and D. L. Russell. These have been presented in numerous articles (see e.g.[6-8,23]).

There are some other methods for proving the boundary controllability results. Some methods which have achieved considerable success are the Method of the Multipliers[13] and the "Hilbert space uniqueness method" (HUM) due to J. L. Lions[14,15]. However, it is not clear whether these methods can be modified to obtain the result of this work. The advantage of our method is to transform the control problem to two well-posed problems.

**2. Nonlinear Cauchy-Kowalevski Theorem for Systems of Differential Equations.** In this section, we shall study the existence and uniqueness of solutions of some abstract Cauchy problems.

We begin by considering a 1-parameter family of Banach spaces  $X_s$  where the parameter  $s$  is allowed to vary in  $[0, 1]$ .

**Definition 2.1.**  $\{X_s\}_{0 \leq s \leq 1}$  is a scale of Banach spaces if for any  $s \in [0, 1]$ ,  $X_s$  is a linear subspace of  $X_0$  and if  $s' \leq s$  then  $X_s \subset X_{s'}$  and the natural injection of  $X_s$  into  $X_{s'}$  has norm less than or equal to 1.

We denote by  $\|\cdot\|_s$  the norm of  $X_s$ .

A theorem which is originally due to L. V. Ovcyannikov is exploited (see, e.g., [1, 10, 21, 22, 25, 26]) in a number of ways to obtain results in the study of the nonlinear abstract Cauchy problem of the form

$$\begin{aligned} \frac{du}{dx} &= F(u, x), \quad |x| < \eta, \eta > 0 \\ u(0) &= u_0. \end{aligned}$$

Here the solutions are sought, as functions of the variable  $x$ , in a scale of Banach spaces  $\{X_s\}$ . The standard condition for Ovcyannikov's Theorem on  $F$  is that there exists a positive constant  $C$  such that for every pair of numbers  $s, s'$ ,  $0 \leq s' < s \leq 1$ , for all  $u, v \in X_s$ , and for all  $x$  in a prescribed interval, we have

$$\|F(u, x) - F(v, x)\|_{s'} \leq \frac{C}{s - s'} \|u - v\|_s. \quad (2.1)$$

This is the key condition needed to prove existence and uniqueness of the solution of the above Cauchy problem. The assumption (2.1) which holds for all  $u, v \in X_s$  is more restrictive. In a paper of T. Kano and T. Nishida[10], they allow the condition to be relaxed to hold only for  $u, v \in X_s$  with  $\|u\|_s < R$  and  $\|v\|_s < R$  for some  $R$ .

For each  $i$ ,  $i = 1, \dots, m$ , let  $\{X_s^i\}_{0 \leq s \leq 1}$  be a scale of Banach spaces with norm  $\|\cdot\|_s^i$ . P. Duchateau and F. Trèves[1] consider systems of differential equations of the form

$$\frac{du_i}{dx} = F_i(u_1, u_2, \dots, u_m, x), \quad |x| < \eta_i, \eta_i > 0, \quad i = 1, \dots, m \quad (2.2)$$

$$u_i(0) = u_0^i, \quad i = 1, \dots, m, \quad (2.3)$$

where the  $u_i$ , as functions of the variable  $x$ , are in  $X_s^i$ ,  $i = 1, \dots, m$ . They allow each  $F_i$  to have different exponents of  $(s - s')$ , that is, there exist constants  $C_i > 0$  such that for every pair of numbers  $s, s'$ ,  $0 \leq s' < s \leq 1$ , for all  $u_i, v_i \in X_s^i$  and for all  $x$ ,  $|x| < \eta_i$ , we have

$$\begin{aligned} & \|F_i(u_1, u_2, \dots, u_m, x) - F_i(v_1, v_2, \dots, v_m, x)\|_{s'} \\ & \leq \frac{C_i}{(s - s')^{\alpha_i}} [\|u_1 - v_1\|_s^1 + \dots + \|u_m - v_m\|_s^m], \quad i = 1, \dots, m \end{aligned} \quad (2.4)$$

for some parameters  $\alpha_i$ ,  $i = 1, \dots, m$ .

We shall discuss the system of differential equations of the kind (2.2) and (2.3). We impose the same conditions on  $F_i$  as (2.4) but only for  $\|u_i\|_s^i < R_i, \|v_i\|_s^i < R_i$  for some  $R_i$ ,  $i = 1, \dots, m$ . The conditions on  $\alpha_i$  are the same as the conditions imposed in [1]. We shall omit the index  $i$  if there is no confusion.

We need the following assumptions. For the initial data, we assume that:

(H1)  $u_{i,0} \in X_s^i$  for every  $s \in [0, 1]$  and satisfies

$$\|u_{i,0}\|_s \leq R_{i,0}$$

for some  $R_{i,0} < \infty$  for  $i = 1, \dots, m$ .

Concerning the function  $F_i$ , we assume that:

(H2) There are  $R_i > R_{i,0} > 0, \eta_i > 0, i = 1, \dots, m$ , such that for every pair of numbers  $s, s'$  with  $0 \leq s' < s \leq 1$  the mapping  $F_i(u_1, \dots, u_m, x), i = 1, \dots, m$ , is continuous from the set

$$\{u_1 \in X_s^1 \mid \|u_1\|_s < R_1\} \times \dots \times \{u_m \in X_s^m \mid \|u_m\|_s < R_m\} \times \{x \mid |x| < \eta_i\}$$

into  $X_{s'}^i$ .

(H3) There are constants  $C_i, i = 1, \dots, m$ , such that for every pair of numbers  $s, s'$  with  $0 \leq s' < s \leq 1$ , for all  $\|u_j\|_s < R_j, \|v_j\|_s < R_j, j = 1, \dots, m$ , and for all  $x, |x| < \eta_i$ , we have

$$\begin{aligned} & \|F_i(u_1, u_2, \dots, u_m, x) - F_i(v_1, v_2, \dots, v_m, x)\|_{s'} \\ & \leq \frac{C_i}{(s - s')^{\alpha_i}} [\vartheta_i^1 \|u_1 - v_1\|_s + \dots + \vartheta_i^m \|u_m - v_m\|_s], \quad i = 1, \dots, m, \end{aligned}$$

where the number  $\vartheta_i^j$  is set to be zero if  $F_i$  is independent of  $u_j$  and to be one otherwise, for some parameters  $\alpha_i \geq 0$ ,  $i = 1, \dots, m$ , such that for any collection of  $m^2$  numbers  $c_i^j$ , the degree of  $P(\lambda, \mu)$  with respect to  $\lambda, \mu$  is at most  $m$ , where the expression  $P(\lambda, \mu)$  of two variables  $\lambda, \mu$  is defined by

$$P(\lambda, \mu) = \det(\lambda I - [\mu^{\alpha_i} \vartheta_i^j c_i^j]),$$

with  $I$  the  $m \times m$  identity matrix and the degree is defined to be the highest degree among all monomials in  $P(\lambda, \mu)$ .

(H4)  $F_i(0, \dots, 0, x)$  is a continuous function of  $x$ ,  $|x| < \eta_i$ , with values in  $X_s^i$  for every  $s < 1$  and satisfies

$$\|F_i(0, \dots, 0, x)\|_s \leq \frac{K_i}{(1-s)^{\alpha_i}}, \quad 0 \leq s < 1$$

for some constants  $K_i$ ,  $i = 1, \dots, m$ , with  $\alpha_i$  defined in (H3).

We now state the existence and uniqueness theorem for solutions of (2.2) and (2.3) as follows.

**Theorem 2.1.** *Under the preceding hypotheses (H1)–(H4), there is a positive constant  $a$  such that the Cauchy problem (2.2)–(2.3) has a unique solution  $\{u_i(x), i = 1, \dots, m\}$ , which are continuously differentiable functions of  $x$ ,  $|x| < a(1-s)$ , with values in  $X_s^i$ ,  $\|u_i(x)\|_s < R_i$ , for every  $s < 1/2$ .*

The proof of this theorem will be given in the next section.

A few remarks about Theorem 2.1 are in order.

First, the necessity of the assumption on the degree of  $P(\lambda, \mu)$  can be illustrated by the case  $m = 1$ ,  $\alpha_1 = 2$  as shown in [1].

Secondly, the assumptions (H2) and (H3) are weaker than those of [1], because here we only require those conditions to hold for  $\|u_j\|_s < R_j$  and  $\|v_j\|_s < R_j$  for some  $R_j$ ,  $j = 1, \dots, m$ . Our assumptions are also more flexible than the assumptions in [10], because we allow the exponents  $\alpha_i$  to be different for each equation. But a small price must be paid for the weaker assumptions. The solution we obtained in Theorem 2.1 has value in  $X_s^i$  for  $s < \frac{1}{2}$ . In fact, the upper bound  $\frac{1}{2}$  is not optimal. By inspecting the proof

of Theorem 2.1, we see that the solution can have bounded value in  $X_s^i$  for  $s < 1 - \epsilon$  for any positive small number  $\epsilon$ .

Finally, when each  $F_i$ ,  $i = 1, \dots, m$  is analytic in all of its arguments and the Cauchy data is analytic, our theorem yields the classical Cauchy-Kowalevski Theorem.

**3. Proof of Theorem 2.1.** Our proof modifies the proof of T. Kano and T. Nishida's Theorem in [10].

We first transform the problem (2.2) and (2.3) to the integral equation

$$u_i(x) = u_{i,0} + \int_0^x F_i(u_1(y), \dots, u_m(y), y) dy, \quad i = 1, \dots, m. \quad (3.1)$$

Let  $a$  be a small positive constant to be determined later. For  $i = 1, \dots, m$ , let  $X^i$  be the Banach space of functions  $u(x)$  with values in  $X_s^i$ , which are continuous in  $x$  for  $|x| < a(1 - s)$  for every  $s \in [0, 1/2)$ , and have the norm

$$M_i[u] \equiv \sup_{\substack{0 \leq s < 1/2 \\ |x| < a(1-s)}} \|u(x)\|_s \frac{|a(1-s) - x|^{e_i}}{a(1-s)} < \infty \quad (3.2)$$

where  $e_i \geq 1$  will be defined later. We are looking for solutions of integral equations (3.1) whose norms  $M_i[u_i]$  are finite with some constant  $a > 0$  suitably small.

We will find solutions of (3.1) in  $X^i$ ,  $i = 1, \dots, m$ , via the following successive approximation procedure

$$u_i^{(0)}(x) = u_{i,0} \quad (3.3)$$

$$u_i^{(k+1)}(x) = u_{i,0} + \int_0^x F_i(u_1^{(k)}(y), \dots, u_m^{(k)}(y), y) dy, \quad k \geq 0, \quad (3.4)$$

where  $\|u_i^{(k)}(x)\|_s < R_i$  for  $|x| < a(1 - s)$ ,  $0 \leq s < 1/2$ ,  $i = 1, \dots, m$ . We shall only deal with the case  $0 \leq x < a(1 - s)$ . The other case is similar.

To ensure that  $\|u_i^{(k+1)}(x)\|_s < R_i$ , we will require that

$$\sum_{k=1}^{\infty} \|u_i^{(k+1)}(x) - u_i^{(k)}(x)\|_s \leq \frac{R_i - R_{i,0}}{2} \quad (3.5)$$

because by recursion this will imply

$$\begin{aligned} \|u_i^{(k+1)}(x)\|_s &\leq \sum_{j=0}^k \|u_i^{(j+1)}(x) - u_i^{(j)}(x)\|_s + \|u_{i,0}\|_s \\ &\leq \frac{R_i - R_{i,0}}{2} + R_{i,0} \\ &< R_i. \end{aligned}$$

We shall prove that (3.5) can be fulfilled for every  $i$  if we diminish the  $x$ -interval step by step, where we must ensure that the length of the limit interval is positive. The  $k$ -th iteration  $u_i^{(k)}$  will be defined on

$$0 \leq x < a_k(1-s) \quad (3.6)$$

where the number  $a_k$  is defined by

$$a_{k+1} = \left[1 - \frac{1}{4}\left(1 + \frac{1}{2} + \cdots + \frac{1}{2^k}\right)\right]a_0 = a_k - \frac{a_0}{2^{k+2}}, k = 0, 1, \dots \quad (3.7)$$

so that

$$a = \lim_{k \rightarrow \infty} a_k = a_0/2 \quad (3.8)$$

and  $a_0$  will be chosen suitably small later. Corresponding to the  $x$ -interval (3.6) we define as (3.2) the quantity

$$M_i^{(k)}[u] \equiv \sup_{\substack{0 \leq s < 1/2 \\ 0 \leq x < a_k(1-s)}} \|u(x)\|_s \frac{[a_k(1-s) - x]^{e_i}}{a_k(1-s)} < \infty.$$

From this definition we immediately get the property

$$M_i^{(k+1)}[u] \leq M_i^{(k)}[u] \quad \text{if } a_{k+1} < a_k. \quad (3.9)$$

Now assume that  $u_i^{(j)}$  are determined with  $M_i^{(j)}[u_i^{(j)}] < \infty$  and  $\|u_i^{(j)}(x)\|_s < R_i$  for  $0 \leq x < a_j(1-s)$ ,  $0 \leq s < \frac{1}{2}$ ,  $j = 1, \dots, k$ ,  $i = 1, \dots, m$ . By assumption (H2),  $u_i^{(k+1)}(x)$  is well-defined. Set

$$\lambda_i^{(k)} = M_i^{(k)}[u_i^{(k+1)} - u_i^{(k)}]. \quad (3.10)$$

Then

$$\begin{aligned} \|u_i^{(k+1)}(x) - u_i^{(k)}(x)\|_s &\leq \frac{\lambda_i^{(k)}}{(a_k(1-s) - x)^{e_i}/a_k(1-s)} \\ &\leq \frac{\lambda_i^{(k)}}{(1 - a_{k+1}/a_k)^{e_i}} \cdot \frac{2^{e_i-1}}{a_k^{e_i-1}} \end{aligned}$$

for  $0 \leq x < a_{k+1}(1-s)$ ,  $0 \leq s < 1/2$ , and thus, by (3.7),

$$\|u_i^{(k+1)}(x) - u_i^{(k)}(x)\|_s \leq (2^{k+2})^{e_i} 2^{e_i-1} a_0^{1-e_i} \lambda_i^{(k)}. \quad (3.11)$$

So if we require that

$$\sum_{k=0}^{\infty} (2^{k+2})^{e_i} 2^{e_i-1} a_0^{1-e_i} \lambda_i^{(k)} \leq \frac{R_i - R_{i,0}}{2} \quad (3.12)$$

for suitable  $a_0$ , then (3.5) holds and by recursion

$$\|u_i^{(k+1)}(x)\|_s < R_i,$$

and thus  $F_i(u_1^{(k+1)}(y), \dots, u_m^{(k+1)}(y), y)$  is defined, and so is  $u_i^{(k+2)}(x)$  for  $i = 1, \dots, m$ .

Our aim is to estimate  $\lambda_i^{(k)}$ ,  $i = 1, \dots, m$ , so that  $\lambda_i^{(k)} \rightarrow 0$  as  $k \rightarrow \infty$  and (3.12) holds for all  $k \geq 0$ . First of all, let us note that without loss of generality we may assume that the constants  $K_i$ ,  $i = 1, \dots, m$ , in assumption (H4) are zero, i.e., we may assume that

$$F_i(0, \dots, 0, x) = 0 \quad \text{for } 0 \leq x < \eta_i, \quad i = 1, \dots, m.$$

In fact, we can take  $u_{i,0}$  to be  $u_{i,0} + \int_0^x F_i(0, \dots, 0, y) dy$  which is bounded by  $R_{i,0} + K_i \eta_i$  for  $0 \leq x < \eta_i$  and  $s \in [0, 1)$ .

By (3.4), we have

$$\begin{aligned} &u_i^{(k+2)}(x) - u_i^{(k+1)}(x) \\ &= \int_0^x [F_i(u_1^{(k+1)}(y), \dots, u_m^{(k+1)}(y), y) - F_i(u_1^{(k)}(y), \dots, u_m^{(k)}(y), y)] dy. \end{aligned}$$

Thus for  $0 \leq x < a_{k+1}(1-s)$ , it follows from the assumption (H3) that

$$\|u_i^{(k+2)}(x) - u_i^{(k+1)}(x)\|_s \leq C_i \int_0^x \frac{1}{(s(y) - s)^{e_i}} \left( \sum_{j=1}^m \vartheta_i^j \|u_j^{(k+1)}(y) - u_j^{(k)}(y)\|_{s(y)} \right) dy$$

for some choice  $s(y)$  with  $s < s(y) < 1 - y/a_{k+1}$ . We may set

$$s(y) = (1 - y/a_{k+1} + s)/2.$$

Then we find by virtue of (3.10),

$$\begin{aligned} & \|u_i^{(k+2)}(x) - u_i^{(k+1)}(x)\|_s \\ & \leq C_i \int_0^x \frac{1}{(s(y) - s)^{\alpha_i}} \sum_{j=1}^m \vartheta_i^j \frac{\lambda_j^{(k)}}{(a_k(1 - s(y)) - y)^{e_j}/a_k(1 - s(y))} dy \\ & \leq C_i \sum_{j=1}^m \vartheta_i^j \lambda_j^{(k)} (2a_{k+1})^{\alpha_i} 2^{e_j-1} \int_0^x \frac{a_{k+1}(1 - s) + y}{[a_{k+1}(1 - s) - y]^{\alpha_i+e_j}} dy. \end{aligned} \quad (3.13)$$

We define the exponents  $e_i, i = 1, \dots, m$  as follows. By (3.13), to get the finite supremum in the definition of  $\lambda_i^{(k)}$ , the exponents  $e_i, i = 1, \dots, m$ , should be defined so that

$$e_i \geq \alpha_i + e_j - 1 \quad \text{for all } j \text{ such that } \vartheta_i^j = 1 \quad (3.14)$$

We also know that  $\vartheta_i^i = 1$  implies that  $\alpha_i \leq 1$  from assumption (H5), so we only have to deal with (3.14) for  $j \neq i$ . By renumbering the variables, we may assume that  $\alpha_1 \leq \dots \leq \alpha_m$ .

We define  $e_i$  in the reverse order of  $i$ , under the following rule:

- (1) if  $e_i$  has been defined in the previous steps, then we skip to the smaller index;
- (2) if  $\vartheta_i^j = 0$  for all  $j \neq i$ , let  $e_i = \alpha_i \vee 1$ , where  $a \vee b = \max(a, b)$ , otherwise, let  $j_0 = \min\{j \neq i \mid \vartheta_i^j = 1\}$ . We let  $e_i = (\alpha_i + e_{j_0} - 1) \vee 1$ , where  $e_{j_0} = \alpha_{j_0} \vee 1$  if  $e_{j_0}$  has not been defined in the previous steps.

By considering the restriction on the  $\alpha_i$  from assumption (H3), it is easy to check that the  $e_i, i = 1, \dots, m$  satisfy (3.14).

To simplify the calculation of the  $\lambda_i^{(k)}$ , we consider only  $m = 3$  (it is the only case we shall have occasion to use). The proof of the general case is essentially similar, although somewhat more cumbersome. By the definition of  $e_i, a_{k+1} < a_0$  and (3.13) we have

$$\begin{aligned} \lambda_i^{(k+1)} &= M_i^{(k+1)} [u_i^{(k+2)} - u_i^{(k+1)}] \\ &\leq \sum_{j=1}^3 C_i \vartheta_i^j \lambda_j^{(k)} (2a_0)^{\alpha_i} 2^{e_j-1} 2^{(3-(\alpha_i+e_j)) \vee 0} a_0^{e_i-(\alpha_i+e_j-1)} \\ &= \sum_{j=1}^3 \vartheta_i^j M_{ij} a_0^{e_i-e_j+1} \lambda_j^{(k)} \end{aligned}$$

where

$$M_{ij} = C_i 2^{\alpha_i + e_j - 1} 2^{[3 - (\alpha_i + e_j)] \vee 0}$$

$$= \begin{cases} 4C_i & \text{if } \alpha_i + e_j \leq 3 \\ 2^{\alpha_i + e_j - 1} C_i & \text{if } \alpha_i + e_j \geq 4. \end{cases}$$

Hence for  $i = 1, 2, 3$ ,  $k = 0, 1, 2, \dots$ ,

$$\lambda_i^{(k+1)} \leq \sum_{j=1}^3 \vartheta_i^j M_{ij} a_0^{e_i - e_j + 1} \lambda_j^{(k)}. \quad (3.15)$$

Now, we compute  $\lambda_i^{(0)}$ . For  $0 \leq x < a_0(1-s)$ ,

$$\begin{aligned} \|u_i^{(1)}(x) - u_i^{(0)}(x)\|_s &= \left\| \int_0^x F_i(u_1^{(0)}, u_2^{(0)}, u_3^{(0)}, y) dy \right\|_s \\ &\leq C_i \sum_{j=1}^3 \vartheta_i^j R_{j,0} \int_0^x \frac{1}{(s(y) - s)^{\alpha_i}} dy \\ &\leq C_i \sum_{j=1}^3 \vartheta_i^j R_{j,0} \int_0^x \frac{(2a_0)^{\alpha_i}}{[a_{k+1}(1-s) - y]^{\alpha_i}} dy \end{aligned}$$

and so,

$$\begin{aligned} \lambda_i^{(0)} &= \sup \|u_i^{(1)}(x) - u_i^{(0)}(x)\|_s \frac{[a_0(1-s) - x]^{e_i}}{a_0(1-s)} \\ &\leq 2C_i (2a_0)^{\alpha_i} \sum_{j=1}^3 \vartheta_i^j R_{j,0} < \infty. \end{aligned} \quad (3.16)$$

Let  $M = \max_{\substack{1 \leq i \leq 3 \\ 1 \leq j \leq 3}} M_{ij}$ . Then by (3.15), for  $i = 1, 2, 3$ ,  $k = 0, 1, 2, \dots$ ,

$$\begin{aligned} \lambda_i^{(k+1)} &\leq \sum_{j=1}^3 \vartheta_i^j M_{ij} a_0^{e_i - e_j + 1} \lambda_j^{(k)} \\ &\leq M a_0^{e_i + 1} \left( \sum_{j=1}^3 a_0^{-e_j} \lambda_j^{(k)} \right). \end{aligned}$$

So,

$$\sum_{i=1}^3 a_0^{-e_i} \lambda_i^{(k+1)} \leq (3M a_0) \left( \sum_{j=1}^3 a_0^{-e_j} \lambda_j^{(k)} \right).$$

Thus if  $a_0$  is chosen so small that

$$3Ma_0 < \left(\frac{1}{3}\right)^{e_i}, \quad (3.17)$$

then

$$\sum_{i=1}^3 a_0^{-e_i} \lambda_i^{(k)} \leq \left[\left(\frac{1}{3}\right)^{e_i}\right]^k \cdot K, \quad (3.18)$$

where

$$K = \sum_{j=1}^3 a_0^{-e_j} \lambda_j^{(0)} < \infty.$$

and hence

$$\sum_{k=0}^{\infty} \sum_{i=1}^3 a_0^{-e_i} \lambda_i^{(k)} \leq 2K. \quad (3.19)$$

Therefore the series  $\sum_{k=0}^{\infty} \lambda_i^{(k)}$  converges.

It remains to verify (3.12). According to (3.11), (3.18), we have for  $0 \leq x < a_{k+1}(1-s)$ ,  $0 \leq s < 1/2$

$$\begin{aligned} \sum_{k=0}^{\infty} \|u_i^{(k+1)}(x) - u_i^{(k)}(x)\|_s &\leq 2^{3e_i-1} a_0 \sum_{k=0}^{\infty} (2^{e_i})^k a_0^{-e_i} \lambda_i^{(k)} \\ &\leq 2^{3e_i-1} a_0 \sum_{k=0}^{\infty} (2^{e_i})^k \left[\left(\frac{1}{3}\right)^{e_i}\right]^k K \\ &\leq 3a_0 2^{3e_i-1} K. \end{aligned}$$

Thus, if  $a_0$  is taken small enough such that

$$3a_0 2^{3e_i-1} K < \frac{R_i - R_{i,0}}{2}, \quad i = 1, 2, 3, \quad (3.20)$$

then (3.12) is satisfied and

$$\|u_i^{(k+1)}(x)\|_s < \frac{R_i - R_{i,0}}{2} + R_{i,0} < R_i.$$

We conclude that if we choose  $a_0$  so small that (3.17), (3.20) hold and  $a_0 < \eta_i$ ,  $i = 1, 2, 3$ , then the functions  $u_i^{(k)}(x)$  are defined for all  $k$  and  $i$  with

$$\|u_i^{(k)}(x)\|_s < R_i \quad \text{for } 0 \leq x < a_k(1-s), 0 \leq s < 1/2, i = 1, 2, 3. \quad (3.21)$$

Also, according to (3.10), for  $0 \leq x < a(1-s) < a_k(1-s)$ ,

$$\begin{aligned} \|u_i^{(k+1)}(x) - u_i^{(k)}(x)\|_s &\leq \frac{\lambda_i^{(k)}}{(a_k(1-s) - x)^{e_i}/a_k(1-s)} \\ &< \frac{\lambda_i^{(k)}}{(a(1-s) - x)^{e_i}/a(1-s)}, \end{aligned}$$

so,

$$M_i[u_i^{(k+1)} - u_i^{(k)}] \leq \lambda_i^{(k)}.$$

Since the series  $\sum \lambda_i^{(k)}$  converges for each  $i$ , the sequence  $u_i^{(k)}$  converges to some limit  $u_i(x)$  in  $X^i$ ,  $i = 1, 2, 3$ , and from (3.21)

$$\|u_i(x)\|_s \leq R_i, \quad 0 \leq x < a(1-s), \quad 0 \leq s < 1/2, \quad i = 1, 2, 3.$$

These  $u_i(x)$  satisfy (3.1). In fact, we have for  $0 \leq x < a(1-s)$  and  $0 \leq s' < s < 1/2$  that

$$\begin{aligned} &\|u_{i,0} + \int_0^x F_i(u_1(y), u_2(y), u_3(y), y) dy - u_i(x)\|_{s'} \\ &\leq \int_0^x \|F_i(u_1(y), u_2(y), u_3(y), y) - F_i(u_1^{(k)}(y), u_2^{(k)}(y), u_3^{(k)}(y), y)\|_{s'} dy \\ &\hspace{25em} + \|u_i(x) - u_i^{(k+1)}(x)\|_{s'} \\ &\leq \frac{C_i}{(s-s')^{\alpha_i}} \int_0^x [\|u_1(y) - u_1^{(k)}(y)\|_s + \|u_2(y) - u_2^{(k)}(y)\|_s + \|u_3(y) - u_3^{(k)}(y)\|_s] dy \\ &\hspace{25em} + \|u_i(x) - u_i^{(k+1)}(x)\|_{s'} \end{aligned}$$

and both terms on the right-hand side of the last inequality tend to zero as  $k \rightarrow \infty$ . This proves the existence part of Theorem 2.1.

For the uniqueness, we also only consider the case  $m = 3$ . We suppose that for some  $a$  there exist  $C^1$  functions  $u_i(x), v_i(x)$  in  $x$  for  $0 \leq x < a(1-s)$ ,  $0 \leq s < 1/2$  with values in  $X^i$  satisfying (3.1) for  $i = 1, 2, 3$ . Then  $w_i(x) \equiv u_i(x) - v_i(x)$  satisfies

$$w_i(x) = \int_0^x [F_i(u_1(y), u_2(y), u_3(y), y) - F_i(v_1(y), v_2(y), v_3(y), y)] dy.$$

Given any fixed  $s_1 < 1/2$ , we see that both  $N_i[u_i]$  and  $N_i[v_i]$  are finite, where the norms  $N_i$  are defined by

$$N_i[w] \equiv \sup_{\substack{0 \leq s < s_1 \\ 0 \leq x < a_k(1-s)}} \|w(x)\|_s \frac{[a(1-s) - x]^{e_i}}{a(1-s)}.$$

Then the assumption (H3) implies that for all  $0 \leq x < a(1-s)$ ,  $0 \leq s < s_1$ ,

$$\|w_i(x)\|_s \leq C_i \int_0^x \frac{1}{(s(y)-s)^{e_i}} \left( \sum_{j=1}^3 \vartheta_i^j \|w_i(y)\|_{s(y)} \right) dy$$

with some choice  $s(y) \in (s, 1-y/a)$ . By the same argument as in the proof of (3.15), we obtain that

$$N_i[w_i] \leq \sum_{j=1}^3 M a^{e_i - e_j + 1} N_j[w_j].$$

where  $M$  is defined as in (3.17). These together imply that

$$\sum_{i=1}^3 a_0^{-e_i} N_i[w_i] \leq (3Ma) \left( \sum_{i=1}^3 a_0^{-e_i} N_i[w_i] \right)$$

and thus  $N_i[w_i] = 0$  if  $3Ma < 1$ . Consequently, if we choose  $a$  sufficiently small then,  $N_i[w_i] = 0$ ,  $i = 1, 2, 3$ , and hence

$$\|w_i(x)\|_s \equiv 0 \quad \text{for } 0 \leq x < a(1-s), 0 \leq s < s_1.$$

Since this is true for all  $s_1$ , we conclude that  $w_i(x) \equiv 0$  for  $i = 1, 2, 3$ . This proves the theorem.

**4. Scales of Banach spaces of Gevrey functions.** We shall define scales of Banach spaces depending on parameters  $d, \beta$ , and  $s$ , where  $d \geq 1$ ,  $\beta > 2$ , and  $s \in [0, 1]$ .

**Definition 4.1.** Let  $K$  be a compact interval and let  $\theta_0$  and  $\theta_1$  be two positive constants such that  $\theta_0 < \theta_1 < \infty$ . Given  $d \geq 1$ ,  $\beta > 2$ , and  $s \in [0, 1]$ , we define the space  $B_s(d, \beta)$  to be the set of all  $C^\infty(K)$  functions  $\phi$  which is defined in  $K$  satisfying

$$\|\phi\|_s \equiv \sup_{n \geq 0} \max_{t \in K} \frac{\tilde{n}^\beta \theta(s)^n}{\lambda(dn)!} |\phi^{(n)}(t)| < \infty, \quad (4.1)$$

where  $\theta(s)^{-1} = (1-s)\theta_0^{-1} + s\theta_1^{-1}$ ,  $\tilde{n} = \max(n, 1)$ , and  $\lambda$  is a positive constant.

It is easy to see that  $\|\cdot\|_s$  in (4.1) is a norm on  $B_s(d, \beta)$  which makes  $B_s(d, \beta)$  into a Banach space. Moreover, for  $d$  and  $\beta$  fixed and  $s$  ranging in  $[0, 1]$  the family  $\{B_s(d, \beta)\}$  forms a scale of Banach spaces. We shall choose  $\lambda$  so that  $B_s(d, \beta)$  is a Banach algebra.

In the following propositions, we shall study the properties of these spaces. First, for any  $d \geq 1$ ,  $p \geq q \geq 0$ ,  $p, q$  integers, it is easy to verify the following two inequalities:

$$\binom{p}{q} \leq \binom{dp}{dq}, \quad \text{where} \quad \binom{p}{q} = \frac{p!}{q!(p-q)!} \quad (4.2)$$

$$\frac{(d(p-q)+1) \cdots (d(p-q)+d)(dq+1) \cdots (dq+d)}{(dp+1) \cdots (dp+d)} \leq d^{2d} \frac{(p-q+1)(q+1)}{p+1}. \quad (4.3)$$

**Proposition 4.1.** *If  $\lambda \leq 1/[2 + 2^\beta \sum_{k=1}^{\infty} (1/k)^\beta]$ , then  $B_s(d, \beta)$  is a Banach algebra for any  $s \in [0, 1]$ .*

PROOF: It suffices to show that for functions  $\phi, \psi \in B_s(d, \beta)$

$$\|\phi\psi\|_s \leq \|\phi\|_s \|\psi\|_s.$$

By Leibnitz's rule, we only need to require that

$$\sum_{k=0}^n \binom{n}{k} \frac{\lambda(d(n-k))! \lambda(dk)!}{((n-k)\sim)^\beta \tilde{k}^\beta} \leq \frac{\lambda(dn)!}{\tilde{n}^\beta}. \quad (4.4)$$

Now, (4.4) is satisfied if

$$\lambda \sum_{k=0}^n \binom{n}{k} \left(\frac{dn}{dk}\right)^{-1} \left(\frac{\tilde{n}}{(n-k)\sim \tilde{k}}\right)^\beta \leq 1.$$

Since

$$\begin{aligned} \sum_{k=0}^n \left(\frac{\tilde{n}}{(n-k)\sim \tilde{k}}\right)^\beta &\leq 2 + \sum_{k=1}^{n-1} \left(\frac{n}{(n-k)k}\right)^\beta \\ &= 2 + \sum_{k=1}^{n-1} \left(\frac{1}{n-k} + \frac{1}{k}\right)^\beta \\ &\leq 2 + 2^\beta \sum_{k=1}^{n-1} (1/k)^\beta \\ &\leq 2 + 2^\beta \sum_{k=1}^{\infty} (1/k)^\beta \end{aligned}$$

and by (4.2), we see that (4.4) is satisfied if

$$\lambda \leq 1/[2 + 2^\beta \sum_{k=1}^{\infty} (1/k)^\beta]$$

and hence the proposition is proved. ■

**Remark 4.1.** A change of the number  $\lambda$  changes the norm of the space  $B_s(d, \beta)$ , but not the space itself. From now on, we shall assume that  $\lambda$  satisfies the above inequality.

**Proposition 4.2.** The partial differentiation  $\partial/\partial t$  defines a bounded linear operator from  $B_s(d, \beta)$  into  $B_{s'}(d, \beta)$  for  $0 \leq s' < s \leq 1$  with norm less than or equal to  $C/(s - s')^d$ , where  $C$  is a positive constant depending only on  $d$ ,  $\theta_0$ , and  $\theta_1$ .

PROOF: We compute

$$\begin{aligned}
& \|\phi'(t)\|_{s'} \\
&= \sup_{n \geq 0} \max_{t \in K} \frac{\tilde{n}^\beta \theta(s')^n}{\lambda(dn)!} |\phi^{(n+1)}(t)| \\
&\leq \sup_{n \geq 0} \max_{t \in K} \left[ \theta(s')^{-1} \left( \frac{\theta(s')}{\theta(s)} \right)^{n+1} \left( \frac{\tilde{n}}{n+1} \right)^\beta \frac{(d(n+1))! (n+1)^\beta \theta(s)^{n+1}}{(dn)! \lambda(d(n+1))!} |\phi^{(n+1)}(t)| \right] \\
&\leq \theta(s')^{-1} \sup_{n \geq 0} \left\{ \left( \frac{\theta(s')}{\theta(s)} \right)^{n+1} (dn+1) \cdots (dn+d) \right\} \|\phi\|_s \\
&\leq \theta_0^{-1} \sup_{n \geq 0} \left\{ \left( \frac{\theta(s')}{\theta(s)} \right)^{n+1} (dn+d)^d \right\} \|\phi\|_s \\
&= \theta_0^{-1} d^d \|\phi\|_s \sup_{n \geq 1} \left\{ \left( \frac{\theta(s')}{\theta(s)} \right)^n n^d \right\} \\
&\leq \theta_0^{-1} d^d \|\phi\|_s (d/e)^d (\ln \theta(s) - \ln \theta(s'))^{-d}.
\end{aligned}$$

Since

$$\frac{\theta(s)}{\theta(s')} = 1 + \theta(s)(s' - s)(\theta_1^{-1} - \theta_0^{-1}) \geq 1 - \theta_1(s - s')(\theta_1^{-1} - \theta_0^{-1}) \geq \exp\left((s - s') \frac{\theta_1 - \theta_0}{\theta_0}\right)$$

we obtain

$$\ln \theta(s) - \ln \theta(s') \geq (s - s') \frac{\theta_1 - \theta_0}{\theta_0}$$

Hence by taking the constant  $C$  to be  $(d^2/e)^d \theta_0^{-1} ((\theta_1 - \theta_0)/\theta_0)^{-d}$ , the proposition is proved. ■

**Remark 4.2.** The constant  $C$  in Proposition 4.2 can be made as small as we wish by taking the constant  $\theta_0$  sufficiently small while keeping the constant  $\theta_1$  fixed in the definition of Banach space  $B_s(d, \beta)$  when  $d > 1$ .

**Proposition 4.3.** *If  $\phi \in B_s(d, \beta)$ , then there exists a positive constant  $C$  depending only on  $\beta, d$  such that for all positive integers  $m, n$  we have*

$$\sup_{t \in K} |D_t^m(\phi_t^n)| \leq (C\|\phi\|_s \theta(s)^{-1} \lambda)^{n-1} \|\phi\|_s \theta(s)^{-(m+1)} \lambda \frac{(d(m+1))!}{(m+1)^\beta}.$$

PROOF: Using Proposition 4.2 and the fact that  $B_s(d, \beta)$  is a multiplication algebra, we can conclude that  $\phi_t^n \in B_{s'}(d, \beta)$  for  $s' \leq s$  and all positive integer  $n$ . We proceed by induction on  $n$ . From the definition 4.1, it is obvious that the proposition is true if  $n = 1$ . We assume that it holds up to level  $n$  for some  $n \geq 1$ . By Leibniz' rule we have

$$|D_t^m(\phi_t^{n+1})| \leq \sum_{k=0}^m \binom{m}{k} |D_t^{m-k}(\phi_t^n)| |D_t^k(\phi_t)|.$$

Then applying the induction hypothesis we get

$$\begin{aligned} |D_t^m(\phi_t^{n+1})| &\leq \sum_{k=0}^m \binom{m}{k} (C\|\phi\|_s \theta(s)^{-1} \lambda)^{n-1} \|\phi\|_s \theta(s)^{-(m-k+1)} \\ &\quad \cdot \lambda \frac{(d(m-k+1))!}{(m-k+1)^\beta} \|\phi\|_s \theta(s)^{-(k+1)} \lambda \frac{(d(k+1))!}{(k+1)^\beta} \\ &\leq (C\|\phi\|_s \theta(s)^{-1} \lambda)^{n-1} \|\phi\|_s \theta(s)^{-(m+1)} \lambda \|\phi\|_s \theta(s)^{-1} \lambda \frac{(d(m+1))!}{(m+1)^\beta} A_m \end{aligned}$$

where

$$A_m = \sum_{k=0}^m \binom{m}{k} \frac{(d(m-k+1))!(d(k+1))!}{(d(m+1))!} \left( \frac{m+1}{(m-k+1)(k+1)} \right)^\beta.$$

But

$$\begin{aligned} &\binom{m}{k} \frac{(d(m-k+1))!(d(k+1))!}{(d(m+1))!} \\ &\leq \binom{dm}{dk} \frac{(d(m-k+1))!(d(k+1))!}{(d(m+1))!} \\ &\leq \frac{(d(m-k)+1) \cdots (d(m-k)+d)(dk+1) \cdots (dk+d)}{(dm+1) \cdots (dm+d)} \\ &\leq d^{2d} \frac{(m-k+1)(k+1)}{m+1} \end{aligned}$$

by (4.2) and (4.3). Thus

$$\begin{aligned}
A_m &\leq d^{2d} \sum_{k=0}^m \left( \frac{m+1}{(m-k+1)(k+1)} \right)^{\beta-1} \\
&\leq d^{2d} \sum_{k=0}^m \left( \frac{2}{k+1} \right)^{\beta-1} \\
&\leq d^{2d} \sum_{k=0}^{\infty} \left( \frac{2}{k+1} \right)^{\beta-1} \\
&=: A_{\infty}.
\end{aligned}$$

Since  $\beta > 2$ ,  $A_{\infty} < \infty$ . By choosing  $C > A_{\infty}$ , the result follows by induction and the proof is complete. ■

**Remark 4.3.** *The point in introducing the factor  $\tilde{n}^{\beta}$  in the definition 4.1 is that for  $\beta > 1$  the spaces  $B_s(d, \beta)$  become Banach algebras and for  $\beta > 2$ , the estimate in Proposition 4.3 is valid.*

It is clear that there should be some kind of relationship between the spaces  $B_s(d, \beta)$  and the Gevrey class 2 functions.

**Definition 4.2.** *Let  $\Omega$  be a subset of  $\mathbf{R}^n$  and  $\delta > 0$ . A  $C^{\infty}$  function  $f$  in  $\Omega$  is said to be of Gevrey class  $\delta$  in  $\Omega$  (in short,  $f \in \gamma^{\delta}(\Omega)$ ) if there exist positive constants  $C$  and  $H$  such that*

$$|D_t^{\alpha} f(x)| \leq CH^{|\alpha|} (\delta^{|\alpha|})!$$

for all multi-indices  $\alpha$  and for all  $x \in \Omega$ .

**Remark 4.4.** *The definition given here of a Gevrey class of functions is different from that in [4] where the fact that that Gevrey class of functions forms an algebra is proved. But, by easy computation, we can also show that, under our definition, the Gevrey class of functions forms as algebra. It is also easy to check that there is an obvious inclusion in both definitions.*

The proof of the following proposition is clear.

**Proposition 4.4.** *For the case of one dimensional compact interval  $K$ ,*

- (a) *The space  $B_s(d, \beta)$  is contained in  $\gamma^d$ , i.e. if  $\phi \in B_s(d, \beta)$  then  $\phi$  belongs to Gevrey class  $d$ .*
- (b) *Suppose  $\phi : \mathbf{R} \rightarrow \mathbf{R}$  is an infinitely differentiable function defined in  $K$  and there are positive constants  $M$  and  $\theta$  such that*

$$|\partial_t^j \phi(t)| \leq M\theta^j (dj)!$$

*for all  $t$  and for all  $j = 1, 2, \dots$ . If  $\theta < \theta_1$ , then  $\phi \in B_s(d, \beta)$  for all  $s \in [0, 1]$ ,  $d \geq 1$ ,  $\beta > 2$ .*

**Proposition 4.5.** *Let  $d, \beta$  denote fixed real parameters such that  $d > 1$ ,  $\beta > 2$ . Suppose that  $f(z, x)$  is a real valued function on  $\mathbf{R}^2$  which is infinitely differentiable with respect to its first argument and that for every compact  $z$ -interval  $I$  there exist two constants  $M > 0$ ,  $a > 0$  such that for  $n = 0, 1, 2, \dots$  and all  $(z, x) \in I \times \{x \in \mathbf{R} \mid |x| \leq \delta\}$ ,*

$$|D_z^n f(z, x)| \leq M a^n \frac{(dn)!}{\tilde{n}^\beta} \quad (4.5)$$

*where  $\delta$  is some number  $> 0$  and  $\tilde{n} = \max(1, n)$ , i.e.  $f \in \gamma^d$  (it is easy to check that the above statement is equivalent to the definition of Gevrey class  $d$  functions).*

*We define a map  $F$  on  $B_s(d, \beta) \times \{x \in \mathbf{R} \mid |x| \leq \delta\}$  by*

$$F(u, x)(t) = f(u(t), x). \quad (4.6)$$

*Then  $F$  is a map from  $B_s(d, \beta) \times \{x \in \mathbf{R} \mid |x| \leq \delta\}$  into  $B_{s'}(d, \beta)$ ,  $0 \leq s' \leq s \leq 1$ .*

**PROOF:** First, we remark that since  $u$  is a real valued function and  $f$  is globally defined,  $F$  is well defined.

For functions  $u \in B_s(d, \beta)$ ,  $u$  is infinitely differentiable defined in a compact set  $K$ , so we can only consider  $f(z, x)$  with  $(z, x)$  being restricted to a bounded set. According to Hörmander[4], there are functions in  $\gamma^d$  having compact support and forming partitions of unity subordinated to arbitrary locally finite open coverings and consisting of non-negative functions. Therefore, as these functions form multiplication algebras, without loss of generality, we may assume that

$$\text{supp } f \subset \{(z, x) \in \mathbf{R}^2 \mid |z| \leq (2aC\lambda)^{-1}, |x| \leq \delta\} \quad (4.7)$$

where  $\lambda$  is defined in (4.1),  $C$  is the constant in Proposition 4.3 and  $a$  is the constant in (4.5).

By the definition of the  $s'$ -norm (4.1), we have

$$\|F(u, x)\|_{s'} \leq \sup_{n \geq 0} \sup_{t \in K} \left( \frac{\theta(s')^n \tilde{n}^\beta}{(dn)! \lambda} |D_t^n F(u, x)| \right) \quad (4.8)$$

where  $D_t^n$  denotes the  $n$ -th derivative of the real valued function  $t \rightarrow F(u(t), x)$  ( $x$  fixed).

For  $n \geq 1$ , we estimate as follows (see [1]),

$$|D_t^n F(u, x)| \leq \sum_{j=1}^n \binom{n-1}{j-1} |D_z^j f(z, x)| \cdot |D_t^{m-j}(u_t^j)|$$

and apply (4.5) and Proposition 4.3 to get

$$\begin{aligned} \sup_{t \in K} |D_t^n F(u, x)| &\leq \sum_{j=1}^n \binom{m-1}{j-1} M a^j \frac{(dj)!}{j^\beta} [\|u\|_s \theta(s)^{-1} \lambda C]^{j-1} \lambda \|u\|_s \\ &\quad \cdot \theta^{-(n-j+1)} \frac{(d(n-j+1))!}{(n-j+1)^\beta}. \end{aligned}$$

Then from (4.8), we have

$$\|F(u, x)\|_{s'} \leq \max \left( M \sup_{n \geq 1} A_n, \sup_{t \in K} \frac{1}{\lambda} |F(u, x)| \right),$$

where

$$A_n = \sum_{j=1}^n \binom{n-1}{j-1} \left( \frac{(dj)!(d(n-j+1))!}{(dn)!} \right) \left( \frac{n}{j(n-j+1)} \right)^\beta \vartheta^j \frac{1}{\lambda C}$$

with  $\vartheta = aC\lambda\|u\|_1$ . In view of (4.7) and the definition of the  $s$ -norm, it will suffice to consider  $\vartheta < \frac{1}{2}$ . We observe that

$$\binom{n-1}{j-1} \left( \frac{(dj)!(d(n-j+1))!}{(dn)!} \right) \leq d^{2d} \cdot \frac{j(n-j+1)}{n}$$

and

$$\frac{n}{j(n-j+1)} \leq \frac{1}{j} + \frac{1}{n-j+1} \leq 2$$

for  $1 \leq j \leq n$ . This then implies

$$A_n \leq \frac{1}{\lambda C} d^{2d} 2^{\beta-1} \sum_{j=1}^n 2^{-j} \leq \frac{1}{\lambda C} d^{2d} 2^{\beta-1} < \infty$$

for all  $n$ . Therefore

$$\|F(u, x)\|_{s'} < \infty$$

and thus  $F(u, x) \in B_{s'}(d, \beta)$ ,  $0 \leq s' \leq s \leq 1$ . ■

**5. Solutions of the Cauchy problem in the  $x$ -direction.** In this section, we shall solve the following problem by using the modified Ovcyannikov Theorem (Theorem 2.1):

$$u_t - u_{xx} = f(u, x) \quad \text{for } x \in (0, 2), t \geq T_0 \quad (5.1)$$

$$u(0, t) = 0, \quad u_x(0, t) = g(t) \quad \text{for } t \geq T_0, \quad (5.2)$$

where  $T_0$  is a positive constant.

**Theorem 5.1.** *Let the function  $f(u, x)$  belong to Gevrey class 2 locally in its first argument, varying continuously with respect to  $x$  and satisfy  $f(0, x) = 0$  and  $D_1 f(0, x) = 0$  for all  $x \in [0, 2]$ . Let  $g(t)$  be a function of Gevrey class 2 in  $t \geq T_0$  and  $g(t) = 0$  for  $t \geq T$  for some  $T > T_0$ . Then there exists a constant  $a > 0$  such that the problem (5.1)–(5.2) has a solution  $u(x, t)$  which is twice continuously differentiable with respect to  $x$  for  $x < a$ , infinitely differentiable with respect to  $t$  for  $t \in [T_0, \infty)$ , bounded for  $x < a$ ,  $t \in [T_0, \infty)$  and vanishes for  $t \geq T$ . Moreover, when  $g(t)$  is small enough, the  $x$ -interval of existence will be greater than 1, i.e.  $a > 1$ .*

**PROOF:** First of all, we rewrite the problem (5.1)–(5.2) as the following Cauchy problem

$$u_{xx} = u_t - f(u, x) \quad \text{for } x \in (0, 2), t \geq T_0 \quad (5.3)$$

$$u(0, t) = 0, \quad u_x(0, t) = g(t) \quad \text{for } t \geq T_0 \quad (5.4)$$

To apply Theorem 2.1, we convert the problem (5.3)–(5.4) to a first order system of differential equations by introducing the variables  $v_1 = u$ ,  $v_2 = u_x$ , and  $v_3 = u_t$ . Then (5.3)–(5.4) can be rewritten as

$$\frac{dv_1}{dx}(x, \cdot) = v_2(x, \cdot) \quad (5.5)$$

$$\frac{dv_2}{dx}(x, \cdot) = v_3(x, \cdot) - f(v_1(x, \cdot), x) \quad (5.6)$$

$$\frac{dv_3}{dx}(x, \cdot) = \frac{\partial}{\partial t} v_2(x, \cdot) \quad (5.7)$$

with the Cauchy data

$$v_1(0, \cdot) = 0, v_2(0, \cdot) = g(\cdot), v_3(0, \cdot) = 0. \quad (5.8)$$

For  $s \in [0, 1]$ , let  $X_s = B_s(2, 4)$ , where  $B_s(d, \beta)$  is defined in Section 4 with  $K = [T_0, T + \epsilon]$  where  $\epsilon$  is any finite number,  $d = 2$ ,  $\beta = 4$ ,  $\lambda$  any fixed constant satisfying the assumption of Proposition 4.1, and the constants  $\theta_0$  and  $\theta_1$  satisfying  $0 < \theta_0 < \theta_1 < \infty$ . The constant  $\theta_0$  will be chosen sufficiently small so that the constant  $C$  in Proposition 4.2 is sufficiently small after  $\theta_1$  is chosen sufficiently large (see below).

For simplification of notation, we let

$$F_1(v_2) = v_2 \quad (5.9)$$

$$F_2(v_1, v_3, x) = v_3 - f(v_1, x) \quad (5.10)$$

$$F_3(v_2) = \frac{\partial}{\partial t} v_2. \quad (5.11)$$

We use the same notations as in Theorem 2.1. Let  $X_s^i = X_s$ ,  $i = 1, 2, 3$ , and  $R_{1,0} = R_{3,0} = 0$ ,  $R_{2,0} = \|g\|_1$ . Then by Proposition 4.4 it is easy to check that  $0 < R_{2,0} < \infty$  if  $\theta_1$  is large enough and by Proposition 4.5, assumption (H2) in Theorem 2.1 is satisfied for  $R_1 > 0$ ,  $R_2 > R_{2,0}$  and  $R_3 > 0$ . It is also clear that for any  $R_1 > 0$ ,  $R_2 > R_{2,0}$ , and  $R_3 > 0$  the assumptions (H3) and (H4) of Theorem 2.1 are satisfied with  $\alpha_1 = 0$ ,  $\alpha_2 = 0$  and  $\alpha_3 = 2$ . In fact, (H2) follows from Proposition 4.5; (H3) follows from Proposition 4.2 with  $P(\lambda, \mu) = \lambda^3 - c_2^3 c_3^2 \lambda \mu^2 - c_1^2 c_2^1 \lambda$ ; and (H4) is clear.

According to Theorem 2.1, there exist a constant  $a > 0$  and a unique solution of the Cauchy problem (5.5)–(5.8) such that  $u(x, \cdot) = v_1(x, \cdot)$  is a twice continuously differentiable function of  $x$  for  $|x| < a$  with values in  $X_0$  and  $\|u(x, \cdot)\|_0 < R_1$  for  $|x| < a$ . Since  $u(x, \cdot) \in X_0$  for  $|x| < a$ ,  $u(x, t)$  is infinitely differentiable in  $t$  for  $T_0 \leq t \leq T + \epsilon$  and  $u(x, t)$  is bounded on  $|x| < a$ ,  $t \geq T_0$ . By using L. Nirenberg's Uniqueness Theorem[20] and the fact that the Cauchy data is zero for  $T \leq t \leq T + \epsilon$ , the solution  $u(x, t)$  obtained above vanishes for  $T \leq t \leq T + \epsilon$ . By defining  $u(x, t)$  to be zero for  $|x| < a$ ,  $t \geq T + \epsilon$ ,  $u(x, t)$  is a solution of (5.1)–(5.2) which is infinitely differentiable with respect to  $t$  for  $t \geq T_0$ , bounded on  $|x| < a$ ,  $t \geq T_0$  and vanishes for  $t \geq T$ .

It is interesting to see how large we can make for the interval of existence. To obtain the estimate, we shall check the proof of Theorem 2.1 and keep track of all constants. First, for any constants  $R_1 > 0$ ,  $R_2 > R_{2,0}$ ,  $R_3 > 0$  and for  $v_i, \tilde{v}_i \in X_s$ ,  $i = 1, 2, 3$ ,  $s \in [0, 1]$  with  $\|v_i\|_s < R_i$ ,  $\|\tilde{v}_i\|_s < R_i$ , and  $|x| < \eta$ , where  $\eta$  can be any large number for our problem, we have for  $0 \leq s' < s \leq 1$ ,

$$\|F_1(v_2) - F_1(\tilde{v}_2)\|_{s'} \leq \|v_2 - \tilde{v}_2\|_s \quad (5.12)$$

$$\begin{aligned} \|F_2(v_1, v_3, x) - F_2(\tilde{v}_1, \tilde{v}_3, x)\|_{s'} &\leq \|v_3 - \tilde{v}_3\|_s + \|f(v_1, x) - f(\tilde{v}_1, x)\|_s \\ &\leq \|v_3 - \tilde{v}_3\|_s + N\|v_1 - \tilde{v}_1\|_s \end{aligned} \quad (5.13)$$

$$\|F_3(v_2) - F_3(\tilde{v}_2)\|_{s'} \leq \frac{C}{(s - s')^2} \|v_2 - \tilde{v}_2\|_s \quad (5.14)$$

where  $N$  is a constant depending on  $R_1$  which will become sufficiently small when  $R_1 \rightarrow 0$  by the assumption  $D_1 f(0, x) = 0$ ; and  $C$  is the constant in Proposition 4.2 which can be chosen sufficiently small.

Now, to get a more accurate estimate of the interval of existence, let us go back to check the proof of Theorem 2.1. Since  $v_1(0) = v_3(0) = 0$ , by using (3.13) with  $e_1 = 1$ ,  $e_2 = 1$ ,  $e_3 = 2$  and the inequalities (5.12)–(5.14) we get

$$\begin{aligned} \lambda_1^{(0)} &\leq 4a_0 R_{2,0} \\ \lambda_2^{(0)} &= 0 \\ \lambda_3^{(0)} &\leq 4Ca_0^2 R_{2,0} \\ \lambda_1^{(k+1)} &\leq 4a_0 \lambda_2^{(k)} \\ \lambda_2^{(k+1)} &\leq 4(Na_0 \lambda_1^{(k)} + \lambda_3^{(k)}) \\ \lambda_3^{(k+1)} &\leq 4Ca_0^2 \lambda_2^{(k)} \end{aligned}$$

and thus

$$\begin{aligned} \lambda_1^{(2k+1)} &= 0, \lambda_2^{(2k)} = 0, \lambda_3^{(2k+1)} = 0 \\ \lambda_2^{(1)} &\leq \gamma R_{2,0} \\ \lambda_1^{(2k)} &\leq 4a_0 \gamma^k R_{2,0} \\ \lambda_2^{(2k+1)} &\leq \gamma^{k+1} R_{2,0} \\ \lambda_3^{(2k)} &\leq 4Ca_0^2 \gamma^k R_{2,0} \end{aligned}$$

for  $k \geq 0$ , where  $\gamma = 16(N + C)a_0^2$ . If we take  $R_2 > 17R_{2,0}$  and

$$a_0 < \min\left\{\frac{R_1}{64R_{2,0}}, \frac{1}{16\sqrt{2C}} \left(\frac{R_3}{R_{2,0}}\right)^{1/2}, \eta_i, i = 1, 2, 3\right\} \quad (5.16)$$

so that  $\gamma < 1/64$ , then (3.5) is satisfied and thus the theorem holds with  $a = a_0/2$ .

To obtain  $a > 1$ , we require that

$$\min\left\{\frac{1}{32\sqrt{N + C}}, \frac{R_1}{64R_{2,0}}, \frac{1}{16\sqrt{2C}} \left(\frac{R_3}{R_{2,0}}\right)^{1/2}\right\} > 2. \quad (5.17)$$

This can be obtained when the "initial data"  $g(t)$  is sufficiently small. Because when this term is small the quantity  $R_{2,0} \equiv \|g(t)\|_1$  is small and so we can only consider small  $R_1$  which makes  $N$  small.

We remark that the interval  $[0, a)$ , where  $a = a_0/2$  and  $a_0$  is given above, is not necessary the largest length of the interval of existence, because we have not always chosen the best possible constants in our argument. However, the estimate (5.16) is sufficient for our purpose. ■

**Remark.** *In that main theorem, we need the analyticity of function  $f$  to guarantee that  $w_x(0, t)$  belongs to Gevrey class 2 but in Theorem 5.1, we only need to assume that  $f$  is of Gevrey class 2 in  $t$  to obtain existence for problem (5.3)-(5.4).*

**6. Existence of Boundary Controller.** In this section, we shall prove our principal result on the existence of the boundary controller  $h(t)$  that steers a prescribed initial data  $w_0$  to the zero for the problem (1.1)–(1.4). The controller  $h(t)$  will be continuously differentiable on a finite time duration  $0 \leq t \leq T$  with  $T > 0$ .

**Theorem 6.1.** *Suppose that  $f(s, x)$  is an analytic function in  $s$  and  $x$  in a neighborhood of the origin and belongs locally to Gevrey class 2 in  $s$  and is Hölder continuous in  $x \in [0, 1]$  and satisfy  $f(0, x) = 0$ ,  $D_1 f(0, x) = 0$  for all  $x \in [0, 1]$ . Let the initial data  $w_0(x)$  be a continuous sufficiently small function<sup>1</sup> in  $[0, 1]$ . Then for any finite time  $T > 0$ , there*

---

<sup>1</sup>the "sufficiently small" assumption can be dropped for some cases, see remark after the proof of Theorem 6.1

exists a controller  $h(t) \in C^\infty((0, \infty)) \cap C([0, \infty))$  such that the solution  $w(x, t)$  of (1.1)–(1.4) satisfies  $w(x, T) \equiv 0$  for  $x \in [0, 1]$ .

PROOF: We organize the proof in a series of steps.

**Step 1.** Extend the domain of the initial data  $w_0(x)$  to be  $[0, 2]$  so that  $w_0(x)$  is continuous and the sup norm of the modified initial data is less than or equal to the sup norm of the original initial data. We also extend the domain of  $f$  to be  $(-\infty, \infty) \times (0, 2)$  so that all properties of  $f$  are maintained.

**Step 2.** We solve the initial-boundary value problem with the new modified initial condition:

$$w_t - w_{xx} = f(w, x) \quad \text{on } (0, 2) \times (0, \infty) \quad (6.1)$$

$$w(0, t) = 0 \quad \text{for } t \geq 0 \quad (6.2)$$

$$w(2, t) = 0 \quad \text{for } t \geq 0 \quad (6.3)$$

$$w(x, 0) = w_0(x) \quad \text{for } x \in (0, 2). \quad (6.4)$$

It is well-known that the solution  $w(x, t)$  exists locally and it is bounded [9]. Let  $T_1$  be any number such that the solution of (6.1)–(6.4) exists for  $t \leq T_1$  and  $\epsilon < T_1$  be any small positive number so that  $f(w, x)$  is an analytic function in the range of values assumed by  $w, x$  for  $x \in [0, 2\epsilon]$ . Then it is also clear that the solution  $w(x, t)$  is a  $C^\infty$  function for  $0 \leq x \leq 2\epsilon$  and  $\epsilon \leq t \leq T_1$  because the nonlinear term  $f(w, x)$  is infinitely differentiable in  $w$  and  $x$  [2,12].

**Step 3.** We claim that the solution  $w(x, t)$  obtained in Step 2 belongs to Gevrey class 2 in  $t$  for  $t \leq T_1$ . Let  $u_0(x) = w(x, \epsilon)$ , where  $\epsilon < T_1$  is any small positive number as in the Step 2. Since  $w(x, t)$  is a  $C^\infty$  solution of the problem

$$w_t - w_{xx} = f(w, x) \quad \text{on } (0, 2\epsilon) \times (\epsilon, T_1]$$

$$w(0, t) = 0 \quad \text{for } \epsilon \leq t \leq T_1$$

$$w(x, \epsilon) = u_0(x) \quad \text{for } x \in (0, 2\epsilon),$$

it follows from a theorem of D. Kinderlehrer and L. Nirenberg[11] that  $w(x, t)$  is real analytic in  $x$  and is of Gevrey class 2 in  $t$  for  $0 \leq x \leq \epsilon$  and  $2\epsilon \leq t \leq T_1$ . In fact, the

derivatives of  $w(x, t)$  satisfy

$$|\partial_x^\lambda \partial_t^j w| \leq CH^{j+2\lambda}(j+2\lambda)!, \quad \forall \lambda, j,$$

for some constants  $C$  and  $H$ . Thus  $w_x(0, t)$  belongs to the Gevrey class 2 in  $t$  for  $2\epsilon \leq t \leq T_1$ .

One can easily see, by contradiction and compactness, that small initial data  $w_0(x)$  in sup norm implies small  $w_x(0, t)$  in Gevrey class 2 norm for  $t \in [2\epsilon, T]$  when  $T$  is a small number less than  $T_1$ .

**Step 4.** Since the initial data  $w_0(x)$  is sufficiently small in sup norm, let us assume that the time interval  $[2\epsilon, T]$  is small enough for  $2\epsilon \leq t \leq T$ , so that  $w_x(0, t)$  is sufficiently small for  $2\epsilon \leq t \leq T$ .

Next, we modify  $w_x(0, t)$  to be a function  $w_x(0, t)\psi(t)$  with support in  $[0, T]$ . Here  $\psi(t)$  is  $C^\infty$  on  $0 \leq t < \infty$  satisfying

$$\begin{aligned} 0 &\leq \psi(t) \leq 1 \\ \psi(t) &= 0 \quad \text{for } t \geq T \\ \psi(t) &= 1 \quad \text{for } 0 \leq t \leq (T + 2\epsilon)/2 \end{aligned}$$

With some care we can take  $\psi(t)$  to be of the Gevrey class 2 for  $t \geq 2\epsilon$  (see [4]). We note that the definition of the Gevrey class 2 in [4] is different from the one we use in this paper which is the same as that in [3]. But it is easy to check that the Gevrey class 2 functions constructed in [4] satisfy our definition.

Let

$$g(t) = \begin{cases} w_x(0, t)\psi(t), & \text{for } 2\epsilon \leq t \leq T \\ 0, & \text{for } t \geq T. \end{cases}$$

Since the Gevrey class of functions forms an algebra which is closed under multiplication,  $g(t) \in \gamma^2$  in  $t$  for  $t \geq 2\epsilon$  and vanishes for  $t \geq T$ . When  $T$  is small,  $g(t)$  will be sufficiently small because  $\|w_x(0, t)\|_1$  is sufficiently small.

**Step 5.** In this step, we solve the Cauchy problem:

$$u_t - u_{xx} = f(u, x) \quad \text{on } (0, 2) \times (2\epsilon, \infty) \tag{6.5}$$

$$u(0, t) = 0, \quad u_x(0, t) = g(t) \quad \text{for } t \geq 2\epsilon. \tag{6.6}$$

Since  $g(t)$  is small, it follows from Theorem 5.1 that there exist a constant  $a > 1$  and a solution  $u(x, t)$  of (6.5)–(6.6) which is twice continuously differentiable in  $x$  for  $x < a$ , infinitely differentiable in  $t$  for  $t \geq 2\epsilon$ , bounded for  $x < a$  and  $t \geq 2\epsilon$  and vanishes for  $t \geq T$ .

**Step 6.** Before we give the conclusion, we still need to show that  $w(x, t)$  which we obtain in Step 2 and  $u(x, t)$  which we get in Step 5 agree in  $[2\epsilon, (T + 2\epsilon)/2]$ . First, we observe that  $w$  and  $u$  are both bounded functions in  $[0, 1] \times [2\epsilon, (T + 2\epsilon)/2]$ . Let  $z(x, t) = w(x, t) - u(x, t)$ . Then by Mean Value Theorem,

$$|z_t - z_{xx}|^2 = |f(w, x) - f(u, x)|^2 \leq C|z|^2$$

on  $[0, 1] \times [2\epsilon, (T + 2\epsilon)/2]$  for some constant  $C$ . On the other hand,  $z(0, t) = 0$  and  $z_x(0, t) = 0$  for  $t \in [2\epsilon, (T + 2\epsilon)/2]$ , i.e., the Cauchy data are zero. Hence, by L. Nirenberg's Theorem[20],  $z \equiv 0$  on  $[0, 1] \times [2\epsilon, (T + 2\epsilon)/2]$ . This shows that  $w(x, t)$  and  $u(x, t)$  are identical on  $[0, 1] \times [2\epsilon, (T + 2\epsilon)/2]$ .

**Step 7.** Now comes our final step. We will read off the require boundary controller  $h(t)$  through  $w(x, t)$  and  $u(x, t)$  by defining  $h(t) = w(1, t)$  for  $0 \leq t \leq 2\epsilon$  and  $h(t) = u(1, t)$  for  $t \geq 2\epsilon$ .

This proves the theorem. ■

**Remark.** *If the initial-boundary value problem (6.1)–(6.4) has a global solution  $w(x, t)$  and  $w(x, t) \rightarrow 0$  as  $t \rightarrow \infty$  for continuous initial data  $w_0(x)$ , for example if  $f(x, u) = u^p$  for  $p > 1$  (see [18]), then we can drop the "sufficiently small" assumption on the initial data and obtain the null boundary controllability for problem (1.1)–(1.4) for time  $T$  sufficiently large because when the time is sufficiently large,  $w_x(0, t)$  will be sufficiently small and belongs to Gevrey class 2 in  $t$ , say  $t > T_0$ , and thus by substituting  $T_0$  for  $2\epsilon$  in steps 4-7 in the proof of Theorem 6.1 and take  $T > T_0$ , the result follows.*

**7. The Null Boundary Controllability For a Semilinear Heat Equation With Nonlinear Term  $f(w, w_x, x)$ .** In this section, we consider the null boundary controlla-

bility problem of the following problem:

$$w_t - w_{xx} = f(w, w_x, x) \quad \text{on } (0, 1) \times (0, \infty) \quad (7.1)$$

$$w(0, t) = 0 \quad \text{for } t \geq 0 \quad (7.2)$$

$$w(x, 0) = w_0(x) \quad \text{for } x \in (0, 1] \quad (7.3)$$

$$w(1, t) = h(t) \quad \text{for } t \geq 0 \quad (7.4)$$

where  $f$  is an analytic function in all arguments near  $(0, 0, 0)$  and belongs locally to Gevrey class 2 in the first two arguments and is Hölder continuous with respect to  $x$  such that  $f(0, 0, x) = 0$ ,  $D_1 f(0, 0, x) = 0$  and  $D_2 f(0, 0, x) = 0$  for all  $x \in [0, 1]$ , where  $D_i$  is the derivative with respect to  $i$ -th argument,  $i = 1, 2$ . The problem is to find a controller  $h(t)$  so that the solution of the resulting problem vanishes for  $t \geq T$  for finite time  $T > 0$ . We will use the same method as that in previous section with little modification. We also use the same notations as before.

The main theorem of this section is the following:

**Theorem 7.1.** *Suppose that  $f(y, z, x)$  is an analytic function in  $y, z$  and  $x$  near  $(0, 0, 0)$ , belongs to Gevrey class 2 locally in  $y$  and  $z$ , is Hölder continuous in  $x \in [0, 1]$  and satisfies  $f(0, 0, x) = 0$ ,  $D_1 f(0, 0, x) = 0$ ,  $D_2 f(0, 0, x) = 0$  for all  $x \in [0, 1]$ . Let the initial data  $w_0(x)$  be a sufficiently small  $C^1$  function in  $[0, 1]$ . Then for any finite time  $T > 0$ , there exists a controller  $h(t) \in C^\infty((0, \infty)) \cap C([0, \infty))$  such that the solution  $w(x, t)$  of (7.1)–(7.4) satisfies  $w(x, T) \equiv 0$  for  $x \in [0, 1]$ .*

**Remarks.**

- (i) *The "sufficiently small" assumption on initial data can be dropped if the following initial boundary value problem*

$$w_t - w_{xx} = f(w, w_x, x) \quad \text{on } (0, 2) \times (0, \infty) \quad (7.5)$$

$$w(0, t) = 0 \quad \text{for } t \geq 0 \quad (7.6)$$

$$w(2, t) = 0 \quad \text{for } t \geq 0 \quad (7.7)$$

$$w(x, 0) = w_0(x) \quad \text{for } x \in (0, 2) \quad (7.8)$$

has a global solution  $w(x, t)$  and  $w(x, t) \rightarrow 0$  as  $t \rightarrow \infty$ .

- (ii) By Mora's paper ([19]),  $L^p$  estimate ([12]) and the existence theorem ([2]), the condition we impose on the initial data gives the local existence of problem (7.5)-(7.8). Other conditions which are not as restricted can also give local existence of (7.5)-(7.8) but they require other regularity on  $f$  (see [12]).
- (iii) When we solve our problem and extend the domain of the initial data to be  $[0, 2]$ , besides the smallness of  $w_0(x)$ , we require  $w_0(x) \equiv 0$  in a neighborhood of 2 so that we can obtain local existence for problem (7.5)-(7.8).

The proof of Theorem 7.1 is similar to the proof of Theorem 6.1. The differences are that we need a proposition similar to Proposition 4.5 to claim that the assumptions of Theorem 2.1 are satisfied and we have to solve the Cauchy problem

$$u_t - u_{xx} = f(u, u_x, x) \quad \text{on } (0, 2) \times (2\epsilon, \infty) \quad (7.9)$$

$$u(0, t) = 0, u_x(0, t) = g(t) \quad \text{for } t \geq 2\epsilon \quad (7.10)$$

where  $\epsilon$  is an small number and  $f$  is the extended function of the function  $f$  in Theorem 7.1 with domain  $[0, 2]$  which preserves all properties. We will solve this Cauchy problem in Theorem 7.2.

Now, here is the proposition similar to Proposition 4.5 which will be used to fulfill the assumptions of Theorem 2.1.

**Proposition 7.1.** *Let  $d, \beta$  denote fixed real parameters such that  $d > 1, \beta > 2$ . Suppose that  $f(y, z, x)$  is a real valued function on  $\mathbf{R}^2$  which is infinitely differentiable with respect to its first two arguments and that for every compact set  $I$  in  $y, z$  space, there exist two constants  $M > 0, a > 0$  such that for  $m = 0, 1, 2, \dots, n = 0, 1, 2, \dots$  and all  $(y, z) \in I$  and  $x \in \{x \in \mathbf{R} \mid |x| \leq \delta\}$ ,*

$$|D_y^m D_z^n f(y, z, x)| \leq M a^{m+n} \frac{(d(m+n))!}{((m+n)\sim)^\beta} \quad (7.11)$$

where  $\delta$  is some number  $> 0$  and  $\tilde{n} = \sup(1, n)$ , i.e.  $f \in \gamma^d$  in its first two arguments.

We define a map  $F$  on  $B_s(d, \beta) \times B_s(d, \beta) \times \{x \in \mathbf{R} \mid |x| \leq \delta\}$  by

$$F(u, v, x)(t) = f(u(t), v(t), x) \quad (7.12)$$

Then  $F$  is a map from  $B_s(d, \beta) \times B_s(d, \beta) \times \{x \in \mathbf{R} \mid |x| \leq \delta\}$  into  $B_{s'}(d, \beta)$ ,  $0 \leq s' \leq s \leq 1$ .

PROOF: With the same reason as in the proof of Proposition 4.5, without loss of generality, we may assume that

$$\text{supp } f \subset \{(y, z, x) \in \mathbf{R}^2 \mid |y| \leq (2aC\lambda)^{-1}, |z| \leq (2aC\lambda)^{-1}, |x| \leq \delta\} \quad (7.13)$$

where  $\lambda$  is defined in (4.1),  $C$  is the constant in Proposition 4.3 and  $a$  is the constant in (7.11).

By the definition of the  $s'$ -norm (4.1), we have

$$\|F(u, v, x)\|_{s'} \leq \sup_{n \geq 0} \sup_{t \in K} \left( \frac{\tilde{n}^\beta \theta(s')^n}{\lambda(dn)!} |D_t^n F(u, v, x)| \right) \quad (7.14)$$

where  $D_t^n$  denotes the  $n$ -th derivative of the real valued function  $t \rightarrow F(u(t), v(t), x)$  ( $x$  fixed). For  $n \geq 1$ , we estimate as follows (see [1]),

$$|D_t^n F(u, v, x)| \leq \sum_{m=1}^n \sum_{j=0}^m \binom{n-1}{m-1} \binom{m}{j} |D_y^{m-j} D_z^j f(y, z, x)| \cdot |D_t^{n-m} (u_t^{m-j} v_t^j)| \quad (7.15)$$

By Leibniz' rule and Proposition 4.3, we get

$$\begin{aligned} \sup_{t \in K} |D_t^{n-m} (u_t^{m-j} v_t^j)| &\leq \sum_{k=0}^{n-m} \binom{n-m}{k} \sup_{t \in K} |D_t^k (u_t^{m-j})| \cdot \sup_{t \in K} |D_t^{n-m-k} (v_t^j)| \\ &\leq \sum_{k=0}^{n-m} \binom{n-m}{k} (C\|u\|_s \theta(s)^{-1} \lambda)^{m-j-1} \|u\|_s \theta(s)^{-(k+1)} \lambda \frac{(d(k+1))!}{(k+1)^\beta} \\ &\quad \cdot (C\|v\|_s \theta(s)^{-1} \lambda)^{j-1} \|v\|_s \theta(s)^{-(n-m-k+1)} \lambda \cdot \frac{(d(n-m-k+1))!}{(n-m-k+1)^\beta} \\ &= \sum_{k=0}^{n-m} \binom{n-m}{k} (C\lambda\|u\|_s)^{m-j} (C\lambda\|v\|_s)^j \frac{[\theta(s)^{-1}]^n}{C^2} \cdot \frac{(d(k+1))!}{(k+1)^\beta} \cdot \frac{(d(n-m-k+1))!}{(n-m-k+1)^\beta} \end{aligned}$$

thus, from (7.11) and (7.15), we get

$$\begin{aligned} &\sup_{t \in K} \frac{n^\beta [\theta(s')]^n}{\lambda(dn)!} |D_t^n F(u, v, x)| \\ &\leq \sum_{m=1}^n \sum_{j=0}^m \binom{n-1}{m-1} \binom{m}{j} M a^m \frac{(dm)!}{m^\beta} \sum_{k=0}^{n-m} \binom{n-m}{k} (C\lambda\|u\|_s)^{m-j} (C\lambda\|v\|_s)^j \\ &\quad \cdot \frac{[\theta(s)^{-1}]^n}{C^2} \cdot \frac{(d(k+1))!}{(k+1)^\beta} \cdot \frac{(d(n-m-k+1))!}{(n-m-k+1)^\beta} \cdot \frac{[\theta(s)^{-1}]^n n^\beta}{\lambda(dn)!} \\ &\leq \frac{M}{\lambda C^2} \sum_{m=1}^n \sum_{j=0}^m \sum_{k=0}^{n-m} \vartheta_1^{m-j} \vartheta_2^j A_{n-1, m-1} A_{m, j} A_{n-m, k} B_{m, j} \end{aligned} \quad (7.16)$$

where

$$\begin{aligned}\vartheta_1 &= aC\lambda\|u\|_s, \vartheta_2 = aC\lambda\|v\|_s, \\ A_{i,j} &= \binom{i}{j} \frac{(d(j+1))!(d(i-j+1))!}{(d(i+1))!} \left[ \frac{i+1}{(j+1)(i-j+1)} \right]^\beta, \\ B_{m,j} &= \binom{m}{j}^{-1} A_{m,j}.\end{aligned}$$

In view of (7.13) and the definition of the  $s$ -norm, it will suffice to consider  $\vartheta_1 < \frac{1}{2}$  and  $\vartheta_2 < \frac{1}{2}$ . According to the proof of Proposition 4.3 and Proposition 4.5, we have

$$\begin{aligned}\sum_{k=0}^{n-m} A_{n-m,k} &\leq d^{2d} \sum_{k=0}^{\infty} \left( \frac{2}{k+1} \right)^{\beta-1} \\ A_{m,j} &\leq d^{2d} \left( \frac{m+1}{(j+1)(m-j+1)} \right)^{\beta-1} \\ &\leq d^{2d} \left( \frac{2}{j+1} \right)^{\beta-1} \\ B_{m,j} &\leq A_{m,j} \leq d^{2d} \left( \frac{2}{j+1} \right)^{\beta-1}\end{aligned}$$

for  $0 \leq j \leq m$ . Thus,

$$\begin{aligned}&\sup_{t \in K} \frac{n^\beta [\theta(s')]^n}{\lambda(dn)!} |D_t^n F(u, v, x)| \\ &\leq \frac{M}{\lambda C^2} \sum_{m=1}^n \left( \frac{1}{2} \right)^m A_{n-1, m-1} \left[ \sum_{j=0}^m d^{4d} \left( \frac{2}{j+1} \right)^{2(\beta-1)} \right] \cdot \left[ \sum_{k=0}^{n-m} d^{2d} \left( \frac{2}{k+1} \right)^{\beta-1} \right] \\ &\leq \frac{M}{\lambda C^2} \left[ \sum_{j=0}^{\infty} d^{4d} \left( \frac{2}{j+1} \right)^{2(\beta-1)} \right] \cdot \left[ \sum_{k=0}^{\infty} d^{2d} \left( \frac{2}{k+1} \right)^{2(\beta-1)} \right] \\ &\quad \cdot \left[ \sum_{m=1}^{\infty} \left( \frac{1}{2} \right)^m d^{2d} \left( \frac{2}{m+1} \right)^{\beta-1} \right] \\ &< \infty\end{aligned}$$

for all  $n \geq 1$ . By (7.10), we have

$$\|F(u, v, x)\|_{s'} < \infty.$$

This completes the proof.  $\blacksquare$

The proof of the following lemma is elementary. We omit the proof.

**Lemma 7.1.** *Let  $\gamma, \delta$  be two positive real numbers. Let  $\{\zeta_k\}$  be a sequence satisfying*

$$\zeta_{k+1} \leq \delta\zeta_k + \gamma\zeta_{k-1} \quad \text{for } k \geq 2$$

$$0 < \zeta_0 < \infty$$

$$0 < \zeta_1 < \infty.$$

*Then the sequence  $\{\zeta_k\}$  converges if and only if two real roots  $\mu_1, \mu_2$  of the quadratic equation*

$$x^2 - \delta x - \gamma = 0$$

*have absolute values less than 1. Moreover,*

$$\zeta_k \leq c_1\mu_1^k + c_2\mu_2^k, \quad k = 0, 1, 2, \dots$$

*where  $c_1, c_2$  are two constants determined by  $\zeta_0$  and  $\zeta_1$ .*

The following Theorem solves the Cauchy problem (7.9)-(7.10).

**THEOREM 7.2.** *Let the function  $f(u, v, x)$  belong to Gevrey class 2 locally in its first two arguments, varying continuously with respect to  $x$  and satisfy  $f(0, 0, x) = 0$ ,  $D_u f(0, 0, x) = 0$  and  $D_v f(0, 0, x) = 0$  for all  $x \in [0, 2]$ , i.e. there exist two constants  $M > 0$ ,  $b > 0$  such that for any integers  $m = 0, 1, 2, \dots$ ,  $n = 0, 1, 2, \dots$ ,*

$$|D_u^m D_v^n f(u, v, x)| \leq Mb^{m+n} \frac{2m!}{\tilde{m}^\beta} \frac{2n!}{\tilde{n}^\beta}.$$

*Let  $g(t)$  be a function of Gevrey class 2 in  $t \geq T_0$  with support in  $[T_0, T]$  where  $T_0 > 0$  and  $T > T_0$  are two finite numbers. Then there exists a constant  $a > 0$  such that the Cauchy problem*

$$u_t - u_{xx} = f(u, u_x, x) \quad \text{on } (0, 2) \times [T_0, \infty) \quad (7.17)$$

$$u(0, t) = 0, u_x(0, t) = g(t) \quad \text{for } t \geq T_0 \quad (7.18)$$

*has a solution  $u(x, t)$  which is twice continuously differentiable with respect to  $x$  for  $x < a$ , infinitely differentiable with respect to  $t$  for  $t \in [T_0, \infty)$ , bounded for  $x < a$ ,  $t \in [T_0, \infty)$*

and vanishes for  $t \geq T$ . Moreover, when  $g(t)$  is small enough, the  $x$ -interval of existence will be greater than 1, i.e.  $a > 1$ .

PROOF: We convert the problem (7.17)-(7.18) to a first order system of differential equations by introducing the variables  $u_1 = u$ ,  $u_2 = u_x$  and  $u_3 = u_t$ . Then (7.13)-(7.14) can be rewritten as

$$\begin{aligned}\frac{du_1}{dx}(x, \cdot) &= u_2(x, \cdot) \\ \frac{du_2}{dx}(x, \cdot) &= u_3(x, \cdot) - f(u_1(x, \cdot), u_2(x, \cdot), x) \\ \frac{du_3}{dx}(x, \cdot) &= \frac{\partial}{\partial t} u_2(x, \cdot)\end{aligned}$$

with the Cauchy data

$$u_1(0, \cdot) = 0, u_2(0, \cdot) = g(\cdot), u_3(0, \cdot) = 0.$$

For  $s \in [0, 1]$ , let  $X_s = B_s(2, 4)$ , where  $B_s(d, \beta)$  is defined in Section 4 with  $K = [T_0, T + \epsilon]$  where  $\epsilon$  is any finite number,  $d = 2$ ,  $\beta = 4$ ,  $\lambda$  is any fixed constant satisfying the assumption of Proposition 4.1, and the constants  $\theta_0$  and  $\theta_1$  satisfying  $0 < \theta_0 < \theta_1 < \infty$  will be chosen so that the constant  $C$  in Proposition 4.2 is sufficiently small.

For simplification of notation, we let

$$F_1(u_2) = u_2 \tag{7.19}$$

$$F_2(u_1, u_2, u_3, x) = u_3 - f(u_1, u_2, x) \tag{7.20}$$

$$F_3(u_2) = \frac{\partial}{\partial t} u_2. \tag{7.21}$$

By substituting Proposition 7.1 for Proposition 4.5, all arguments in Theorem 5.1 for showing the existence of solutions apply and so we get the first part of the theorem. We are going to show that the  $x$ -interval of existence can be greater than 1 when  $g(t)$  is sufficiently small by checking the proof of Theorem 2.1.

First for any constants  $R_1 > 0$ ,  $R_2 > R_{2,0}$ ,  $R_3 > 0$  and for  $u_i, \tilde{u}_i \in X_s$ ,  $i = 1, 2, 3$ ,

$s \in [0, 1]$  with  $\|u_i\|_s < R_i$ ,  $\|\tilde{u}_i\|_s < R_i$ , we have for  $0 \leq s' < s \leq 1$

$$\|F_1(u_2) - F_1(\tilde{u}_2)\|_{s'} \leq \|u_2 - \tilde{u}_2\|_s \quad (7.22)$$

$$\begin{aligned} \|F_2(u_1, u_2, u_3, x) - F_2(\tilde{u}_1, \tilde{u}_2, \tilde{u}_3, x)\|_{s'} &\leq \|u_3 - \tilde{u}_3\|_s + \|f(u_1, u_2, x) - f(\tilde{u}_1, \tilde{u}_2, x)\|_s \\ &\leq \|u_3 - \tilde{u}_3\|_s + N[\|u_1 - \tilde{u}_1\|_s + \|u_2 - \tilde{u}_2\|_s] \end{aligned} \quad (7.23)$$

$$\|F_3(u_2) - F_3(\tilde{u}_2)\|_{s'} \leq \frac{C}{(s - s')^2} \|u_2 - \tilde{u}_2\|_s \quad (7.24)$$

where  $N$  is a constant depending on  $R_1$  which will become sufficiently small when  $R_1 \rightarrow 0$  by the assumption  $D_u f(0, 0, x) = 0$ ,  $D_v f(0, 0, x) = 0$ ; and  $C$  is the constant in Proposition 4.2 which can be chosen sufficiently small.

Now, let us go back to check the proof of Theorem 2.1. Since  $u_1(0) = u_3(0) = 0$ , by using (3.13) with  $e_1 = 1$ ,  $e_2 = 1$ ,  $e_3 = 2$  and the inequalities (7.22)-(7.24), we get

$$\begin{aligned} \lambda_1^{(0)} &\leq 4a_0 R_{2,0} \\ \lambda_2^{(0)} &\leq Na_0 R_{2,0} \\ \lambda_3^{(0)} &\leq 4Ca_0^2 R_{2,0} \\ \lambda_1^{(k+1)} &\leq 4a_0 \lambda_2^{(k)} \\ \lambda_2^{(k+1)} &\leq 4(Na_0 \lambda_1^{(k)} + Na_0 \lambda_2^{(k)} + \lambda_3^{(k)}) \\ \lambda_3^{(k+1)} &\leq 4Ca_0^2 \lambda_2^{(k)} \end{aligned}$$

and thus

$$\lambda_2^{(k+1)} \leq \gamma \lambda_2^{(k-1)} + \delta \lambda_2^{(k)}$$

for  $k \geq 0$ , where  $\gamma = 16(N + C)a_0^2$  and  $\delta = 4Na_0$ . From Lemma 7.1, we know that the sequence  $\{\lambda_2^{(k)}\}$  converges if and only if absolute values of both roots of quadratic equation

$$x^2 - \delta x - \gamma = 0 \quad (7.25)$$

are less than 1. Let  $\mu_1$  be the positive root and  $\mu_2$  be the negative root of equation (7.25). Then by computing  $\mu_1, \mu_2$ , we know that

$$\delta < 2, \gamma + \delta < 1, \gamma - \delta < 1 \text{ implies } 0 < \mu_1 < 1, -1 < \mu_2 < 0.$$

That is, if  $a_0$  is chosen so that

$$4Na_0 < 2 \quad (7.26)$$

$$16(N+C)a_0^2 + 4Na_0 < 1 \quad (7.27)$$

$$16(N+C)a_0^2 - 4Na_0 < 1, \quad (7.28)$$

then the sequence  $\{\lambda_2^{(k)}\}$  converges and so are  $\{\lambda_1^{(k)}\}$  and  $\{\lambda_3^{(k)}\}$ . Especially,

$$\lambda_2^{(k)} \leq c_1\mu_1^k + c_2\mu_2^k \quad (7.29)$$

with

$$\begin{aligned} c_1 &= \frac{\gamma - 16a_0^2N^2 - 4Na_0\mu_2}{\sqrt{\delta^2 + 4\gamma}} R_{2,0} \\ &= \left( 2N + \frac{4(N+C)}{\sqrt{N^2 + N + C}} - \frac{6N^2}{\sqrt{N^2 + N + C}} \right) a_0 R_{2,0} \\ &< \left( 2N + 4\sqrt{N+C} \right) a_0 R_{2,0} \end{aligned} \quad (7.30)$$

and

$$\begin{aligned} c_2 &= \frac{4Na_0\mu_1 - \gamma - 16a_0^2N^2}{\sqrt{\delta^2 + 4\gamma}} R_{2,0} \\ &= \left( 2N - \frac{4(N+C)}{\sqrt{N^2 + N + C}} - \frac{2N^2}{\sqrt{N^2 + N + C}} \right) a_0 R_{2,0} \\ &< 2Na_0 R_{2,0}. \end{aligned} \quad (7.31)$$

We also need to choose  $a_0$  so that (3.12) holds, that is, we need

$$\sum_{k=0}^{\infty} 2^{k+2} \lambda_1^{(k)} \leq \frac{R_1}{2} \quad (7.32)$$

$$\sum_{k=0}^{\infty} 2^{k+2} \lambda_2^{(k)} \leq \frac{R_2 - R_{2,0}}{2} \quad (7.33)$$

$$2a_0^{-1} \sum_{k=0}^{\infty} 2^{k+2} \lambda_3^{(k)} \leq \frac{R_3}{2}. \quad (7.34)$$

Since

$$\begin{aligned} \sum_{k=0}^{\infty} 2^{k+2} \lambda_2^{(k)} &\leq \sum_{k=0}^{\infty} 2^{k+2} [c_1\mu_1^k + c_2\mu_2^k] \\ &= \frac{4c_1}{1-2\mu_1} + \frac{4c_2}{1-2\mu_2}, \end{aligned} \quad (7.35)$$

if  $a_0$  is chosen so that

$$2\mu_1 \leq \frac{1}{2} \quad \text{and} \quad 2\mu_2 \geq -\frac{1}{2},$$

i.e.

$$4(N + \sqrt{N^2 + N + C})a_0 \leq \frac{1}{2} \tag{7.36}$$

$$4(N - \sqrt{N^2 + N + C})a_0 \geq -\frac{1}{2}, \tag{7.37}$$

then by (7.30), (7.31) and (7.35),

$$\begin{aligned} \sum_{k=0}^{\infty} 2^{k+2} \lambda_2^{(k)} &\leq 8c_1 + \frac{8}{3}c_2 \\ &\leq 32 \left( \frac{2}{3}N + \sqrt{N + C} \right) a_0 R_{2,0}, \end{aligned}$$

and thus if  $a_0$  is also chosen so that

$$32 \left( \frac{2}{3}N + \sqrt{N + C} \right) a_0 R_{2,0} < \frac{R_2 - R_{2,0}}{2}, \tag{7.38}$$

then (7.33) is satisfied. Now, we consider (7.32),

$$\begin{aligned} \sum_{k=0}^{\infty} 2^{k+2} \lambda_1^{(k)} &= 4\lambda_1^{(0)} + \sum_{k=1}^{\infty} 2^{k+2} \lambda_1^{(k)} \\ &\leq 16a_0 R_{2,0} + \sum_{k=1}^{\infty} 2^{k+2} 4a_0 \lambda_2^{(k-1)} \\ &= 16a_0 R_{2,0} + 32a_0 \sum_{k=0}^{\infty} 2^k \lambda_2^{(k)} \\ &\leq 16a_0 R_{2,0} + 32a_0 \sum_{k=0}^{\infty} [c_1(2\mu_1)^k + c_2(2\mu_2)^k] \\ &\leq 16a_0 R_{2,0} + 32a_0 \left[ \frac{c_1}{1 - 2\mu_1} + \frac{c_2}{1 - 2\mu_2} \right] \\ &\leq 16a_0 R_{2,0} \left[ 1 + 8 \left( \frac{4}{3}N + \sqrt{N + C} \right) a_0 \right]. \end{aligned}$$

Thus, if we require that

$$16a_0 R_{2,0} \left[ 1 + 8a_0 \left( \frac{4}{3}N + \sqrt{N + C} \right) \right] \leq \frac{R_1}{2}, \tag{7.39}$$

then (7.32) is satisfied. Similarly, to obtain (7.34), we require that

$$32Ca_0R_{2,0} \left[ 1 + 8Ca_0 \left( \frac{4}{3}N + \sqrt{N+C} \right) \right] \leq \frac{R_3}{2}. \quad (7.40)$$

Hence by putting all of these estimates together,  $a_0$  should be chosen so that (7.26)-(7.28),(7.36)-(7.40) hold and so when the Cauchy data  $g(t)$  is sufficiently small and the constants  $N$  and  $C$  are taken sufficiently small,  $a_0$  can be chosen so that  $a_0 > 2$  and thus the  $x$ -interval of existence  $a = a_0/2 > 1$ . This completes the proof. ■

**Remark.** In Theorem 7.1, we need analyticity of function  $f$  near  $(0,0)$  to guarantee that  $w_x(0,t)$  belongs to be Gevrey class 2 but in Theorem 7.2, we only need to assume that  $f$  is Gevrey class 2 in  $t$  to obtain existence for problem (7.17)-(7.18).

#### REFERENCES

1. P. Duchateau & F. Trèves, *An abstract Cauchy-Kovalevskaja theorem in scales of Gevrey classes*, in "Symp. Math. VII.", 1971, pp. 135-163.
2. A. Friedman, "Partial Differential Equations of Parabolic Type," Prentice-Hall, New Jersey, 1964.
3. M. Gevrey, *Sur la nature analytique des solutions des équation aux dérivées partielles*, Annales Scientifiques de l'École Normale Supérieure **35** (1918), 129-190.
4. L. Hörmander, "Linear Partial Differential Operators," Academic Press, New York, 1963.
5. F. John, "Partial Differential Equations, 4th edition," Springer Verlag, New York, 1982.
6. H. O. Fattorni, *Boundary control systems*, SIAM J. Control **6** (1968), 349-388.
7. H. O. Fattorni, *Boundary control of temperature distributions in a parallelepipedon*, SIAM J. Control **13** (1975), 1-13.
8. H. O. Fattorni, *Calculus of Variations and Control Theory* (1976), "The time-optimal problem for boundary control of the heat equation," Academic Press, New York-San Francisco-London,.
9. D. Henry, *Lecture Notes in Mathematics* **840** (1981), "Geometric Theory of Semilinear Parabolic Equations,".
10. T. Kano and T. Nishida, *Sur les ondes de surface de l'eau avec une justification mathématique des équations des ondes en eau peu profonde*, J. Math. Kyoto Univ. **19(2)** (1979), 335-370.
11. D. Kinderlehrer and L. Nirenberg, *Analyticity at the boundary of solutions of nonlinear second order parabolic equations*, Comm. Pure Appl. Math. **31** (1978), 283-338.
12. O. A. Ladyženskaja, V. A. Solonnikov, and N. N. Uralčeva, "Linear and Quasilinear Equations of Parabolic Type," 1968.
13. L. Lasiecka and R. Triggiani, *Exact controllability for the wave equation with Neumann boundary control*, Appl. Math. and Optimization **19** (1989), 243-290.
14. J. L. Lions, *Contrôlabilité exacte des systèmes distribués*, Comptes Rendus, Series I **320** (1986), 471-476.
15. J. L. Lions, *Exact controllability, stabilization and perturbations for distributed systems*, SIAM Review **30** (1988), 1-68.
16. W. Littman, *Boundary control theory for hyperbolic and parabolic partial differential equations with constant coefficients*, Annali Scuola Normale Superiore, Pisa (1978), 567-580.
17. W. Littman and L. Markus, *Exact boundary controllability of a hybrid system*, Arch. Rat. Mech. Anal. **103** (1988), 193-236.

18. P. Meier, *On the critical exponent for reaction-diffusion Equations*, Arch. Rat. Mech. Anal. **109** (1990), 63-71.
19. X. Mora, *Semilinear Parabolic Problems Define Semiflows on  $C^k$  Spaces*, Trans. Amer. Math. Soc. **278**(1) (1983), 21-55.
20. L. Nirenberg, *Uniqueness in Cauchy problems for differential equations with constant leading coefficients*, Comm. Pure Appl. Math. **10** (1957), 89-105.
21. L. Nirenberg, *An abstract form of the nonlinear Cauchy-Kowalewski Theorem*, J. Differential Geometry **6** (1972), 561-576.
22. T. Nishida, *A note on a theorem of Nirenberg*, J. Differential Geometry **12** (1977), 629-633.
23. D.L. Russell, *Controllability and stabilization theory for linear partial differential equations. Recent Progress and open questions*, SIAM Rev. **20** (1978), 639-739.
24. S. Taylor, *Gevrey regularity of solutions of evolution equations and boundary controllability*, Thesis, University of Minnesota (1989).
25. F. Trèves, *An abstract nonlinear Cauchy-Kovalevskaja Theorem*, Trans. AMS **150** (1970), 77-92.
26. W. Tutschke, *On an abstract nonlinear Cauchy-Kowalevski Theorem - a variant of L. Nirenberg's and T. Nishida's proof*, Z Anali Anwendungen **5**(2) (1986), 185-192.

School of Mathematics, University of Minnesota, 206 Church Street SE, Minneapolis, MN 55455-0487

#	Author/s	Title
1050	J.E. Dunn & Roger Fosdick,	The Weierstrass condition for a special class of elastic materials
1051	Bei Hu & Jianhua Zhang,	A free boundary problem arising in the modeling of internal oxidation of binary alloys
1052	Eduard Feireisl & Enrique Zuazua,	Global attractors for semilinear wave equations with locally distributed nonlinear damping and critical exponent
1053	I-Heng McComb & Chjan C. Lim,	Stability of equilibria for a class of time-reversible, $D_n \times O(2)$ -symmetric homogeneous vector fields
1054	Ruben D. Spies,	A state-space approach to a one-dimensional mathematical model for the dynamics of phase transitions in pseudoelastic materials
1055	H.S. Dumas, F. Golse, and P. Lochak,	Multiphase averaging for generalized flows on manifolds
1056	Bei Hu & Hong-Ming Yin,	Global solutions and quenching to a class of quasilinear parabolic equations
1057	Zhangxin Chen,	Projection finite element methods for semiconductor device equations
1058	Peter Guttorp,	Statistical analysis of biological monitoring data
1059	Wensheng Liu & Héctor J. Sussmann,	Abnormal sub-Riemannian minimizers
1060	Chjan C. Lim,	A combinatorial perturbation method and Arnold's whiskered Tori in vortex dynamics
1061	Yong Liu,	Axially symmetric jet flows arising from high speed fiber coating
1062	Li Qiu & Tongwen Chen,	$\mathcal{H}_2$ and $\mathcal{H}_\infty$ designs of multirate sampled-data systems
1063	Eduardo Casas & Jiongmin Yong,	Maximum principle for state-constrained optimal control problems governed by quasilinear elliptic equations
1064	Suzanne M. Lenhart & Jiongmin Yong,	Optimal control for degenerate parabolic equations with logistic growth
1065	Suzanne Lenhart,	Optimal control of a convective-diffusive fluid problem
1066	Enrique Zuazua,	Weakly nonlinear large time behavior in scalar convection-diffusion equations
1067	Caroline Fabre, Jean-Pierre Puel & Enrike Zuazua,	Approximate controllability of the semilinear heat equation
1068	M. Escobedo, J.L. Vazquez & Enrike Zuazua,	Entropy solutions for diffusion-convection equations with partial diffusivity
1069	M. Escobedo, J.L. Vazquez & Enrike Zuazua,	A diffusion-convection equation in several space dimensions
1070	F. Fagnani & J.C. Willems,	Symmetries of differential systems
1071	Zhangxin Chen, Bernardo Cockburn, Joseph W. Jerome & Chi-Wang Shu,	Mixed-RKDG finite element methods for the 2-D hydrodynamic model for semiconductor device simulation
1072	M.E. Bradley & Suzanne Lenhart,	Bilinear optimal control of a Kirchhoff plate
1073	Héctor J. Sussmann,	A cornucopia of abnormal subriemannian minimizers. Part I: The four-dimensional case
1074	Marek Rakowski,	Transfer function approach to disturbance decoupling problem
1075	Yuncheng You,	Optimal control of Ginzburg-Landau equation for superconductivity
1076	Yuncheng You,	Global dynamics of dissipative modified Korteweg-de Vries equations
1077	Mario Taboada & Yuncheng You,	Nonuniformly attracting inertial manifolds and stabilization of beam equations with structural and Balakrishnan-Taylor damping
1078	Michael Böhm & Mario Taboada,	Global existence and regularity of solutions of the nonlinear string equation
1079	Zhangxin Chen,	BDM mixed methods for a nonlinear elliptic problem
1080	J.J.L. Velázquez,	On the dynamics of a closed thermosyphon
1081	Frédéric Bonnans & Eduardo Casas,	Some stability concepts and their applications in optimal control problems
1082	Hong-Ming Yin,	$\mathcal{L}^{2,\mu}(Q)$ -estimates for parabolic equations and applications
1083	David L. Russell & Bing-Yu Zhang,	Smoothing and decay properties of solutions of the Korteweg-de Vries equation on a periodic domain with point dissipation
1084	J.E. Dunn & K.R. Rajagopal,	Fluids of differential type: Critical review and thermodynamic analysis
1085	Mary Elizabeth Bradley & Mary Ann Horn,	Global stabilization of the von Kármán plate with boundary feedback acting via bending moments only
1086	Mary Ann Horn & Irena Lasiecka,	Global stabilization of a dynamic von Kármán plate with nonlinear boundary feedback
1087	Vilmos Komornik,	Decay estimates for a petrovski system with a nonlinear distributed feedback
1088	Jesse L. Barlow,	Perturbation results for nearly uncoupled Markov chains with applications to iterative methods
1089	Jong-Shenq Guo,	Large time behavior of solutions of a fast diffusion equation with source
1090	Tongwen Chen & Li Qiu,	$\mathcal{H}_\infty$ design of general multirate sampled-data control systems
1091	Satyanad Kichenassamy & Walter Littman,	Blow-up surfaces for nonlinear wave equations, I
1092	Nahum Shimkin,	Asymptotically efficient adaptive strategies in repeated games, Part I: certainty equivalence strategies
1093	Caroline Fabre, Jean-Pierre Puel & Enrique Zuazua,	On the density of the range of the semigroup for semilinear heat equations

- 1094 Robert F. Stengel, Laura R. Ray & Christopher I. Marrison, Probabilistic evaluation of control system robustness
- 1095 H.O. Fattorini & S.S. Sritharan, Optimal chattering controls for viscous flow
- 1096 Kathryn E. Lenz, Properties of certain optimal weighted sensitivity and weighted mixed sensitivity designs
- 1097 Gang Bao & David C. Dobson, Second harmonic generation in nonlinear optical films
- 1098 Avner Friedman & Chaocheng Huang, Diffusion in network
- 1099 Xinfu Chen, Avner Friedman & Tsuyoshi Kimura, Nonstationary filtration in partially saturated porous media
- 1100 Walter Littman & Baisheng Yan, Rellich type decay theorems for equations  $P(D)u = f$  with  $f$  having support in a cylinder
- 1101 Satyanad Kichenassamy & Walter Littman, Blow-up surfaces for nonlinear wave equations, II
- 1102 Nahum Shimkin, Extremal large deviations in controlled I.I.D. processes with applications to hypothesis testing
- 1103 A. Narain, Interfacial shear modeling and flow predictions for internal flows of pure vapor experiencing film condensation
- 1104 Andrew Teel & Laurent Praly, Global stabilizability and observability imply semi-global stabilizability by output feedback
- 1105 Karen Rudie & Jan C. Willems, The computational complexity of decentralized discrete-event control problems
- 1106 John A. Burns & Ruben D. Spies, A numerical study of parameter sensitivities in Landau-Ginzburg models of phase transitions in shape memory alloys
- 1107 Gang Bao & William W. Symes, Time like trace regularity of the wave equation with a nonsmooth principal part
- 1108 Lawrence Markus, A brief history of control
- 1109 Richard A. Brualdi, Keith L. Chavey & Bryan L. Shader, Bipartite graphs and inverse sign patterns of strong sign-nonsingular matrices
- 1110 A. Kersch, W. Morokoff & A. Schuster, Radiative heat transfer with quasi-monte carlo methods
- 1111 Jianhua Zhang, A free boundary problem arising from swelling-controlled release processes
- 1112 Walter Littman & Stephen Taylor, Local smoothing and energy decay for a semi-infinite beam pinned at several points and applications to boundary control
- 1113 Srdjan Stojanovic & Thomas Svobodny, A free boundary problem for the Stokes equation via nonsmooth analysis
- 1114 Bronislaw Jakubczyk, Filtered differential algebras are complete invariants of static feedback
- 1115 Boris Mordukhovich, Discrete approximations and refined Euler-Lagrange conditions for nonconvex differential inclusions
- 1116 Bei Hu & Hong-Ming Yin, The profile near blowup time for solution of the heat equation with a nonlinear boundary condition
- 1117 Jin Ma & Jiongmin Yong, Solvability of forward-backward SDEs and the nodal set of Hamilton-Jacobi-Bellman Equations
- 1118 Chaocheng Huang & Jiongmin Yong, Coupled parabolic and hyperbolic equations modeling age-dependent epidemic dynamics with nonlinear diffusion
- 1119 Jiongmin Yong, Necessary conditions for minimax control problems of second order elliptic partial differential equations
- 1120 Eitan Altman & Nahum Shimkin, Worst-case and Nash routing policies in parallel queues with uncertain service allocations
- 1121 Nahum Shimkin & Adam Shwartz, Asymptotically efficient adaptive strategies in repeated games, part II: Asymptotic optimality
- 1122 M.E. Bradley, Well-posedness and regularity results for a dynamic Von Kármán plate
- 1123 Zhangxin Chen, Finite element analysis of the 1D full drift diffusion semiconductor model
- 1124 Gang Bao & David C. Dobson, Diffractive optics in nonlinear media with periodic structure
- 1125 Steven Cox & Enrique Zuazua, The rate at which energy decays in a damped string
- 1126 Anthony W. Leung, Optimal control for nonlinear systems of partial differential equations related to ecology
- 1127 H.J. Sussmann, A continuation method for nonholonomic path-finding problems
- 1128 Yung-Jen Guo & Walter Littman, The null boundary controllability for semilinear heat equations
- 1129 Q. Zhang & G. Yin, Turnpike sets in stochastic manufacturing systems with finite time horizon
- 1130 I. Györi, F. Hartung & J. Turi, Approximation of functional differential equations with time- and state-dependent delays by equations with piecewise constant arguments
- 1131 I. Györi, F. Hartung & J. Turi, Stability in delay equations with perturbed time lags
- 1132 F. Hartung & J. Turi, On the asymptotic behavior of the solutions of a state-dependent delay equation
- 1133 Pierre-Alain Gremaud, Numerical optimization and quasiconvexity
- 1134 Jie Tai Yu, Resultants and inversion formula for  $N$  polynomials in  $N$  variables
- 1135 Avner Friedman & J.L. Velázquez, The analysis of coating flows in a strip
- 1136 Eduardo D. Sontag, Control of systems without drift via generic loops
- 1137 Yuan Wang & Eduardo D. Sontag, Orders of input/output differential equations and state space dimensions
- 1138 Scott W. Hansen, Boundary control of a one-dimensional, linear, thermoelastic rod